FINAL REPORT

BUOYANT VENUS STATION MISSION FEASIBILITY STUDY FOR 1972 - 1973 LAUNCH OPPORTUNITIES

VOLUME III: CONFIGURATION DEFINITION PART II: APPENDIXES

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Prepared under Contract No. NAS1-7590 by MARTIN MARIETTA CORPORATION Denver, Colorado 80201

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

FOREWORD

The use of a buoyant station to explore the atmosphere of Venus has shown great promise in previous studies. The high temperatures and pressures likely to be encountered and the unknown surface characteristics tend to make the <u>in situ</u> exploration of this planet difficult. The buoyant station concept permits the mission's instruments to be floated in the atmosphere in a moderate environment, localizing the environment problem to relatively compact drop sondes, and avoiding the problem of landing, deployment, and survival on the surface. Relatively simple missions can thus be defined that have the advantages of long duration and mobility over the surface, depending on the existing wind patterns. From such a station, measurements relating both to the atmosphere and the surface can be made. The surface measurements can be obtained either indirectly or by sondes dropped from the parent buoyant station.

This final report on the Buoyant Venus Station Mission Feasibility Study for 1972 - 1973 Launch Opportunities is submitted by the Martin Marietta Corporation, Denver Division, in accordance with Contract NAS1-7590.

This report is submitted in three volumes as follows:

Volume I - Mission Summary Definition and Comparison;

Volume II - Trajectory Analysis for 1972 and 1973 Missions;

Volume III - Configuration Definition.

^{*}J. F. Baxter: Final Report, Buoyant Venus Station Feasibility Study, Volume I, Summary and Problem Identification.

CONTENTS

		Page
FOREWORD CONTENTS		ii iii thru vi
APPENDIX		_
A	VENUS MODEL ATMOSPHERES	1
	Model Used for BVS Study	1 2
	Revised Models	27
T)	References	29
В	HEAT SHIELD ANALYSIS	29
	Heat Shield Requirements	29 48
	Heat Shield Development Requirements	51
Ó	References	53
С		53
	Lunar Orbiter	72
	Mariner '69	72 85
'n	Mariner, Venus/Mercury	93
D	TV DROP SONDE	93 97
	Symbols	97
	Mission Profile	
	Science Subsystem	99
	Telecommunications	103
	Orbital Mission	105
	Effect on BVS Design with a Direct Earth	
	Link	110
	Structure and Thermal Control	110
Е	DUAL-ALTITUDE BALLOON	113
	Dual-Altitude Mission Design Criteria	114
	Configuration Description and Operation	115
	Concept Description and Operation	120
F	STERILIZATION	127
-	Sterilization Criteria	127
	Sterilization Impact on Systems and	/
	Components	128
	BVS Sterilizable Equipment Survey Results .	129
	BVS Study Summary	131
	References	131
G	MULTIPATH ANALYSIS	133
J	Symbols	133
	Surface Model	134

	Communications Geometry	141
	Summary	141
	References	141
Н	DOPPLER AND RANGING OPTIONS FOR BVS POSITION	
	DETERMINATION	145
	Symbols	146
	Changes to Baseline System	148
	One-Way Doppler from Spacecraft to BVS	148
	One-Way Doppler from BVS to Spacecraft	153
	Two-Way Doppler, Spacecraft to BVS to	
	Spacecraft	153
	Two-Way Doppler and Ranging	156
	References	160
		and
		161
Figure		
A1	Venus Pressure and Temperature Profile Models	
	Used in Study	21
A2	Venus Pressure vs Temperature on H ₂ O Phase	
	Diagram	22
EA	Venus Lower Atmosphere	23
A 4	Mariner and Venera Pressure Profiles	24
A5	Venus Temperature Profiles	25
A 6	Venus Atmosphere	26
В1	Ablation Material Required vs Velocity	30
В2	BVS Heat Shield Requirement Summary	36
В3	Heat Shield Ablation Summary	37
В4	Structure Temperature Histories	38
В5	Stagnation Point Ablator Sensitivity to	
	Radiation Heating	41
В6	Ultimate Tensile Strength of AXF-5Q POCO	
	Graphite	42
В7	Carbon Phenolic Ablation Sensitivity, V/M	
	Swingby	44
B8	ESA-5500 and ESA-5500(M) Ablation Sensitivity,	
	Direct Entry	45
В9	Carbon Vapor Pressure	46
B10	Effect of Carbon Vapor Properties on Carbon	
	Phenolic Ablation	47
C1	Orbiter Spacecraft with BVS Capsule	5.5
C2	Performance Capability, Capsule System Weight	
	in Orbit vs Orbit	59
C3	Unmodified Telecommunication System, Mars/	
	Venus Orbiter	62
C4	Spacecraft Science Equipment Showing	
-	Additions	63
.C5	Orbital Power Requirement for Spacecraft	67

C6	BVS/Entry Vehicle	69
C7	Lunar Orbiter/Capsule Electrical Interface	71
C8	Flyby Spacecraft Configuration with BVS	
	Capsule	73
C9	Spacecraft Support Equipment	78
C10	Mariner/Capsule Electrical Interface	84
C11	Venus/Mercury Spacecraft Configuration with	
	BVS Capsule	87
D1	TV Drop Sonde	95
D2	Altitude/Time History of TV Drop Sonde	98
D3	Surface Imaging	100
D4	Smear due to Roll and Pitch	102
D5	Sonde Telecommunications	104
D6	Bit Rate Required vs Number of Images to be	
	Transmitted for Various Transmission	
	Periods	107
D7	Transmitter Power Antenna Gain Products vs	
	Bit Rate for Various Communications Ranges	
	Using Frequency Shift Key Modulation	108
.D8	Transmitter Power Antenna Gain Product vs Bit	
	Rate for Various Communications Ranges	100
	Using Coherent Phase Shift Key Modulation	109
E1	Effect of Allowable Balloon Stress on Balloon	
	Size	116
E2	Effect of Allowable Balloon Stress on Balloon	117
77.0	Weight	117
E3	Balloon Temperature	119. 121
E4	Gas Mixtures Required for Equilibrium Float	121
E5	Gondola Arrangement Showing Pump Installation,	122
77.6	Dual-Altitude Mission	122
E6	<u>-</u>	124
G1	Balloon	136
G2	Angle Convention	138
G2 G3	Fading Margin vs Fading Parameter	140
G4	Communications Geometry	142
G5	Incidence Angle Variation and Fading Margin	143
H1	Spacecraft Transmitter for Doppler and	143
111	Command	150
H2	One-Way Doppler Receiver and Demodulator	152
Н3	BVS Receiver and Demodulator for Doppler,	
,113	Ranging and Command	154
H4	BVS Transmitter for Ranging, Doppler, and	,
**	Data	155
Н5	Spacecraft Doppler Frequency Measurement	157
H6	Spacecraft Transmitters for Ranging, Doppler,	
	and Command	159

<u> Table</u>		
A1	Radio Refractivity of Gases at 293°K, 1 atm	1
A2	Venus Model Atmospheres, Extrapolation of	
	Mariner 5 Data to Surface, Adiabatic Lapse	
	Rate ($CO_2 = 95\%$, Mean Molecular Weight =	
	43.21)	3
A3	Venus Model Atmospheres, Extrapolation of	
	Mariner 5 Data to Surface, Adiabatic Lapse	
	Rate (CO2 = 90%, Mean Molecular Weight =	
	42.41)	9
A4	Venus Model Atmospheres, Extrapolation of	
	Mariner 5 Data to Surface, Adiabatic Lapse	
	Rate ($CO_2 = 85\%$, Mean Molecular Weight =	
	41.61)	15
В1	Heat Shield Material Environmental	
	Sensitivity	31
B2	ESA-5500 and ESA-5500(M) Recession Rates	34
C1	Spacecraft Modifications	54
C2	Summary Weight Statement	57
C3	Spacecraft Modifications Affecting Weight	58
C4	BVS and Subsonic Probe Functions to be	
	Supported by Orbiter Spacecraft	61
C5	Orbiter Spacecraft Experiment Characteristics .	65
C6	Spacecraft Modifications	75
C7	BVS and Subsonic Probe Functions to be	
	Supported by Mariner Spacecraft	77
C8	Spacecraft Support Equipment Power and Weight	
	Summary	79
C9	Scientific Objectives and Instruments for	
	Flyby Spacecraft	80
C10	Flyby Spacecraft Experiment Characteristics	81
C11	Spacecraft Modifications	86
C12	Spacecraft Experiments	89
D1	TV Sonde Weight Statement	9.3
D2	Drop Sonde Link Calculations, FSK Modulation	
	(1024 bps)	105
E1	Comparison of Dual-Altitude Configuration	126
F1	BVS Sterilization Hardware	130
H1	Performance Data Doppler and Ranging Measure-	
	ment Systems	147
H2	Equipment Weight, Power, and Volume Summary	149
нз	Acquisition Time Ranging Code	161

VENUS MODEL ATMOSPHERES

by Allan R. Barger Martin Marietta Corporation

The model atmospheres used in this study were based on the preliminary Mariner V and Venera IV data (refs Al and A2). The radius reference for the Mariner V data has since been revised (ref. A3). However, this revision merely shifts the profiles given in reference Al downward by 8.85 km. (The model profiles used in the BVS study were based on a radius scale that was shifted 6.74 km downward from that given in ref. Al.) The only effect of this new revision is to slightly change the radius (by ~ 2 km) at which significant deployment events occur.

This appendix summarizes both the model atmospheres used in the study and a model based on the more recent analyses of the Mariner V data.

MODELS USED FOR BVS STUDY

The three models used in the study were developed from the Mariner V and Regulus occultation data and the Venera IV measurements. First, the Mariner V refractivity profile (shifted downward by 6.74 km from that of ref. A1) was used to establish the radius reference and the pressures and temperatures calculated for compositions of $90 \pm 5\%$ CO₂ and $10 \pm 5\%$ N₂ over the range 6091 to 6118 km radius. The refractivies used for the calculations are given in table A1 (from ref. A4).

TABLE A1.- RADIO REFRACTIVITY OF GASES AT 293 °K, 1 ATM

CO ₂	$N = 461 \pm 1 \times 10^6$
N ₂	$N = 274.0 \pm .5$
Ar	$N = 258.6 \pm .4$
He	$N = 32.5 \pm .2$
02	$N = 247.4 \pm .2$

Next, the profiles were extended upwards from 6118 and made to pass through the Regulus data. To match the Mariner pressures to those of the Regulus data by extrapolating between them with an isothermal region and a constant temperature lapse rate, the Regulus occultation level had to be shifted upward by 7 to 10 km.

Below 6091 km, the atmospheric properties were extrapolated downward to 6050 km radius assuming a pressure- and temperature-dependent dry adiabatic lapse rate.

The properties for the three models are tabulated in tables A2 thru A4. Figure A1 shows the pressure and temperature profiles and the location of the clouds.

The cloud top radius is 6121 ± 8 km. If it is assumed that the clouds are composed of $\rm H_2O$, in either liquid or solid form, the thickness of the cloud layer can be estimated. Anduevskiy (ref. A2) finds that any water clouds formed would be composed of ice or supercooled water droplets with the bottom of the layer being 35.5 to 34.3 km above the point where Venera IV ceased transmission (assuming a water vapor content of 0.5 to 1.0% by volume). Similar results are obtained using the Mariner V P-T curve (see fig. A2). The cloud layer is then about 6 to 10 km thick.

Fortunately, confidence in the models is greatest in the regions where the BVS is to float (i.e., below 6120 and above 6090 km radius) since most of the measurements refer to that region. Above the cloud tops and below the last Venera IV measurements of pressure and temperature, the confidence level decreases with distance.

REVISED MODELS

These models are based on more recent analyses (e.g., refs. A3 and A5).

As above, the Mariner V refractivity profile (revised as in ref. A3) was used to establish the radius reference and the lower atmosphere properties obtained by extrapolating down to 6050 ± 5 km with a pressure- and temperature-dependent adiabatic lapse rate. This is shown in fig. A3; figures A4 and A5 compare the Mariner and Venera data.

Work is still in progress on making a model for the upper atmosphere consistent with the Mariner and Regulus data because there is still some uncertainty concerning the lapse rate above the clouds. However, fig. A6 shows that approximate agreement can be obtained merely by matching McElroy's model (ref. A5) to the Mariner pressure profile; the temperature profiles do not quite match up but this is not significant.

TABLE A2,- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE, (CO₂ = 95%, MEAN MOLECULAR WEIGHT = 43.21)

RADIUS	ALT	ALTITUDE	PRES	SURE	TEMPERATUR	ATURE	MASS DE	DENSITY	PRESSURE SCALE HT	SCALE HT	TEMPERATURE LAPSE RATE	SPECIF HEAT
W.W.	χ Σ	FEET	MILLIBARS	LBS/SOIN	KELVIN F	AHRENHE I T	GM/CUCM	LBS/CUFT	χχ		DEG K/KM	
6091.0	41.0	41.0 134514.4	ō	0.7460E 02	455,52	360.26	0.5870E-02	0.3664E 00	10.009			
6000.0	0.04	1 (1	0.5480F 0) 0.8236F 0	4	76.1		3969F	10.203	-0.1936	-8.8127	5.1638
•	•		5.60 AT	70.70)))	•		,		-0.1923	-8.7570	5.1983
0.6809	39.0	39.0 127952.7	0.6259E 0	0.9075E 02	473.09	391.90	0.6876E-02	0.4292E 00	10.395	•	i C	
6088.0	38.0	38.0 124671.9	0.6885E 04	M) 4 0.9983E 02	481.80	407.57	0.7427E-02	0.4636E 00	10.586	1161-0-	een/•8=	5.2321
6087.0	37.0		1 6.79 ATM	00100	490.45	423414	0-80125-02		10.776	-0.1899	-8.6508	5.2656
		•	7.46 ATM	70.00		+1227+	1	1		-0.1887	-8.6000	5.2985
0.9809	36.0	36.0 118110.2	ં	0.1201E 03	499.05	438.63	0.8632E-02	0.5389E 00	10.965	10.107	0 4 9 0	
0.8808	35.0	35.0 114829.4	0.9073E 0	0.1315E 03	507.61	454.03	0.9290E-02	0.5799E 00	11.153	-	0.00	000
0.700	200	26.0	(8.95 AT	10205	F16.11	78-047	0.99865-03	0.83345 00	11.330	-0.1864	-8.5034	5.3622
*) + +	0+0+0++	9.78 AT		•		707770		3	-0.1854	-8.4573	5.3931
6083.0	33.0	108267.7	0.1082E 0	5 0.1569E 03	524.57	484.56	0.1072E-01	0.6694E 00	11.525		eļ.	7
6082.0	32.0	32.0 104986.8	(10.68 ATM 0.1179E 05	M) 5 0.1710E 03	532.99	499.71	0.1150E-01	0.7181E 00	11.709	-0.1843	-8.4120	5.4240
			(11.64 AT		-					-0.1833	-8.3678	5.4544
6081.0	31.0	31.0 101706.0	0.1284E 0	0.1861E 03	541.36	514.78	0.1232E-01	0.7695E 00	11.892	-0.1823	-8.3246	5.4845
6080.0	30.0	98425	0.1395E 0	0.2023E 03	549.69	529.77	0.1319E-01	0.8238E 00	12.075	1		
6079	29.0	95144.3	(13.77 ATM)) 0.2197F 03	557.97	544.68	0.14116-03	0.8811F 00	12,256	-0.1813	-8.2832	5.5138
			(14.95 AT							-0.1804	-8.2426	5.5427
6078•0	28.0	91863.5	0.1643E 0	0.2382E 03	566.22	559.52	0.1508E-01	0.9416E 00	12.436	0	C	1
607709	27.0	88582 • 6	0.1779E 0	5 0.2580E 03	574.42	574.29	0.1610E-01	0.1005E 01	12.616	+61T-0-	-0.5032	• 2 (•
0.9209	26.0	301	(17.56 AT 0.1925E 0	0.2792E	582	589.0	0.1717E-01		2.79	-0.1786	-8.1653	5.5989
6075.0	25.0	2021.0	·~	0.3017F 0	06	03	1830	•1142		-0.1777	-8.1280	5.6264
			(20.53 AT							-0.1768	±8.0918	5.6535
6074.0	24.0	78740.1	0 5	0.3257E 03	598.82	618.20	0.1949E-01	0.1217E 01	13.149	0.77	0	
6073.0	23.0	7545943	0.2422E 0) 0.3513E 03	606.87	632.71	0.2074E-01	0.1295E 01	13,325	00/100	#8•056Z	2.680.5
6072.0	22.0	- 3	(23.91 AT 0.2610E 0	M) 5 0+3784E 03	614.90	647.15	0.2206E-01	0.1377E 01	13.500	-0.1752	-8.0211	5.7071
			(25.76 AT	7		- 11				-0.1744	-7.9865	5.7337
6071.0	21.0	68897.6	0.2809E 05	0.4074E 03	622.89	661.53	0.2344E-01	0.1463E 01	13.675	=0-1736	7.0520	75.75
0.0709	20.0	65616.8	0	0.4381E 03	630.84	675.85	0.2489E-01	0.1553E 01	13.848	001700	676681	
0.66.0	0.01	62226.0	(29.81 ATM	_ <	77 889	400.11	0.24415-01	0.186.00	14.021	-0.1728	-7.9205	5.7853
00000												

Table a2.- Venus model atmospheres, extrapolation of mariner 5 data to surface, adiabatic lapse rate, $(co_2 = 95\%)$ mean molecular weight = 43.21) - continued

RADIUS	ALT	ALTITUDE	PRESSURE	SURE	TEMPE	EMPERATURE	MASS DE	DENSITY	PRESSURE SCALE HT	SCALE HT	TEMPERATURE LAPSE RATE	SPECIF
ΚM	ΚM	FEET	MILLIBARS	LBS/SOIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	χ	KM/KM	DEG K/KM	_
6068.0	18.0	59055.1	0.3484E 05	0.5052F 03	99.949	704.32	0.2800E-01	0.1748E 01	14,193			
0.1909	17.0	55774.2	(34.39 AT 0.3737E 0	0.5419E 03	654.52	718.46	0.2967E-01	0.1852E 01	14.365	-0.1713	-7.8572	5.8357
0.9909	16.0	52493.4	0.4005E 0	0.5807E 03	662.35	732.56	0.3142E-01	0.1962E 01	14.535	90/100	-1.66/02	0000 4 6
6065.0	0.8	49212.6	(39.52 ATM)	0.6218F 03	670.14	746.59	0.3326E-01 0.2076E 01	0.2076E 01	14.705	-0.1699	-7.7962	5.8853
1	14.0	45931.7	(42.32 AT 0.4588E 0	0.6653E 03	16.779		0.3517E-01	0.2196E 01	14.874	-0.1691	-7.7659	5.9102
2043.0	0.21	0.0450	(45.28 ATM)	0.71135 03	685.65	774.51	0-37185-01	0.2321F 01	15.043	-0.1684	-7,7360	5.9350
		000000	(48.41 AT	0.78000	70 70 70 70 70 70 70 70 70 70 70 70 70 7				15.21	-0.1678	-7.7068	5.9594
0.000	3 :	0.01666	(51.72 AT	00 10100	20.00				010	-0.1671	-7.6782	5.9836
0.1909	0.11	36089.5	U.55.22 ATM)	U.8113E U3	*O***	802.1	0.41486101	0.6239E UI	2000	-0-1664	-7.6500	6.0077
0.0909	10.0	32808.4	0.5969E 0	0.8655E 03	708.69	815.98	0.4377E-01 0.2732E 01	0.2732E 01	15.544			
0.6509	0.6	29527.5	(58.91 AT 0.6363E 0	0.9227E 03	716.32	829•71	0.4617E-01 0.2882E	0.2882E 01	15.710	869T•0-	-(•6226	2160.0
			(62.80 AT	C C C C C C C C C C C C C C C C C C C	100		10.36.00		370 31	-0.1651	7.5957	6.0546
0.8409) 8	795797	(66.91 ATM)	U. Y830E US	76.67	840.04	0.486/6701			-0.1645	-7,5691	6.0778
6057.0	7.0	22965.8	0.7218	0.1046E 04	731.49	857.01	0.5128E-01	0.3201E 01	16.040	-0.1639	-7.5426	6.1012
0.9509	0.9	19685.0	0.7680E 0	0.1113E 04	739.03	870.60	0.5400E-01	0.3371E 01	16.204			
6055.0	5.0	16404.2	_°	0.1184E 04	746.55	884.13	0.5684E-01	0.3549E 01	16.367	2691-0-	-(-5164	0.1245
6054.0	0.4	13123.3	0.8678E 0	0.1258E 04	754.05	897.62	0.5981E-01	0.3734E 01	16.530	0701.0-	A O A + + + + + + + + + + + + + + + + +	1 1 0
6053.0	9	9842.5	(85.64 AT	0.1336E 04	761.52	911.06	0.6290E-01	0.3926E 01	16.692	-0.1620	-7.4660	6.1699
6052.0	2.0	•	(90.96 AT	0.1418E 04	768,96					-0.1614	-7.4416	6.1922
										-0.1609	-7.4177	6.2142

TABLE A2.- VENUS MODEL AIMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE; ADIABATIC LAPSE RATE, (CO₂ = 95%, MEAN MOLECULAR WEIGHT = 43.21) - Continued

VENUS MODEL		OSPH WGT	ATMOSPHERES COMP AR WGT = 43.21	UTED (95	UTED FROM DATA (95.0 PERCENT		FROM THE OCCULTATIONS CARBON DIOXIDE 5.0	CF PEF	MARIMER V AND (CENT NITROGEN)	KEGULUS)	13 RARCH 19	<u> </u>
RADIUS	à	PRESSURE	URE		TEMPE	EMPERATURE	MASS DE	DENSITY	KEFRACŤIŲITY		ALTITUDE	
X	MILLIBARS	RS.	LBS/SQIN	A	LVIN	FAHRENHEIT	GM/CUCA	LBS/CUFT	N UNITS	- E M M M M M M M M M M M M M M M M M M	ABOVE SORT	
6090.78	0.5260E	0.4	0.7627E 0		457.56	363.94	0.5974E-02	0.3730E 00	.1500E		· .	
6091.00	0	2 0		02 44	455.52	343.62	0.58/0E-02 0.5415F-02	0.3380F 00	0.14/3E 04	10.0098 8098	137795.7	
6093.00	Ç	04	ш		7.03	326.98	0.4986E-02	.3113E				
6094.00	Ô	70			427.79	10.3	0.4584E-02	362E			144356.9	
6095.00	0	40	رس		418.56	293,75	0.4207E-02	•2626E			147637.8	
6096.00	0 9				409 34	277.14	0.3853E-02		د ند			
6097609	0.2717E	400	0.3512F 0	02 40 02 39	390.91	260.55	0.3522E-02	0.2199E 00	0.8843E 03	8.608 8	154159.5	
90.6609	0.2	04.			381.70	227.40	0.2924E-02	.1826E	لنا ا			
6100.00	0.1909E	04			372.50	210.84	U.2656E-02	•1658E	لدا		-	
6101.00	C.				363.31	194.29	U.2406E-02	•1502E	ш		167522.8	
6102.00	0 0		ii Lii		354.12	177.75	0.2175E-02	•1358E	u (7 * 809	170603.6	
6103.10	ب ر	† 6			244.04	161.22	0.1960E-02	0.1224E 00			1/3884.0	
6104.00		0 4	0.1658E 0		6.51	146.05	0.1759E-02	1098E	u	7.4262	177165.3	
6105.00	$^{\circ}$	03			328.24	131.17	U-1573E-02	.9820E-	1.1		180446.2	
6106.00	្វំ	03			319.98	116.31	0.1402E-02	0.8757E-01	ü		183727.0	
6106.97	0.7553E	03			1.98	116,31	U.1251E-02	0.7814E-01			٠	
6107.00	0.7520E	0.0	0.1090E 0		311.76	101.50	0.1247E-02	0.7785E-01			187007.8	
6108.00	0.64493E) C			504.452	88°78	0.1102E=02	0.6881E-01		807/0	190288	
6110.00	0			1 (2)	89.74	61.87		0.5327F-01	ı ı.		196850.4	
6111.00	0	0	ш	01 28	82.42	48.68		0.4665E-01	ı w	6 - 246	200131.2	
6112.00	0.3	03			275.09	35.50	0.6521E-03	0.4071E-01			203412.0	
6113.00	0.0	03	0.4267E 0		267.77	22,33	0.5670E-03	0.3540E-01		5.9268	206692.9	
6114.00	50	n (256.73	9.10	0.4911E=03	0.2845E-01	0.1753E 05		2039/56/	
6115.00		0 0		01 25	256.18	1.46	0.4189E-03	0.2615E-01		5.674	213254.5	
6116.00	0				255.06	-0.55	0.3525E-03	0.2200E-01			216535.4	
6117.00	0	03	0.2118E 0		253.93	-2.58	0.2964E-03	0.1850E-01	0.7442E 02	5.627	219316.2	
6118.00	0.1222E	0 0			252.81	-4·60 	0.2491E-03	0.1555E-01		5.6048	23097	
6119.00	0	ი ი ი	0.1482E 0	01 25	2.15	5.78	U 2088E-03	0.1499E-01	0.5242E 02		226377.9	
6120.00	0	02			251.62	-6.74	U-1749E-03	0.1092E-01	LUI		29658.	
6121.00	ာ်	0.2		01 25	51.09	-7.70	U.1464E-U3	0.9144E-02	0.3677E 02		32939.	
6122.00	0 5			14	250.55	-8.66	0.1226E-03		Ш		236220.5	
6123.00	O (50.05	29.65	0.1026E-03	0.6405E-02	0.2575E 02		239501.63	
0124*00	-	2 5			かせ・ハナン	110.0	0.8583E=04	0.000 BE -0.00			7.000000	
6126.00	0	0 0	0.4207E 0	00 24	8.43	12.49	0.6000E-04	0.3746E-02	0.1506E 02	5.5221	245343.8	
6127.00	0.2	02			247.90	-13.44	0.5015E-04	0.3130E-02			5262	
6128.00	0.2018E	0.2	ш		7.37	-14.40	U.4189E-04	0.2615E-U2	Э Ш	5.502	255905.5	
6128•21	0.1943E				N.	-14:40		0.2518E-02		001	256594	
6130.00		200	0.2035E 0	00 24	247.92	-13.41	0.2905E-04	0.1814E-02	0.7295E 01	5.5179	262467.2	
,		t						1			1	

TABLE A2. - VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE, (CO₂ = 95%, MEAN MOLECULAR WEIGHT = [43.21) - Continued

VENUS MODE	ODEL ATMOSPHERE	S COMP	്രവ്	FROM DATA FROM	FROM THE OCCULTATIONS CARBON DIOXIDE - 5+0		OF MARINER V AND F PERCENT NITROGEN)	REGULUS	
RADIUS	PRESSURE	SURE	TEMPE	TEMPERATURE	MASS DENSITY		REFRACTIVITY	PRESSURE SCALF HT	ALTITUDE AROVE SURE
Σ Σ	MILLIBARS	LBS/SOIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	N UNITS) ! \ ! \(\overline{\text{Z}}	FEET
6131-00	0+1171E.02	0.1698E 00	248.28	12.75	0.2420E-04	0.1510E=02.	0.6076E 01-	5.5279	- 265748±0 269028±8
6133.00	0.8164E	0.1183E 0	249.02	-11.42	U.1680E-04	0.1049E-02		5.5479	272309.7
6134.00	0.6818E	.0.9887E	248+39	-10.76	0.1401E-04	0.8746E-03-	ш	55.7	~
6135.00	0.5696E 01		249.75	-10.10	0.1168E-04	0.7294E-03	933E	799	7887
6136.00	0.4761E		250.12	44.6	0.9747E=05	•6085E=0		5.57(9	x 0
6138.00	0.3328F 01	0.4826F-01	250.85	8 / 8	0.67906-05	0.4239E-03	0.1704E 01	5.5979	288713.9
6138•21	0.3206E	4.0	250.93	-8.12	0.65375-05	.4081E-0		5.6000	289402.8
6139+00	0.2784E	9	251.22	7.46	0.5670E-05	0.3539E-03	0.1423E 01	507	291994.7
6140.00	0.2330		25	16.80	0.4/36E=05	0.295 /E=03		5.6279	298556.4
6142.00	0-1633F	0.2368E-01	70	5.448	0.3308E-05			5.6979	30183763
6143.00	0.1367E		252	-4.83	0.2765E-05	Ó	344E	547	305118.1
6144.00	0.1146E		23	-4.17	0.2313E-05	0		.657	308399.0
6145.00	0.9606E	0-1392E-01	253.41	13.51	0.1935E-05	0.1208E-03		-667	11679
6146.00	0.8054E 00		2 5	12.86	0.1619E-05	0.1011E-03	0.4066E 00	5.6879	314760•6
6148-00	0.0174L	0.82	254.51	1.55	0.1135E-05	0.7089E-04		697	321522.3
6149.00	0.4754E	0.68	~	68.0-	0.9513E-06	0.5939E-04		. 707	324803.1
6150.00	0.3991E	0.5787E-0	ın.	-0.24	0.7971E-06	0.4976E-04		5.7179	328084.0
6151.00	0.3351E	0.4859E-02	255.60	0.41	0.6681E-06	0.4171E-04		.727	331364.8
6152.00	0.2815	0.4081E-02	255.96	1.06	0.5602E-06	0.3497E=04	0.11406E 00	5. 13/9	334645.6
6154 00	0.1987E	0.2882E-02	256.68	2 - 37	U-3942E-06	0.2461	9	757	341207•3
6155.00	0.1671E	0.2423E-02	257.05	3.02	0.3308E-06	0	0.8306E-01	7.	344488.1
LO.	0.1405E	0.2037E-02	257.41	3.67	0.2777E-06	Ö	0.6973E-01	.777	47769.
57.00	0.1182E 00	0.1714E-02	257.77	4.92	0.2332E-06	0.1456E-04	0.5855E-01	787	351049.8
58,00	0.9947E-01	0.1442E-02	258.13	4.97		0.1223E-04	0.4918E-01	5.7979	54390
6159-00	0.8372E-01	0.1214E-02	258 • 49	5.62		0.102/E-04	0.4433E-01	5.8079	35/01/1-5
61.00	0.5937E-01		259.22	6.92	0.1163E-06	0.7262E-05	0.2920E-01		364173.2
62.00	0.5001E-01	0.7252E-0	259.58	7.57	0.9784E-07	0.6108E-05	0.2456E-01	.837	367454.1
63.00	0.4214E-01	0-6111E-0	259.94	8 22	U-8230E-07	U.5138E-U5	0.2066E-01	847	370734.9
64.00	C.3552E-01	0.5151E-0	60°3	8.87	0.6926E-07	.4324E-0	0.1738E-01	768.	374015.
65.00	0.2995E-01	0.4343E-0	260.66	9.51	U 5830E 07	0.3639E=05	0.1463E-01	5 8 6 7 3 5 5 4 3 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	311290.0
6166.00	0.2526E-01	U-3663E-U	261.02	10.16	0.4909H-0.	0.3064E=05	0.1232E-01	V - C - C - C - C - C - C - C - C - C -	4.7.0000
00.75	0.2131E-01		261.57	10.01	0.4134E=07	0.2581E-05	0.10386-01		282878•2 285104-6
6168.00	0.1800E-01		266.995	20.87	0.3418E-07	10	0.8582E-02	6.0157	87139
99.00	0.1529E-01	0.2217E-0	75.7	36.68	809	0.1753E-05	0.7053E-02		390420•0
6170.00	0.1305	0.1892E-0	284.53	52.49	U-2323E-07	0.1450E-05	0.5832E-02	6.4157	393760.8
r- 1	0.1119E	0.16	293,30	68.28	932E	0.1206E-05	31E-0	6.6157	396981.6
C 1	3.9646E	398E	302.07	0 1	616E	600	4057E	6.8157	400262.5
3	0.834/E-02	0.1210E-03	۰	99.84	0.13586-07	0.8482E-06	0.3411E-02	/*OT2/	40304363
00.47.14	U. /253E	U-1051E-03	818	115.60	ш	U./166E-U6	0.28815-02	1677.	4.0007

Table A2.- Venus model atmospheres, extrapolation of mariner 5 data to surface, adiabatic lapse rate, (CO₂ = 95%, Mean Molecular Weight = 43.21) - Continued

VENUS M	ODEL ATMOSP LECULAR WGT	VENUS MODEL ATMOSPHERES COMPUTED FROM DATA MEAN MOLECULAR WGT = 43.21 (95.0 PERCENT	TED FROM (95.0 PER		FROM THE OCCULTATIONS CARBON DIOXIDE 5.0		OF MARINER V AND PERCENT NITROGEN)	REGULUS	
RADIHS	PRES	RESSURE	TEMPERATUR	ATURE	MASS DENSITY	NSITY	REFRACTIVITY	PRESSURE SCALF HT	ALTITUDE ABOVE SURE
×	MILLIBARS	LBS/SGIN	KELVIN F	KELVIN FAHRENHEIT	GM/CUCM	LBS/CUFT	N UNITS) ! X ! X	FEET
6175.00			328.35	131.36	U.9742E-U8	0.6082E-06	0.2445E-U2	7.4157	410105.0
6176.00	0.55	0.8030	337.09	147.10	0.8304E-08	0.5184E-06	0.2084E-02	7.6157	413385.8
6177.00			345.83	162.83	0.7108E-08	0.4437E-06	0.1784E-02	7.8157	410666.6
6178.00	0.42	•	354.57	178.56	0.6108E-08	0.3813E-06	0.1533E-02	8.0157	418847.5
6179.00		0.	363*30	194.27	0.5268E-08	0.3289E-06	0.1322E-02	8.2157	423228.3
6180.00	0.33		372.02	209.97	0.4560E-08	0.2847E-06	0.1145E-02	415	426509.1
6180.55	0.3149E	0.4567		209.97	0.4219E-08	0.2633E-06	0.1059E-02	8 5250	428313•0
6181.00	0.29	0.4333E-04	380 74	225.60	0.3961E-08	0.24/3E-06	0.9745E-03	8 0 1 0 / 0 1 0 1 0 /	0.00/2024
6182.00		O	2004	257.00	0.04011100	0.1246100	75.74	0.010	436351.7
6184.00) C	406.86	272.68	0.2644F-08	0.1651F=06	0.6640F=03	9.2157	439632.5
6185.00		O	415.55	288.33	0.2325E-08	0.1451E-06	0.5837E-03	9.4157	442913.4
6186.00		0	424.24	303.97	0.2049E-08	0.1279E-06	0.5145E-03	9.6157	446194.2
6187.00		ំ	432.93	319.60	0.1811E-U8	U.1130E-06	0.4548E-03	9.8157	449475.U
6188.00	0.1407E-02	0.2	441.61	335.23	0.1605E-08	0.1002E-06	0.4029E-03	10.0157	452755.9
6189.00	0.1275E-02	0.1	450.28	350.84		0.8899E-07	0.3578E-03	10.2157	456036.7
6190.00	0.1157E-02	•	458.95	366.44	0.1268E-08	0.7922E-07	0.3185E-U3	10.4157	459317.6
6191.00		0	467.61	382,03	0.1132E-08	0.7067E-07	0.2842E-03	10.6157	462598.4
6192.00		0	476.26	397.61	0.1012E-08	0.6318E-07	0.2541E-U3	10.8157	465879•3
6193.00		0	484.91	413.18	0.9067E-09	0.5661E-07	0.2276E-03	11.0157	469160•1
6194.00		0	493.56	428.74	C.8139E-09	0.5081E-07	0.2043E-03	11.2157	472441.0
6195.00		0	502.20	444.29	0.7320E-09	0.4570E-07	U.1837E-03	11.4157	475721.8
6196.00				459.83	0.6596E-09	0.4118E-07	0.1656E-03	11.6157	479002.6
6197.00				475.36	0.5954E-09	0.371/6-07	0.14945103	11.3157	U = 827284
00.8619		•		470 888		0.5561E107	0. 1351E 03	7 CTO - 2 T	400004
00.6619	0.5216E		536.70	506-39	0.4876E-09	0.0044E107	0.1224E-03	14.415/	486840•1
00.00.00	0.48096108	0.69/08 00	040 070	75.1.68 7.03	**************************************	0.2761E=07	0.1110E-05	12-4137	477170•0 705704
00.4029			000° 442	707 000 000	94018E109	10-3004E-07		12.0127	0.0000000000000000000000000000000000000
6202	0.41046103) ¢	20.000	777 * 00 8 7 7 8 8 7 8 8 8 8 8 8 8 8 8 8 8 8 8 8		0.2280E-0.7	0.92666104	14-010-41	1000 1000 1000 1000 1000 1000 1000 100
6204 00			579.70	583.79		0.1898E-07	0.7635E-04	13,2157	505249.3
6205.00		Ö	588.28	599.24		0.1734E-07	0.6977E-04	13.4157	508530.1
6206.00		0	596.86	614.68	0.2542E-09	0.1587E-07	0.6384E-04	13,6157	511811.0
6207.00	0.2818E-03	\circ	605.43	630.11	0.2329E-09		U.5849E-04	13.8157	515091.8
6208.00		0.3803E-0	614.00	645.53	0.2137E-09		0.5366E-04	14.0157	1837
6209.00	0.2443E-03	°	622.56	560 94	0.1963E-09		0.4928E=04	14.2157	21653.
6210.00	0.2279E	ं	631.12	676.34	0.1805E-09		0.4532E-04	14.4157	524934.5
6211.00	0.2127E	0	639.67	691.73	0.1662E-09	0.1037E-07	0.4172E-04	14.6157	2821
6212.00	0.1987E	0	648.21	707.11	v.1531E-09	0.9564E-08	0.3846E-04	14.8157	531496.1
6213.00	0.1858E	0	656.75	722.48	U.1413E-09	0.8824E-U8	0.3548E-04	15.015/	34777.
21	0.1739E	ਂ	99	737.84	0.1305E-09	0.3151E-08	C.3277E-04	15.2157	538057.7
2	0.1629E	0.2363E-05	673.8	753.19	0.1207E-09	0.7536E-08	0.3030E-04	15.4157	541338.6
7:	0.15286	Š :		o o	COTTLANDS	0.69/66-08	0.2805E-04	15.0157	0.44014.0
717	U. 1433E	0.4079E-0	Ω,	183.80	0.1000E10V	0.6465ETC8	0.75995-04		4 - COV - FO
6218.00	0.1346E	0.1952E-0		799-18	9600E	0.5993E-08	24.10	16.0157	551181.1
7	0.12	0.183	707.87	814.49	0.8911E-10	0.5565E=08	0.223/E-04	16.215/	224467.0

TABLE A3. - VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO₂ = 90%, MEAN MOLECULAR WEIGHT = 42.41)

18 MARCH 68

RADIUS	ALTITUDE	ш	PRESSI	SURE	TEMPE	EMPERATURE	MASS DE	DENSITY	PRESSURE	SCALE HT	TEMPERATURE	SPECIF
X X	KM FEET		MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	KW	KM/KM	DEG K/KM	(CP/R)
7 0.1609	41.0 134514.	4	0.4980E 04	0.7221E 02	442.62	337.04	0.5739E-02	0.3582E 00	606*6	and the second s		
	40.0 13123	3.6	<u> </u>		451.49	353.01	0.6217E-02	0.3881E 00	10.108	-0.1986	-8.8714	5.0347
60869	39.0 127952	12.	5.43 ATM) 0.6069E 04	0.8801E 02	460.31	368.89	0.6726E-02	0.4199E 00	10.305	-0.1972	8.8147	5.0687
0		6	_			384•66		0.4536E 00	10.501	-0.1959	-8.7597	5.1022
		- (-	1		30	1	;		-0-1947	-8.7072	5.1347
0.00	0.166121 0.16		7.24 ATM)	0.1064E 03	8/1/4	4004	- 1	C*+894E CC	10.000	-0.1935	-8.6556	5.1670
6086.0	36.0 118110.2	١ ،	0.8056E 04	0.1168E 03	486.44	415.92	0.8447E-02	0.5274E 00	10.889		3 0 0	
085.0	35.0 114829	. 4	_	0.1279E 03	495.05	431.42	0.9092E-02	0.5676E 00	11.082	6767.0-	6600.0	0067.6
C	0.4	٠,	_	ļ .	503-61	28-977	Į	0.61015 00	11.273	-0.1912	-8.5569	5.2300
		_	_		ζ.					-0.1900	-8.5102	5.2605
6083.0	33.0 10826	7.07	50	0.1527E 03	512.12	462.15	0.1049E-01	0.6552E 00	11.463			
6082.0	32.0 104986	<u>.</u> ω	10.39 ATM) 0.1148E 05	0.1665E 03	520.59	477.39	0.1125E-01	0.7028E 00	11.652	-0•1890	-8.4647	5.2905
		- 0	_	1	1		i		0,00	-0.1879	-8.4197	5.3205
7 0.1809	31.0 101/06.0		(12.34 ATM)	U.1815E U3	10.626	474. 00.	0.12065-01	0.1530E 00	11.840	-0.1869	-8.3761	5.3499
0.0809	30.0 98425	7		0.1972E 03	537.39	507.63	0.1291E-01	0.8061E 00	12.027		,	1
2 0.6209	29.0 9514	44.3	(13.42 AIM) 0.1477E 05	0.2142E 03	545.72	522.64	0.1380E-01	0.8621E 00	12,213	-0•1859	-8.3334	5.3791
			(14.58 ATM)	0.00	667.00	n ton	0 14766-01	00 30100	200	-0.1849	-8.2923	5.4076
0.00		1)	ATW)		70.	10.100	To-100 + + + • • •		066.71	-0.1839	-8.2522	5.4356
607700	27.0 88582	9	-	0.2517E 03	562.27	552.43	0.1574E-01	0.9832E 00	12.582	0801.0-	0.01	7 7 7 7
0.9209	26.0 8530	* 0 8 * 10 £ 5 8 * 0 * 8 * 10 £ 5 8	0.1878E 05	0.2723E 03	570.49	567.22	0.1679E-01	0.1048E 01	12.765	0681.0	76170-	20405
6075.0	25.0 82021	0	18.53 ATM)	0.2944F 03	578.67	581.94	0.17895-01	0.1117F 01	12.947	-0.1821	-8+1755	5.4903
		_	-					t		-0.1812	-8-1385	5.5170
6074•0	24.0 78740	۰ آ	2192E 05	0.3178E:03	586.81	596.59	0.1905E-01	0.1189E 01	13.128	-0.1803	-8-1026	5.5433
073.0 2	23.0 75459	3	-	0.3428E 03	594.91	611.18	0.2027E-01	0.1265E 01	13,309			
6072.0	22.0 7217	72178•4 0•	0.2547E 05 (0.3694E 03	602.98	625.71	0.21556-01	0.1345E 01	13.488	-0.1795	-8.0673	5.5694
		-	-1				- 1	- 1		-0.1787	-8.0326	5.5953
6071.0 2	21.0 6889	68897•6 0• (2	0.2742E 05 (27.06 ATM)	0.3976E 03	611.02	640.17	0.2289E-01	0.1429E 01	13.667	-0-1779	-7.9984	5.6211
6070.0	20.0 6561	6.8 0		0.4276E 03	619.02	654.57	0.2430E-01	0.1517E 01	13.845			
0.6909	19.0 6233	62335.9 0.	1M)	0.4594E 03	656.99	668.91	0.2578E-01	0•1609E 01	14.022	-0.1770	-7.9647	5.6467
	,		S						1	2761-0-		,,,,

TABLE A3.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO₂ = 90%, MEAN MOLECULAR WEIGHT = 42.41) - Continued

RADIUS	ALT	ALTITUDE	PRESSI	SURE	TEMPE	TEMPERATURE	MASS DENSITY	PRESSURE SCALE HT	SCALE HT	TEMPERATURE LAPSE RATE	SPECIF HEAT
Σ	Σ	FEET	MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GM/CUCM LBS/CUFT	ΚX	KM/KM	DEG K/KM	(CP/R
6068.0	18.0	59055.1	0.3401F 05	0.4932F 03	3 634.92	683.20	0.2732E-01 0.1706E 01	14.198			
		-	ATM)	1	i .	.			-0.1755	-7.9007	5.6962
0.67909	17.0	55774 • 2	0.3648E 05 (0.5289E 03	3 642 83	697.42	0.2894E-01 0.1807E 01	14.3/4	-0.1748	-7.8696	5.7206
0.9909	16.0	52493.4	05	0.5668E 03	3 650.70	711.59	0.3064E-01 0.1913E 01	14.548		1	1
4045.0	ر د)	(38.58 ATM)	0.60695 03	3 658.54	725.71	0.3242E-01.0.2024F.01	14.723	-0.1740	0668-1-	2. (443
2000		1-	-	1					-0.1733	-7.8086	5.7691
6064.0	14.0	45931.7	0.4478E 05	0.6493E 03	3 666.35	739.77	0.3428E-01 0.2140E 01	14.896	-0.1726	-7,7783	5.7935
6063.0	13.0	42650.9	0.5	0.6941E 03	3 674.13	753.77	0.3622E-01 0.2261E 01	15.068		, i	:
0 6 80 8	,)	(47.24 ATM)	20 34177	881.88	767-73	0.3825F=01 0.2388F 01	15.240	-0.1718	-7.7486	5.8176
0.0000	0.01)		1	1	3		1	-0.1711	-7.7195	5.8415
0.1909	11.0	36089.2	0.5458E 05	0.7915E U3	3 689.61	781.62	0.4037E-01 0.2520E 01	15.412		0007.2	4
0.0202	0	3.9008	0.58.87 ATM)	0.84425 03	3 697.30	795.47	0.4259F-01 0.2659F 01	15.582	+0/101	606001	2000
•	2	_	_						-0.1698	-7.6628	5.8886
6050	0.6	29527.5	: 1	0.8999E 03	3 704.96	809.27	0.4490E-01 0.2803E 01	15.752			
		_				0	0		-0.1691	1.6994	2.9117
0.8509	ာ ဆ	7.94797	0.55010E U5 (65.24 ATM)	0.9585E U.S	09.711	70 • c 78	0.4/52E-01 0.2934E 01	4	-0.1685	-7.6086	5.9344
6057.0	7.0	22965 • 8	1.	0.1020E 04	4 720.21	836.72	0.4983E-01 0.3111E 01	16.089		1	,
6056.0	9)	(69.44 ATM) 0.7485F 05	0.1085E 04	4 727 80	850.37	0.5246E-01 0.3275E 01	16.257	-0.1678	-(.5823	0/46.4
		_	_	1	}				-0.1672	-7.5556	5.9800
6055.0	5.0	16404.2	0.7958E 05 (78.54 ATM)	0.1153E 04	4 735.36	863.97	0.5520E-01 0.3446E 01	16.425	-0.1665	-7.5294	6.0028
6054.0	4.0	13123.3	1	0.1225E 04	4 742.89	877.53	0.5805E-01 0.3624E 01	169991		4 2 1	1
6053.0	6	9842.5	(83.44 ATM) 0.8977F 05	0.1301F 04	4 750.39	891.04	0.6102E-01 0.3809E 01	16.757	-0.1659	*7 5039	6.0252
		•	-	1	Į			ł	-0.1653	-7.4791	6.0472
6052.0	2.0	6561.6	0.9526E 05	0.1381E 04	4 757.88	904•51	0.6412E-01 0.4003E 01	16.923	-0.1647	-7.4547	6.0689
6051.0	1.0	3280.8		0.1465E 04	4 765.33	917.93	0.6734E-01 0.4204E 01	17.087			0
		_	200								

TABLE A3.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE ($CO_2 = 90\%$, MEAN MOLECULAR WEIGHT = 42.41) \tilde{c} Continued

18 MARCH 1968 VENUS MODEL ATMOSPHERES COMPUTED FROM DATA FROM THE OCCULTATIONS OF MARINER V AND REGULUS

MEAN	MEAN MOLECULAR WG	14.24 = 10		190.0 PERCEN		CARBON DIOXIDE	10.0 PERCE	PERCENI NIIROGENI		
RADIUS	PRE	RESSURE		TEMPE	TEMPERATURE	MASS UF	DENSITY	REFRACTIVITY	PRESSURE SCALE HT	ALTITUDE ABOVE SURF
χ Σ	MILLIBARS	LBS/	SUIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	N UNITS	1 X	
6090.78	0.5092E C	14 0.7384E	0.2	444.63	340.66	0.5842E-02	0.3647E 00	0.1463E 04	9.9540	135750.3
6091.00	0.4980E	14 0.7222E		442.62	337.05	U.5739E-UZ	0.3583E €	0.1437E 04	8606.6	134514.4
6092.00	0.4498E	14 0.6522E	0.5	433.55	320.72	0.5290E-02		0.1325E 04	9.7098	137795.2
90,6609	0.4053E	14 0.5877E		424.48	304.39	J.4867E-U2	.38E	ш	8405-6	141076.1
6094.00	α	14 0.5285E	0.5	415.41	288.08	0.4470E-02	•2791E	10	9.3096	144356.9
00*5509	0.3269E	14 0.4741E	0.5	406.36	271.78	0.4098E-02	358E	397C	9.1098	7637
6096.00	CVI	14 0.4243E	0	397.30	255.48	0.3750E-02			8.5098	150918.6
6097.00	612E	ာံ	-	388.26	239+20	0.3425E-02	U.2138E	0.8579E 03	8 • 7098	154199.5
00*8609	325E	04 0.3372E	0	379.22	222.93	0.3121E-02	0.1948E		8.5098	157480.3
00*6609	365E	ံ	ာ	370.19	206.67	0.2837E-02	0.1771E	0.7109E 03	8.5098	160761.1
6100.00	328E	ာ	2	361.16	190.42	0.2574E-02	0.1607E		8.1098	164042.0
6101.00	0.1613E		Э.	352.13	174.18	0.2329E-02	0.1454E		7 • 50.98	16/522.8
6102.00	0.1419E	្វំ	2	343.12	157.95	0.2102E-02	0.1312E 00		860/•/	1 (0603.6
6103.00			\circ	334.11	141.73	0.1892E-02	C.1181E CO		7.5098	173884.5
6103.18	0.1215E C		0.5	332.49	141.73	0.1856E-02	0.1159E 00		7.4739	174474.0
6104.00			Ç	325.83	126.83	v.1695E-02	0.1C58E 00		7.3262	177165.3
6105.00	6 0	3 0.1373E		317.72		v.1513E-02			7.1462	180446.2
6106.00)	309.62	7.65	0.1347E-02	\circ		996.9	183727.0
6106.97			0	301.77	7.65	0.1200E-02		0.3007E 03	6.7917	186908.5
6107•00				301.55	83.12	0.1196E-02			6.7868	187007.8
6108.00				294.34	70.15	0.1055E-02	0.6588E-01		6.6268	190288.7
6109.00		13 0.7622E	0.	287.14	57.19	0.9283E-03	0.5795E-01	0.2325E 03	6.4668	195569.5
6110.00	_		5	279.94	44.23	0.8138E-03	0.5081E-01		8900.	196850.4
6111.00	0.3828E	m		272.75	31.29	0.7111E-03	4.		6.1468	200131+2
6112.00	0.3246E	ံ က	-	265.57	18.35	U-6192E-03	0.8	0.1551E 03	5.9868	203412.0
6113.00	0.2740E	o ต	07	258.38	5.43	0.5371E-03	ന ാ		5.8268	506692.9
6114.00	0.2302E	m		251.21	-7.48	0.4640E-03			5.6668	208973.7
6114.51	0.2103E 0	် ဗ		247.55	17.48	0.4300E→03	0.2684E-01	0	5.5853	211646.4
6115.00	0.1926E	m	5	246.42	-16.09	0.3955L-03	0.2469E-UI		5.5607	213254.5
6116.00	0.1607E U	3 0.2331E	 	244.13	-20.22	0.3332E-03)	0.8347E 02	5.510/	216535.4
6117.00	0.1340E	n		241.83	-24.35	0.2802E-03	0.1749E-01		5.4607	219816-2
6118.00	0.1114E	m		239.54	-28.48	0.2352E-03	0.1468E-01		5.4107	223097.1
6118.21	0.1072E	3.0.1		239.06		0.2267E-03	0.1415E-01		2.4002	223/85.9
6119.00	0.9263E	N	ਤ :	238.65		0-1961E-03	0.1224E-01	0.4914E 02	5.00 5.00 5.00 5.00 5.00 5.00 5.00 5.00	2263/1.99
6120.00	0.7694E	7		238.13		0.1632E-03	0.1019E-01		5.3823	229658
6121.00	0.6388E	2	7	237.61		0.13576-03	0.8477E-02		276	232939°D
6122.00	O N	12 0.7688E		237.09	-32.90	U.1129E-03	7.0		5 • 3623	236220.5
6123.00	0.4399E	2	_	236.57	-33°85	U-9386E-04			5.3523	239501.3
6124.00	0.3649E	N	-	236.05	-34.77	U. 7800E-04	\circ		5 • 3423	242782.1
6125.00	0.3025E	Ŋ		235.53	-35.70	0.6479E-04		لنا	5.5323	246063.0
6126.00	0.2507E 0	် ၁		235.01	-36.63	U-5380E-04	0.3359E-02		5.3223	249343.8
6127.00	0.20	0,3012	_	4.5	-37.56	0.4466E-04	0.2788E-02	0.1118E 02	.512	252624.6
6128.00	0.1721E C	2 0.2495E		233.98	-38.50	U.3706E-04	0.23146-02		•	255905.5
6128-21	0.16	12 J.2398E	3	233.87	138.50		0.2225E-U2	0.8928E 01	5.3002	256594.3
6129.00	0	2 0.2066E	o M	234.16	-38.17	0.3066E-04	•1914E	0.7681E 01	5.50B1	259186.5
6130.00	6.11	2 0.1712E	00	234.52	-37.52	0.2535E-04	0.1582E-02	0.6351E 01	5.3181	262467.2

TABLE A3. VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO₂ = 90%. MEAN MOLECULAR WEIGHT = 42.41) - Continued

VENUS M	VENUS MODEL ATMOSPHERES MEAN-MOLECULAR WGT = 42	HERES COMPUTED : 42.41	TED FROM	FROM DATA FROM O PERCENT CARBO	FROM THE OCCULTATIONS CARBON DIOXIDE 10.0		OF MAKINER V AND PERCENT NITROGEN)	REGULUS	
RADIUS	PRES	PRESSURE	TEMPE	EMPERATURE	MASS DE	DENSITY	REFRACTIVITY	PRESSURE	ALTITUDE
X.	MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	N UNITS) X X	FEET
6131.00	0.9785E	0	234.89	-36.86	0.2097E-04	0.1	0.5253E 01		265748.0
6132.00	0.8112E	0.1176E	235.25	-36.21	0.1735E-04	0.1083E			269028•8
6133.00	•		235.61	-35.55	U.1436E-04	968E-0		•	272309.7
6134.00	0.5581E		235.98	-34.90	995		u i	1845.4	21084612
6135.00	0.4632	0 0	236.34	-34.24	9853E+0	0.6151E=03	0.2468E 01	5.3681	2/88/1-4
6136.00	0.3845E	٠ د	236.70	-33.59	8165510	?		•	α
6137-00	0.3193E	0 9	237.07	-32.94	5768ETO	0.4225E=03.			285433.
6138•00	0.2653E	0.3847E-01	237.57	132.28	0.5904F105	0.3368F103	0-1400E 01		288715.9
6139-00	0-2204F			131.63	to 1	0.2906E-03		5.4081	291994•7
6140.00	0.1833E	0	2	6.0	0.3863E-05	411E-0		5.4181	295275.6
6141.00	0.1524E			-30.33	206E-0	002E-0		5.4281	298556.4
6142.00	0.1268E	_	14	-29.68	662E-0	0.1662E-U3	96,70E	5.4381	301837.3
6143.00	0.1055	0.1530E-01	239.24	-29.03	0.2211E-05	0.1380E-03	0.5540E 00	5.4481	305118.1
6144.00	0.8784E U		V	-28.38	8376	0.11476-03		1004-01	0.000000000000000000000000000000000000
6145.00		0.1060E=01	239.96	121.13	0.1527E-05	0. 4993 (E-04	0.82826E 00	1001-0	217040-6
0740	0.00000			127.08	0-12/05/00	0 - 7 - 50 E = 04		10.44	318241-5
00.44.0	0.00°C		241-04	125.78	0.87916-05	0.5488F-04	200 700 F	5.4981	321522
6149.00	0.3529E	0.5117E-0	241.40	-25-13	0.7317E-06	0.4568E-04	0.1832E 00	5.5081	324803.1
6150.00	0.2943E 0	0.4268E-0	241.76	-24.49	0.6092E-06	0.3803E-04		5.5181	328084.0
6151.00	0.2456E			-23.84	0.5074E-06	0.3167E-04	0.1271E 00	5.5281	331364.8
6152.00	0.2050E 0			-23.19	0.4227E-06			5.5381	334645.6
6153.00	0.1711E	0.2482E-02	242.84	-22.55	U-3523E-06		0.8826E-01	5.5481	337926.5
6154.00	0.1429E 0			-21.90	0.2937E-06		U. /358E-01	7.00 m	341707193
6155.00	0.1194			-21.26	0.2449E-06	0.1529E-04	0.6136E-01	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	344488
6156.00	0.9982	0.144/E-02		10.02	0.2043E-06	0.12755-04	0.49705.01	7.00	0.000.000
00.7619	0.8346			76.61-	0.1705610	0 1064E 104	10-37/24.0	1000	00.000000000000000000000000000000000000
0128400	0.6979E-01	0.1012E-02	20.44	75.61	0.1423E=06	0.8888E-05	0.2078F101	5.6081	257511-5
0104600		0.4000.0	20. 4.70	000	0-11000-00	0.4200E=05	0.2487E-01	1 × 1 × 1 × 1	360802.4
6161-00	0.0004.0	0.5930F-0	245-70	17.39	0.8298F-07	0.5180F-05	0.2078F-01	5.6281	6417
6162 • 00	0.3424E-01	0.4965E-0	246.06	-16.75	0.6936E-07	0.4330E-05	0.1737E-01	5.6381	367454.1
.6163.00	0.2868E-01	0.4159E-03	246.41	-16,11	0.5799E-07	0.3620E-05	0.1452E-01	5.6481	370734.9
6164.00	0.2403E-01	0.3484E-0	246.77	-15.47	0.4850E-07	0.3028E-05	0.1215E-01	5.6581	374015.7
6165.00		_	247.13	-14.83	U.4058E-07	0.25336-05	0.1016E-01	5.6581	377296.0
6166.00		Ö	247.48	-14.19	0.3396E-07	0.2120E-05	0.8508E-02	5.6781	380577.4
6166.53	0.1	ċ	247.67	-14.19	0.3091E-07	0.193UE-U5	0.7744E-02	5.6834	382314.0
6167.00	0.1417	o		-8.38	0.2812E-07		0.7044E-02	5.7540	383858
6168.00	0.1193		2		U-2308E-07	0.1441E-05	0.5783E-02	5.9040	387139.1
6169.00	O	0.1464E-U	263.61	14.83	U. 1904E-07	ှ	0.4771E-02	6.0540	390420.0
6170.00	0.8577		270.05	26.43	578E-0	0.9856E-06	0.3955E-02	6.2040	393700.8
6171.00	0.7314E-0	0.1060E=0	276.49	38.02	0.1314E-07	0.8207E-06	0.3293E-02	6.3540	396981.ed
4.5	,	2000	66.787	00.64	013660	0.00025-00	0.22.25.02	01010	j :
01/2000	0 - 53 / 8E - 0 2	0.178E-04	787.50	0 T • T 8	0 4720E-08	0.57676-00	0.2512E=02	1 0	4000404 600000
) 1	,	0.01215-04	770017	0.4.4		001-001-001-001-001-001-001-001-001-001	70-30+41-0	0	1 1 2000

TABLE A3.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE ($CO_2=90\%$, MEAN MOLECULAR WEIGHT = 42.41) - Continued

VENUS M	VENUS MODEL ATMOSPHERES MEAN MOLECULAR WGT = 42.	HERES COMPU = 42.41	COMPUTED FROM DATA .41 (90.0 PERCENT		FRUE THE OCCULTATIONS CARBON DIOXIDE 10.0		OF MARINER V AND REGULUS PERCENT NITROGEN)	REGULUS	
RADIUS	PRESSURE	รบกิย	TEMPER	EMPERATURE	MASS DE	DENSITY	REFRACTIVITY		ALTITUDE
×	MILLIBARS	LBS/SQIN	KELVIN F	FAHRENHEIT	CM/CUCM	LBS/CUFT	N UNITS) X X	FEET
6175,00	Ö	0.5812E-04	302,21	84.31	0.6582E-08	0.4109E-06	0.1648E-02	6.9540	410105.0
6176.00	0.3476E	0.5041E-04	308.63	95.86	0.5588E-08	0.3489E=06	G.1400E-02	7.1040	413385.8
6177.00		0.4385E-04	315.04	107.41	0.4761E-U8	(JV	0.1192E-02	7.2540	416666.6
6178.00	0.2	0.3826E-04	321.45	118.95	4070E-0	0.2540E-06	0.1019E-02	7.4040	419947.5
6178.53		0.3516E-04	325.49	118.95	3692E-0	0.2305E-06	0.9251E-03	7.4985	4.
6179.00		0.334 /E-04	327.86	130.48	0.3489E=08	0.2178E-06	0.8742E-03	1.0400	423228
00.0819	0.2024E-02	0.2936E-04	334.76	142.00	0.10011.008	0.18/3E=06	0. (519E-03	7 . 854.0	426509•I
6182.00		0.2276F=04	34.7.05	165.02	030F10	0.1398F-06	0.5610F103	0.400	433070 8
6183.00	0	0.2011F-04	353.44	176.53	942E-0	\sim	0.4865E-03	8.1540	436351.7
6184.00	0.1	0.1780E-04	359.83	188.03	589E-0	0.1054E-06	0.4231E-03	8.3040	439632.5
6185.00		0.1580E-04	366.21	199,51	0.1472E-08	0.9192E-C7	0.3688E-03	8.4540	442913.4
6186.00		0.1405E-04		210.99	0.1286E-08	0.8032E-07	0.3223E-03	8 • 6040	446194•2
6187.00		0.1252E-04		222.46	127E-0	0.7035E-07	0.2823E-03	8.7540	449475.0
6188.00		0.1118E-04		233.93	0.9893E-09	0.6176E-07	C.2478E-03	8.9040	452755.9
6189.00	0.6901E=03	0.1000E+04	391.69	245.38	0.8704E-09	0.5434E-07	0.2180E-U3	9.0540	456035.7
00.0019		0 - 3 A O O E - C O O O O O O O O O O O O O O O O O O	0.0000	750.07	V0110100	10 - 4 - 0 - 10 - 10 - 10 - 10 - 10 - 10	C*1722E103	0.0000	0
6192-00		0 - 7242F=05	404.41	270.71	0.60719E-09	0.4232E-07	0.1500FT	0+00-6	400000000000000000000000000000000000000
6193,00	16647°0	524F-0	417.11	291-14	U-5322E-09	0.3322E-07	0.13338-03	9.6540	469160.1
6194.00		0.5886E-05	423.46	302,55	0.4728E-09	U.2952E-07	0.1184E-03	9.8040	472441.0
6195.00		0.5320E-05	429.80	313.97	0.4209E-09	0.2627E-07	0.1054E-03	9.9540	475721.8
6196.00		0.4815E-05	436.13	325.37	C.3753E-09	0.2343E-07	0.9462E-04	10.1040	479002•6
6197.00		0.4364E-05	445.46	336.77	U.3352E-09	0.2092E-07	0.8397E-04	10.2540	432283.5
6198.00	0.2732E-03	0.3961E-05		348.16	0.2999E-09	0.1872E-U7	0.7512E-04	10.4040	485564•3
6199.00	0.2483E-03	0.3601E-05	455.1	359.54	U.2687E-09	0.1677E-07	0.6731E-04	10.5540	488845
6200.00	0.7260E-03	0-3277E-05	461.4	370.492	0.2411E-09	0.1505E-07	0.6041E-04	10 - 7040	492126
6201.00	0.2060E-03	0.298/E-05		382.28	0.216/E-09	0.1353E-0.	0.5450E+04	0400°	470400
6202-00	0.18805-03	0.2400E-05	4 4 6 00	404.04	0.1754F-09	0.1218E=0/	0.448876104	11.0040	440087 501068.5
6204.00		278F-0	486.67	416.34	0-1587F-09	0.9911F-08	0.3977E-04	11.3040	05249
6205.00	0	0.2087E-05	492.97	427.68	0.1434E-09	0.8958E-US	0.3594E-U4	11.4540	508530.1
6206.00	0.13	0.1913E-05	499.27	439.01	0.1298E-09	U.8108E-08	U.3253E-U4	11.6040	511811.0
6207.00		0.1756E-05	505.56	450.34	0.1176E-09	0.7347E-08	0.2948E-04	11.7540	515091.8
6208.00		0.1614E-05	511.84	461.65	C.1067E-09	0.6667E-08	0.2675E-04	11.9046	18572.
6209.00		484E-0	518.13	472.96	U.9701E-10	0.6056E-08	0.2430E-04	12.0540	
6210.00		0.1367E-05	524.40	484.26	U-8824E-10	0.55086-08	0.2210E-04	12.2040	524934.5
6211.00	୍	0.126UE-05	530.68	495.56	J.8035E-10	0.5016E-08	0.2012E-04	12.3540	528215.2
6212.00		0.1163E-05	536.95	506.84	0.7325E-10	0.4573E-08	0.1834E-04	12.5040	531496.1
6213.00		0.1074E-05	543.22	Н	0.6685E-10	0.4173E-08	S	12.6540	534777.0
6214.00	0.68	0.9929E-06	549.48	529.40	0.6107E-10	U-3813E-08	0.1530E-04	12.8040	538057.7
6215.00		0.9187E-06	555.74	540.66	0.5585E*10	0.3487E-08	0.1399E-04	12 • 9540	541554 5
02129	0.5868E-04	0.85007E-06	201.49	55T 675	0.51146-10	0.919ZE=08	0.12816-04	10 0EAC	0.440 H V = V
000		72175		1000	11000	0.04070.00	- 1-	0.404.40	ייים היא ת היים היא ת
00.0120	0.00400	0.67075-06	71.4.4	- 0	011117700	0.2445	401100000	10.40	C - C - C - C - C - C - C - C - C - C -
0004770		0.01941-00	97056	0	0.39475	0.14047-00	0.78875100	0.00	0.100

Table A3.- Venus model atmospheres, extrapolation of mariner 5 data to surface, adiabatic lapse rate (${\rm CO}_2$ = 90%, mean molecular weight = |42.41) - Concluded

	ALTITUDE	FEET	557742.8	561023.6	564304.5	567585.3	574147.0	577427.8	580708.7	583989.5	587270.3	590551.2	593832.1	597112.8	600353.7	603674.6	606955.3	610236.2	613517.1	616798.0	620078.7	623359.6	020040.5	62992I•3	1.202000	036483.0	639763.8	643044.6	646325.5	649506.3	652887.2	656168•0	656168•0
REGULUS	PRESSURE SCALE HT	ς 1 χ Σ	13.7040	13.8540	14.0040	14.1540	14.4540	14.6040	14.7540	14.9040	15.0540	15.2040	15.3540	15.5040	15.6540	15.8040	15,9540	16.1040	16.2540	16.4040	16.5540	16.7040	16.8540	17.0040	0.501.	17.5040	17.4540	17.6040	17.7540	17.9040	18.0540	18.2040	18.2040
° CF MARINER V AND I PERCENT NITROGEN)	REFRACTIVITY	N UNITS	0.9089E-05	0.8361E-05	0.7698E-05	0.7094E-05	0.6040E-05	0.5581E-05	0.5160E-05	0.4775E-05	0.4422E-05	0.4C98E-C5	0.3801E-05	0.3528E-05	0.3277E-05	0.3046E-05	0.2833E-05	0.2637E-05	0.2456E-05	0.2289E-05	0.2135E-05	0.1992E-05	0.1860E-05	0.1738E-05	0 - 1675E-05	0.1520E+05	0.1422E-05	0.1332E-05	0.1248E-05	0.1170E-C5	0.1398E-JS	0.1030E-05	0.1030E-05
	ENSITY	LBS/CUFT				0.1768E-08			0.1286E-08									0.6573E-09	0.6122E-09		0.5321E-09	0.4965E-09	0.4636E-09	0.4332E-09	0.4050E-09	C-3788E-09	0.3545E-09	0.3320E-09	0.3111E-09	0.29175-09	0.2736E-U9	0.2568E-09	0.2568E-09
FROM THE OCCULTATIONS CARBON DIOXIDE 10•0	MASS DENSITY	GM/CUCM	0.3628E-10	0.3337E-10	0.3073E-10	0.2832E-10	0.2411E-10	0.2227E-10	0.2060E-10	0.1906E-10	U.1765E-10	U-1636E-10	0.1517E-10	0.1408E-10	0.1308E-10	0.1216E-10	0.1131E-10	0.1052E-10	0.9806E-11	0.9139E-11	U.8523E-11	U.7953E-11	U.7426E-11	0.6939E-11	0.648/E-11	0.6068E-11	0.5679E-11	0.5319E-11	0.4984E-11	0.4672E-11	0.4383E-11	0.4113E-11	0.4113E-11
	TEMPERATURE	FAHRENHEIT	596.88	608.10	-	630.52			675.27		_		,-	•	7	•		, -							-				897.31	908.34	•		930,37
TED FROM DATA	TEMP	KELVIN	586.97	593.20	288.43	605.66	618.10	624.31	630.52	636.73	645.93	649.13	655.32	661.51	07.799	673.88	90.089	686.23	692.40	698.56	704.73	710.88	717.04	723.19	(29.33	735.48	741.61	747.75	753.88	760.00	766.13	772.24	772.24
HERES COMPUT = 42.41 (SURE	LBS/SOIN	0.6313E-06	0.5871E-06	0.5464E-06	0.5090E-06	0.4425E-06	0.4131E-U6	0.3859E-06	0.3607E-06	0.3374E-06	0.3158E-06	0.2958E-06	0.2773E-06	0.2600E-06	0.2440E-06	0.2291E-06	0.2152E-06	0.2023E-06	0.1903E-06	0.1791E-06	0.1686E-06	0.1589E-06	0.1498E-06	0.1413E-06	0.1333E-06	0.1258E-06	0.1188E-06	0.1123E-06	0.1062E-06	0.1004E-06	0.9509E-07	0.9509E-07
VENUS MODEL ATMOSPHERES COMPUTED FROM DATA MEAN MOLECULAR WGT = 42.41 (90.0 PERCENT	PRESSURE	MILLIBARS	0.4354E-04		0.3768E-04				0.2661E-04									0.1484E-04	0.1395E-04									0.8199E-05		-	0.6929E-05	0.6558E-05	0.6558E-05
VENUS M	RADIUS	¥	6220.00	6221.00	6222.00	6223.00	6225.00	6226.00	6227.00	6228.00	6229.00	6230.00	6231.00	6232.00	6233.00	6234.00	6235.00	6236.00	6237.00	6238.00	6239.00	6240.00	6241.00	6242.00	6243.00	6244.00	6245.00	6246.00	6247.00	6248.00	6249.00	6250.00	6250.00

Table A4.- Venus model atmospheres, extrapolation of mariner 5 data to surface, adiabatic lapse rate (co_ = 85%, mean molecular weight = 41.61)

18 MARCH 68

RADIUS	ALT	ALTITUDE	PRESS	SURE	TEMPE	EMPERATURE	MASS DE	DENSITY	PRESSURE	SCALE HT	TEMPERATURE	SPECIF
×	Σ	FEET	MILLIBARS	LBS/SQIN	KELVIN F	FAHRENHEIT	GM/CUCM	LBS/CUFT	KM KM	KM/KM KM/KM	DEG K/KM	(CP/R)
6091.0	41.0	134514.4	0.4726E 04	0.6852E 02	429.90	314.14	0.5501E-02	0.3434E 00	608.6	and promise a con-		
0.0609	0	131233	0.52)E 0	438.83	330.22	0.5962E-02	o	10.013	-0.2037	-8.9280	4.9085
0.000		127052	_ c) 0-8367E 02	467.70	346-10	0.66516-02	0.4027F 00	10.215	-0.2023	-8.8700	4.9422
		, ,	1 69 69 C	0.9219F 02	456.52	62.0	4079A	0.43516	0.41	-0.2010	18.8147	4.9748
)	110131		ار		000	f)			-0.1997	-8.7611	5.0069
6087.0	37.0	121391.0	0.6992E 04	_	465.28	377.84	0.7521E-02	0.4695E 00	10.616	-0.1984	-8.7096	5.0382
0.9809	36.0	118110.2	0.7676	0.1113E)	. •	393.52	.8105E	0.5060E	H 20	~	-8.6591	5.0692
6085.0	35.0	114829.4	0.8413E 04	0.1219E 03	482.65	409•11	0.8723E-02	0.5446E 00	11.012	-0.1960	18.6099	5.0999
6084.0	34.0	111548+5	0.92056	0.1334E 03	491.27	424.62	0.9378E-02	0.5854E 00	11.208			100
6083.0	33.0	108267.7	0.1005	0.1458E 03	499.83	440.03	0.1006E-01	0.6286E 00	11.403	-0.00 C	700	2 7 7 7
6087.0	32,0	104986.8	(9.92 ATM 0.1097E 05) 0.1590E 03	508.35	455.37	0.1080E-01	0.6742E 00	11.597	857.0-	-8.5165 -8.5165	26196
6081.0	31.0	101706.0	(10.82 / 0.1195E	0.1732E 0	16	70.6	П	.7224E	11.789	-0.1927	-8.4718	5.1881
0.080	30.0	98425.2	(11.79 ATM 0.1299F 05) 0.1884F 03	525.26	485.80	0.1238E-01	0.7732E 00	11,981	-0.1916	-8.4277	5.2170
0.9703	29.0	77 77 70	_) 0.2047F 0	33.6	8.00	0	0.8267E	_	-0.1906	-8.3847	5.2455
	N 1	-) 6	(13,93		i i		1 0			-0.1896	-8,3428	5.2735
6078.0	28•0	91863.5		0.2221E 03	24T.49	26.616	0.14145-01	0.8832E 00	105.71	-0.1886	-8.3020	5,3012
6077.0	27.0	88582•6	0.1660E 16.38	0.2407E 03	550.29	S	0.1509E-01	0.9425E 00	ŝ	-0.1876	-8.2626	5.3282
0.9109	26.0	85301.8	ပီ ်	0.2605E 03	558.56	545.74	0.1609E-01	0.1005E 01	12,738	1067		0.48.0
6075.0	25.0	82021.0	0.1942E 05	0.2816E U3	566.79	560.55	0.1715E-01	0.1070E 01	12,924	20 G	0 . L . L	יים מים מים
6074.0	24.0	78740.1	0.2097	0.3041E 03	574.98	575.29	0.1825E-01	0.1139E 01	13.110	4		
6073.0	23.0	75459.3	(20.70 ATM) 0.3280E 03	583.13	589,97	0.1941E-01	0.1212E 01	13,295	-0.1849	-8.1504	5.4069
6072.0	22.0		0.2437	0.3535F 0	1 .2	04.5	0.2063E-01		13.479	-0.1840	-8.1148	5.4324
			(24.06	(11000	0		.0.71010	į L	677 61	-0.1832	-8.0801	5.4575
0.41.00	0 .	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	25.90	0.3803E 0). ()	010010	10-11412-01	0 0 1 0	9	-0.1823	8.0460	5.4825
0.0709	20.0	65616.8	0.2822E	0.4092E 03	607.38	633.62	0.2325E-01	0.1451E 01	13,845			
6069.0	10.0	62335.0) 0.4396F 03	615.39	648.04	0.2466F-01	0.1539F 01	14.027	0.1815	-8.0122	5.5074
•	`	١.			١							

TABLE A4.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO_2 = 85%, MEAN MOLECULAR WEIGHT = 41.61) - Continued

RADIUS	RADIUS ALT	ALTITUDE	PRESSURE	URE	TEMPE	EMPERATURE	MASS DE	DENSITY	PRESSURE		TEMPERATURE	
					- 1		in the same	-	SCALE HI	Ц	APSE RATE	- 1
KM	ΚM	FEET	MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	χ	KM/KM	DEG K/KM	(CP/R)
6068.0	18.0	59055	0.3254E 05	0.4719E 03	623.38	662.41	0.2613E-01	0.1631E 01	14.207			
1			(32,12				10-35/50	10 35051 0	100	-0.1799	-7.9467	5.5564
0.000	0.1	201/402	0.34.45 ATM)	U.SUOIE US	70.100	71.010	70-31017.0	J.	1000+1	-0.1792	-7.9154	5.5803
0.9909	16.0	52493.4	0.3740E 05	0.5423E 03	639.24	690.97	0.2928E-01	0.1828E 01	14.566			ţ
6065.0	0.8	4921246	(36.91 ATM) 0.4004F 05	0.5806F 03	647.13	705.17	0.3096E-01	0.1933E 01	14.745	18/1•0-	94881-	2.6039
			(39.52 ATM)		1			1		-0-1777	-7.8544	5.6274
0.4909	14.0	45931.7	0.4283E 05	0.6211E 03	654.99	719.31	0.3273E-01	0.2043E 01	14.923	-0.1769	-7,8241	5.6510
6063.0	13.0	42650.9	0.5	0.6639E 03	662.81	733.40	0.3457E-01	0.2158E 01.	15.100		1	. 1
6062.0	12.0	39370.0	(45.18 ATM) 0.4890E 05	0.7090E 03	670.61	747.43	0.3649E-01	0.2278E 01	15.276	-0.1762	-1.7942	5.6746
		1			1					-0.1755	-7.7648	5.6979
6061.0	11.0	36089.2	0.5219E 05 (51.50 ATM)	0.7567E 03	678.38	761.41	0.3850E-01	0.2403E 01	15.451	-0.1747	-7.7359	5.7211
0.0909	10.0	32808.4	0.556	0.8070E 03	686.12	775.34	0.4060E-01	0.2534E 01	15.626	() ()	1	ı
0.950.9	0.0	29527.5	(54.93 ATM) 0.5931E 05	0.8601E 03	693,83	789.22	0.4278E-01	0.2671E 01	15,800	0+110-	0,0,0	20(43
			58.54	1	ŗ	0000	10-11-01	10000	750.91	-0.1734	-7-6798	5.7667
6058•0	O 100	707707	(62.34 ATM)	U.9139E US		60.508	0.42065	- 1	+12.01	-0.1727	-7.6525	5.7892
6057.0	7.0	22965.8	0.6723E	0.9748E 03	709.16	816.83	0.4744E-01	0.2962E 01	16.146		-7. K 2E 0	6.0112
6056.0	0.9	19685.0	0.7150E 05	0.1036E 04	716.79	830.56	0.4992E-01	0.3116E 01	16.318	021100-	(6000)	;
4	4		(70,56				0.000	10 37755	14.400	-0.1714	-7.5998	5.8331
0.6509	9	16404.2	0.15995	O.IIOIE 04	60.471	844.624	10-30676•0		064.07	-0.1707	-7.5735	5.8553
6054.0	4.0	13123.3	0.8072E	0.1170E 04	731.97	857.88	0.5519E-01	0.3445E 01	16.661	, 1	i i	ú
6053.0	3.0	9842.5	(79.66 ATM) 0.8568E 05	0.1242E 04	739.52	871.47	0.5799E-01	0.3620E 01	16.831	70/1-0-	-1.004/0	2001/4
1		d .	84.56		1		1000		900	-0.1695	-7-5222	5.8991
6052.0	2.0	6561.6	0.9090E	0.1318E 04	40 - / 4/	885.01	10-30A06-0	0.38025.01	00001	-0.1689	-7.4976	5.9205
6051.0	1.0	3280.8	0.9638E	0.1397E 04	754.54	898.51	0.6393E-01	0.3991E 01	17.169	9	400 A	9
6050.0	0.0	0.0	0.1021E 06	0.1481E 04	762.02	911.97	0.6708E-01	0.4187E 01	17,337	6001.0	+6-+	•

TABLE A4.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO_2 = 85%, MEAN MOLECULAR WEIGHT = 41.61) - Continued

VENUS MC	ENUS MODEL ATMOSPHERES EAN MOLECULAR WGT = 41.	SSPH VGT		707	COMPUTED FROM DATA 61 (85.0 PERCENT	DATA CENT	FROM THE OCCULTATIONS CARBON DIOXIDE 15.0		OF MAKINER V AND H PERCENT NITRUGEN)	REGULUS	18 MARCH 1968	
RADIUS	g.	PRESS	SSURE		TEMPE	EMPERATURE	MASS DE	DENSITY	KEFRACTIVITY	PRESSURE	ALTITODE	
χ	MILLIBARS	35	LBS/SGIN		KELVIN	FAHRENHELT	GM/CUCM	LBS/CUFT	N UNITS	SCAL KE KR	ABOVE SORP FEET	
6090.78	0.4833E		0.7008E	0.2	431.86	317.69	0.5601E-02	3496E	0.1400E 04	•	133790.3	
6091.00	0.4726	0.0			429.90		0.5501E-02	0.3434E	.1375E	8608.6	154514.4	
6092,00	0.4263E				420.99	·	0.5066E-02	0.3163E 00	0.1266E 04	8609.6	137795.2	
00.4609	0.3447	† d	عا. ك		403.20	- 17	0.46274F102	0.2668E		0,000	1410704	
6095.00	0	40	ينا ل		394,32	500	U.3914E-02		.9784E	8600.6	9 6	
00.9609	0.2760	94	نيا		385,44	234.13	U.3578E-02		an	8608.8	150918.6	
00.7609	0.2461	04	ш	0.5	376.57	18.1	0.3264E-U2		*8159E	8.6098	154199.5	
6098.00	0.21885	0.0			367.70	Λ.	0.2971E=02	0.1855E 00	0.7427E 03	8 4098	157480.3	
00.0019	0.1715F	2 0	0.2487F	2 C	340.08	170.24	0.2093E=02	0.1584E	0.661118 03	8 - 10 0 48	16676161	
6101.00	0.1511E	04	u		341.13		U-2210E-02	0.1379E		7.8098	167322 8	
6102.00	327	0.4			332,28	138.44	0.1992E-02	ш.	0.4979E 03	7.6098	170603.6	
6103.00	0.1162E	04	ш		323.44	122.53	U.1790E-02	ш	•4476E	7.4098	173884.5	
6103,18	0.1134E	7 3	0.1644E	25	321.86	122.53	0.1756E=02	0.1096E 00	0.4390E 03	7.3739	174474.0	
6105,00	·	1 5	111		207.97		0.1427F=02	0.8914F1		7.0462	180446.2	
6106.00	0.7631E	03			299.42		0.1269E-02	0.7923E-01	0.3172E	6.8662	183727.0	
6106.97	0.6614E	03			291.72	9.29		0.7046E-01	0.2821E	6.6917	186908.5	
6107.00	0.6584E	03	1111		291.50	65.04		0.7019E-01	0.2810E	6.6868	870078	
6108.00	0.5659E	0 0			284.43	52.32	ന	0.6181E-01	0.2474E	6.5268	190288.7	
00.0114	O 4 2 4 0 E	n e	0 1020E		270 21	54.00 50.00	0.8691E108	0.5426E-0-	0.21/25	0.0000	0.0000VI	
6111.00	0.3510	9 6		1.0	263.26	14.20		0.4747E-01	0.1657F	6.0468	200131.2	
6112,00		03	4305E		256.21	1.51		0.3595E-01	0.1439E	5.8868	203412.0	
6113.00	0.2499	03	ш		249.16	-11.16		0.3111E-01	0.1245E	5.7268	206692.9	
6114.00	0.2093E	60		0.7	242-12	-23.84		0.2681E-01	0.1073E	5.5668	209973.7	
6114.51	0.1909E				238,53		0.3974E-03	0.2481E-01	0.9934E	5 4853	211646.2	
6115.00	0.1450	n e	0.2330E		73% 40	75.00.1	0.3659E-03	0.1834E#U1	0.9145E	0.44.0 0.450	713754°5	
6117.00					230.00		U-2594E-03	0.1619E-01	0.6485E	5.2932	219816.2	
6118.00	0.9942	0.5		T0	226.57	-51.83	0.2176E-03	U.1358E-U1	0.5440E	5.2161	223097.1	
6118.21	0.9550	0.5	ш		225.85	-51,83	U.2097E-U3	0.1309E-01	0.5241E	5.1999	223785.9	
6119.00	0.8202	2 0			225.45	153.84	U.1804E-03	0.1126E-01	0.4509E	5.1920	26377	
6120.00	0.55/54	2 0	0.9808C	000	201 11	124.70	0.1490F-03	0.9306E-02	0.3725E	5 - 1820 1430	229058•8 393030: 8	
6122,00	0.4595	0 0			223.93	1.00	0-1016F-03	0.6346F-02	0.2540F	5-1620	236220.5	
6123.00	0.3785	50	ш		223.42	-57.49	U-8389E-04	0.5237E-02	.2096E	5.1520	39501	
6124.00	0.3116	02	ш	00	222.92		0.6921E-04	0.4321E-02	0.1730E	5.1420	242782.1	
6125.00	0.2565E	0.2	<u>ш</u> :		222.41	OI :	U.5708E-04	0.3563E-02	0	5.1320	46063	
6126,00	0.2110	ر د د	360E		221-90		0.4706E-04	0.2938E-02	0.1176E	5-1220	49343	
6128.00	0.1427	200	0.2069F	000	220 89	-62-05	0.38/8E=04	0.1994F-02	0.7085E	5-1120	757674 0 755905 5	
6128.21	0.1369	0.2	1 12		220.79	-62.05		5	0.7666E	5.0990	56594	
6129.00	0.1173E	05	701E		221.07	_	0.2623E-04	0.1637	0.6556E	5.1078	259186.3	
6130.00	0.9650E	03	0.1399E	00	221.43	-61.08	0.21535-04	ਂ	0.5381E	5.1178		

TABLE A4.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADLABATIC LAPSE RATE (CO₂ = 85%, MEAN MOLECULAR WEIGHT = 41.61) - Continued

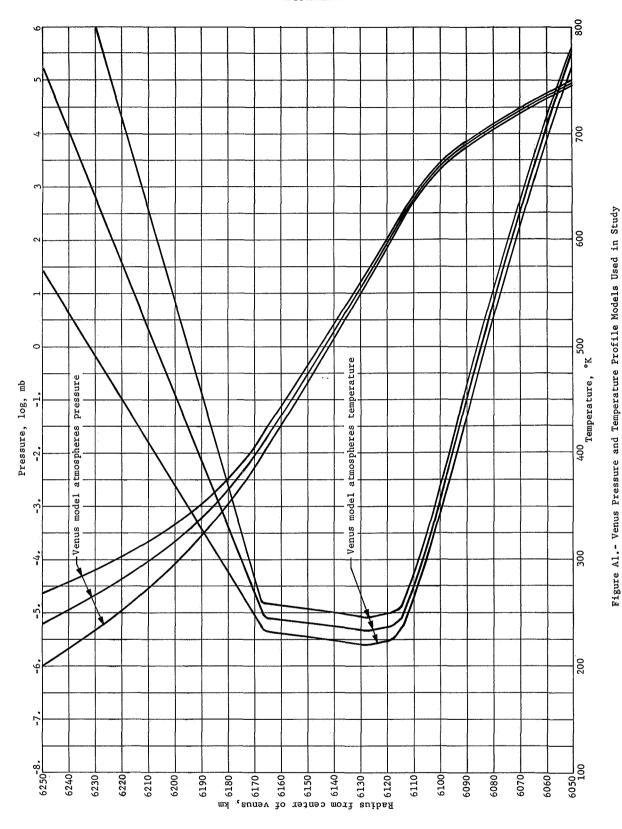
0.17.04.0	0000	30113	TOMBE	TOTAL	T O O O O O	DENCITY	REFERACTIVITY		ALTITUDE
KADIOS	PRESSOR	SURE	- - - - - - - - - - - - - - - - - - -	AA I UKE	MASS UR			SCALE HT	ABOVE SURF
Σ	MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GMYCUCM	LBS/CUF-T	STIND		FEET
	0.7938E	0.1151E 00		-60.43	0.1767E-04	0.1103E-02	0.4418E 01	٦.	265748.0
N	0.6533E		22	-59.78	0.1452E-04	0.9065E-03		.137	269028.8
6133.00	0.5378E		222.51	-59.13	U-1193E-04	0.7449E-03		.147	272309.7
6134.00	0.4430E	0.6423E-01	222.87	-58.48	0.9808E-U5	4.6123E-03	ш	.157	275590.5
6135.00	0.3650E	0	223.23	-57.84	0.8065E-05	0.5035E-03	0.2015E 01	9	278871.4
6136.00	0.3008E	0.4	223.59	-57.19	0.6634E-05			7	282152.2
6137.00	9		223.95	-56.55	0.5460E-05	0-3408E-0	0.1364E U1	7.	285433.1
6138.00	0.2046E	0.5	224.31	-55.90	0.4495E=05	0.2		7	288713.9
6138.21	_		224.38	-55.90	0.4315E+05	0.2694E-03		2.1997	289402•8
6139.00	_		224.67	-55.25	0.3702E-05	0.2311E-03		207	291994.7
6140.00			225.03	-54.61	0.3050E-05	0.1904E-03		Çį.	295275.6
6141.00	_		225.38	-53.97	0.2513E-05	0.1569E-03		.227	298556.4
6142.00	_		225.74	-53.32	0.2072E-05	0-1293E-03	.5179E	5.23/8	30183/•3
6143.00	_		226.10	-52.68	0.1709E-05	0.1067E-U3	0.4272E 00	5.2478	305118
6144.00	0.6493E		226.46	-52.04	0.1410E-05	0.88045-04		5,4278	0.0000000000000000000000000000000000000
6145.00	0.5369E		226.81	-51.39	0.1164E-05	0.726/E-04			3116/9.8
6146.00	0.4442E	္	227.17	-50.75	0.9611E-06	0.6000E-04		3	314960.6
6147.00	0.3676E		227.53	-50.11	0.7938E-06	0.4956E-04		V	318241.5
6148.00	0.3043E		227.88	L+6.64-	0.6559E-06	0.4095E-04		5.2978	321522.3
6149.00	0.2520E		228.24	-48.83	0.5422E-06	0.3385E-04		5.3078	324803.1
6150.00	0.2087E	°,	228.59	-48•19	0.4483E-06	0.2799E-04	0.1120E 00	ന്നു.	328084.0
6151.00	0.1730E		228.95	-47.55	0.3708E-06	0.2315E-04	0.9268E-01	5.3278	331364.8
6152.00	0		229.30	-46.91	0.3068E-06	0.1915E-04	0.7669E-01	5.3378	334645.6
6153.00	0.1189E	0.1724E-0	229.66	-46.27	0.2540E-06	0.1585E-04	0.6348E-01	5.3478	337926.5
6154.00	Ų		230.01	-45.63	0.2103E=06	0.1313E-04	0.5257E-01	.357	341207.3
6155.00			230.37	66.44-	0.1742E-06	0.1087E-04	0.4354E-01	5.3678	344488.1
6156.00	Ų		230.72	-44.36	0.1443E-06	0.9012E-05	0.3608E-01	5.3778	347769.0
6157.00	0	0.8187E-03	231.08	-43.72	0.1196E-06	0.7471E-05	0.2991E-01	.387	351049.8
6158.00	0	0.6801E-03	231.43	-43.08	0.9923E-07	0.6195E-05	0.2480E-01	.397	354330.7
6159.00	Ó	0.5652E-03	231.78	-42.45	0.8231E-07	0.5138E-05	0.2057E-01	407	357611.5
6160.00	Ò	0.4698E-03	232.14	-41.81	0.6830E-07	0.4264E-05	0.1707E-01	•417	360892.4
6161.00	0	0.3907E-U3	232.49	-41.18	U.5669E-07	0.3539E-05	0.1417E-01	. 427	364173.2
6162.00	0	0.3250E-03	232.84	-40.54	0.4707E-07	0.2939E-05	0.1176E-01	•437	367454.1
6163.00	J	0.2705E-03		-39.91	0.3910E-07	0.2441E-05	0.9773E-02	.447	370734.9
6164.00	_	0.2251E-03		-39.27	0.3249E-07	0.2028E-05	0.8120E-02	5.4578	374015.7
6165.00	0	0.1875E-03		-38.64	0.2700E-07	0.1686E-05	0.6750E-02	5.4678	377296.6
6166.00	_	0.1561E-03	234.25	-38.01	0.2245E-07	0.1401E-05	0.5612E-02	5.4778	380577.4
6166.13	0	0.1525E-03	234.30	-38.01	0.2192E-07		0.5479E-02	5.4791	381003.5
6167.00	0	0.1303E-03	237.95	-31.35	0.1843E-07		0.4607E-02	5.5661	383858
6168.00	0	0.1090E-03	242.15	-23.79	0.1515E-07		0.3788E-02	5.6661	387139.1
6169.00	0	0.9154E-04	246.34	-16.24	0.1250E-07	0.7805E-U	0.3125E-C2	5.7661	390420•0
6170.00	0	0.7708E-04	250.53	-8.70	0.1034E-07	460E-0	0.2586E-02	5.8661	393700.8
	0.4489E-02	0.6509E-04	254.72	-1.16	0.8592E-08	0.5364E-06	0.2147E-02	5.9661	396981.6
6172.00	0.3801	0.5512E-04	5	ñ		0.4468E-06	0.1788E-02	6.0661	400262.5
c									
6173.00	0.3228E-02	0.4681E-04	263.09	13.89	0.5978E-08	0.3732E-06	0.1494E-02	6.1661	403543

TABLE A4.- VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE ($CO_2=85\%$, MEAN MOLECULAR WEIGHT = 41.61) - Continued

US MODEL ATMOSPHERES COMPUTED FROM DATA FROM THE OCCULTATIONS OF MAKINER V AND REGULUS	
AND	OGEN
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MODE	MOLF.C
SU	Z

TABLE A4. - VENUS MODEL ATMOSPHERES, EXTRAPOLATION OF MARINER 5 DATA TO SURFACE, ADIABATIC LAPSE RATE (CO. = 85%, MEAN MOLECULAR WEIGHT = 41.61) - Concluded

		² 00)	≈ 85%, ME	AN MOLECULAR	WEIGHT = 41.6	$(CO_2 = 85\%$, MEAN MOLECULAR WEIGHT = 41.61) - Concluded	* Cl		
VENUS MOD MEAN MOLE	EL ATMOSPH CULAR WGT	VENUS MODEL ATMOSPHERES COMPUTED FROM DATA FROM THE OCCULTATIONS MEAN: MOLECULAR WGT = 41.61 (85.0 PERCENT CARBON DIOXIDE 15.0	ED FROM 85.0 PE	DATA FROM RCENT CARBO	THE OCCULTA	ATIONS OF MA 15.0 PERCE	OF MAKINER V AND PERCENT NITROGEN)	KEGULUS	
RADIUS	PRESSURE	SURE	TEMPE	TEMPERATURE	MASS DENSITY	ENSITY	REFRACTIVITY	PRESSURE SCALE HT	ALTITUDE ABOVE SURF
X X	MILLIBARS	LBS/SQIN	KELVIN	FAHRENHEIT	GM/CUCM	LBS/CUFT	N UNITS		FEET
6220.00	0-1117E-04	0.1620E-06	456.64	362.29	0.1174E-10	0.7334E-09	0.2936E-05	10.8661	557742.8
	0.1020E-04	0.1479E-06	460.70	369.59	0.1062E-10	0.6631E-09	0.2654E-05	10.9661	561023.6
	.9315E-05	0.1350E-06	464.75	376.88	0.9612E-11	0.6001E-09	0.2402E-05	11.0661	564304.5
	0.8513E-05	0.1234E-06	468.80	384.17	0.8706E-11	0.5435E-09	0.2176E-05	11.1661	567585.3
	0.7787E-05	0.1129E-06	472.84	391.45	0.7893E-11	0.4927E-09	0.1972E-05	11.2661	570866.2
	0.7128E-05	0.1033E-06	4/6.89	9 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	U. / 162E-11	VOLUE / 44+0	0.1/906-05	1000-11	0.4444
6226.00 0	0.59875-05	0.86826-07	484.97	413.27	0.59116-11	0.3690E-09	0.1477F-05	11.5661	580708-7
	0.5493E-05	0.7966E-07	489.00	420.54	0.5377E-11	0.3357E-09	0.1344E-05	11.6661	583989.5
_	0.5044E-05	0.7314E-07	493.04	427.80	U-4895E-11	0.3056E-09	U.1223E-05	11.7661	587270.3
-	J.4635E-05	0.6720E-07	497.07	435.05	0.4460E-11	0.2784E-09	0.11146-05	11.8661	590551.2
	0.4261E-05	0.6179E-07	501.09	442.30	0.4067E-11	0.2539E-09	0.1016E-05	11.9661	593832.1
	0.3921E-05	0.5686E-07	505-12	449.55	0.3711E-11	0.2317E-09	0.9276E-06	12.0661	597112.8
	0.3610E-05	0.5235E-07	509.14	456.79	0.3389E-11	0.2115E-09	0.8471E-06	12.1661	600393.7
	0.3327E-05	0.4824E-07	513.16	464.03	C-3097E-11	0.1933E-09	0.7741E-06	12.2661	603674.6
	0.3067E-05	0.4448E-07	517.18	471.26	0.28326-11	0.17685-09	0.708UE-06	17.3661	606955.3
	0.2830E-05	0.4103E-07	521.20	478.49	0.2592E-11	0.1618E-09	0.6479E-06	12.4661	610236.2
	0.2612E-U5	0.3788E-07	525.21	485.71	0.2374E-11	0.1482E-09	0.5934E-06	12.5661	613517.1
	0.2413E-05		529.22	492.93	0.2176E-11	0.1358E-09	0.5439E-06	12.6661	0.867919
	0.2231E-05		533.23	500.14	0.1995E-11	0.1246E-09	0.4988E-06	12,7661	620078.7
	0.2063E-05		537.23	507.35	0.1831E-11	0-1143E-09	0.4578E-06	12.8661	623359.6
	0.1910E-05	0.2769E-07	541-23	514.55	0.1682E-11	0.1050E-09	0.4204E-06	12.9661	626640.5
	0-1768E-05	0.2564E-07	545.23	521.75	0.1545E-11	0.9650E-10	0.3863E=06	15.0661	629921.0
	U. 1638E-05	0.23/6E-0/	549.23	528.94	U. 1441E-11	0.8874E-10	0.3552E=06	100 T 0 C T	1.202600 0.002500
	0 - ID IDE - 05	0.2203E-07	22.500	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	0 130/E-11	O MICAGE TO	0.5000E=00	1007 CT	000000000000000000000000000000000000000
	0 14095-05	0.2045F107	17.100	74.04.0	0-1704E-11		0013A00000	1000000	4 4 4 4 6 4 4 4
	0.1.0000.1.00 0.1.0000.1.00	10 H H / K H - O	07.100	100	0 1 1 0 0 0 1 1 T	0113076000	0.0000000000000000000000000000000000000	1004-01	10111
6247•60 0	0.112850	0-1/01E=0/	5600	564.85	0.10225-11	0.5889E-10	0.23578106	13.6661	644606.3
	0-1077T-0	0 1001 C	71.67.4	1000	0.07045-12	04 700010	0.01745104	13-7661	660887.2
	0.97635-06	0.1415F-07	577.13	572.01	U-8040F-12	0.5019E-10	0.2009F-06	13.8661	656168.0
	0.9763E-06	0.1415E-07	577.13	579.18	0-8040E-12	0.5019E-10	0.2009E-06	13,8661	656168.0



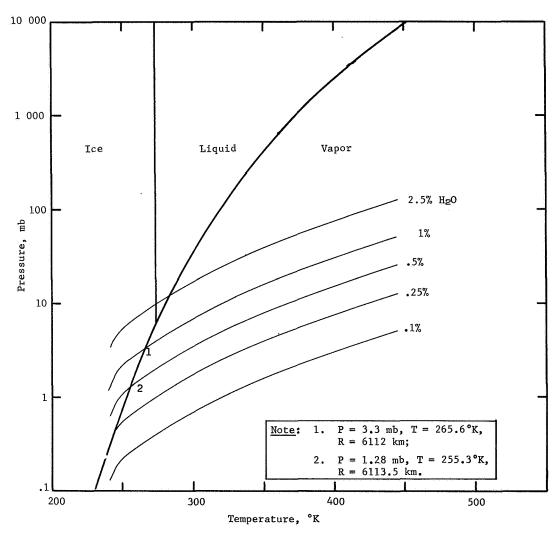
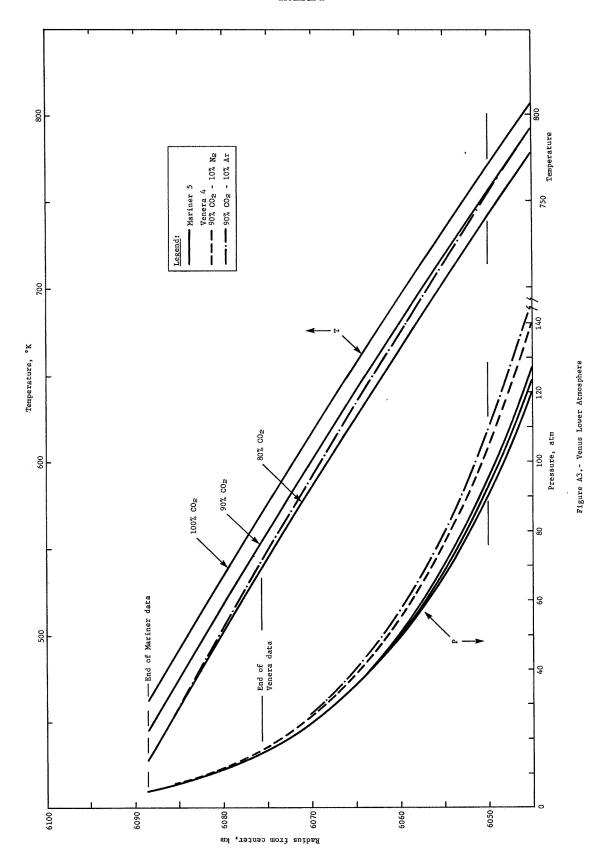


Figure A2.- Venus Pressure vs Temperature on H₂O Phase Diagram



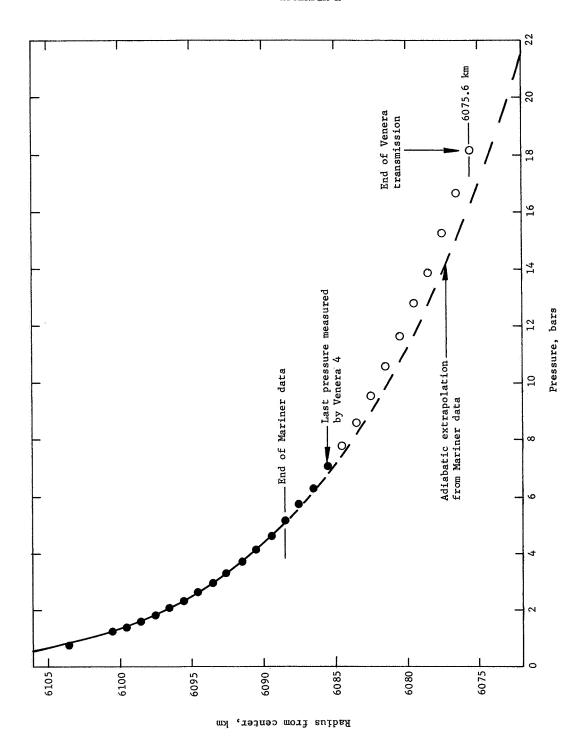
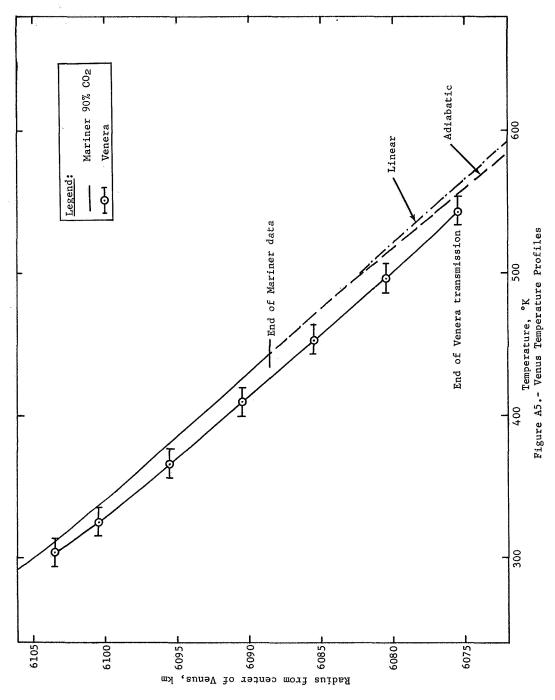


Figure A4.- Mariner and Venera Pressure Profiles



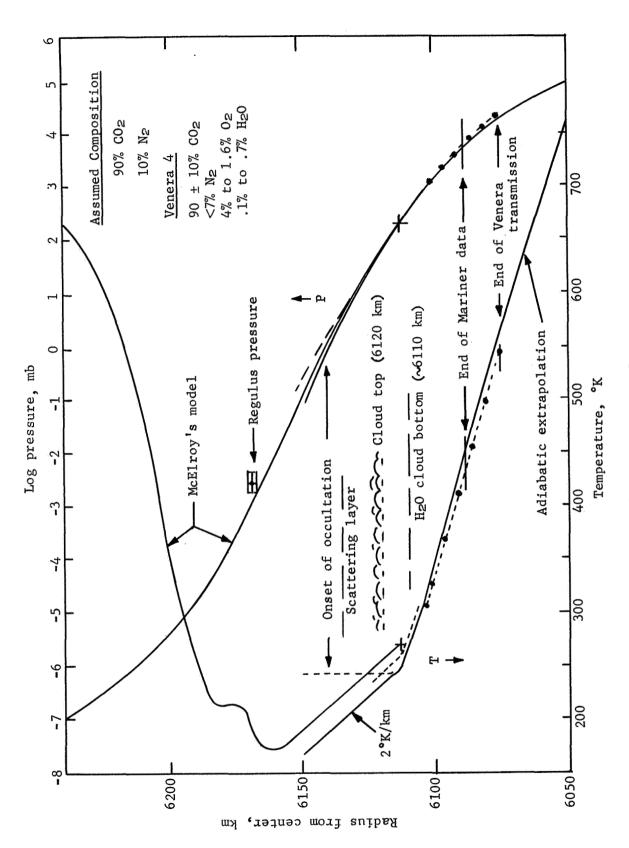


Figure A6. - Venus Atmosphere

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APPENDIX B

HEAT SHIELD ANALYSIS

by H. Edward Sparhawk and John R. Mellin Martin Marietta Corporation

APPENDIX B

The heat shield design requirements for a Venus entry vehicle have been studied for three entry modes: (1) entry from Venus orbit, (2) entry from Venus approach trajectory, and (3) entry from an approach trajectory that allows the spacecraft to swing by Venus and continue on a course to Mercury. The requirement for this study relative to the heat shield has been defined as:

- 1) Determination of the thickness and weight of ablative material required for the missions studied;
- 2) A definition of heat shield development requirements.

HEAT SHIELD REQUIREMENTS

The baseline aeroshell configuration for the three missions considered in the BVS study was selected as a spherically blunted, 55° half-angle cone. The approach taken to define the heat shield requirements for this vehicle was as follows:

- 1) Ablative materials were selected for analysis, which are consistent with the present state of the art in this technology;
- 2) The heat shield thicknesses and unit weights (fig. B1) were determined using nominal material properties, but using heating inputs that have been increased by appropriate uncertainty factors;
- 3) The sensitivity of the predicted backface temperature to uncertainties in both the aerothermal environment and to material performance unknowns were evaluated.

Ablative Material Consideration

The ablative heat shield thicknesses and weights determined for the three BVS missions were based on the properties of ablative materials that have been extensively ground tested and whose performance has been verified during Earth reentry flight test. The materials selected for this study are: Martin Marietta ESA-5500, a carbon filled elastomeric silicone ablator that was used on high heating rate leading edges of the PRIME vehicle; Avcoat 5026-39 HC-G Apollo material, which is a filled epoxy; and laminated carbon phenolic, which has been flight tested in numerous forms on ballistic entry systems. These materials, which represent the three basic types of charring ablation materials, each have specific advantages and disadvantages that must be weighed in terms of specific mission requirements. These are summarized in Table B1.

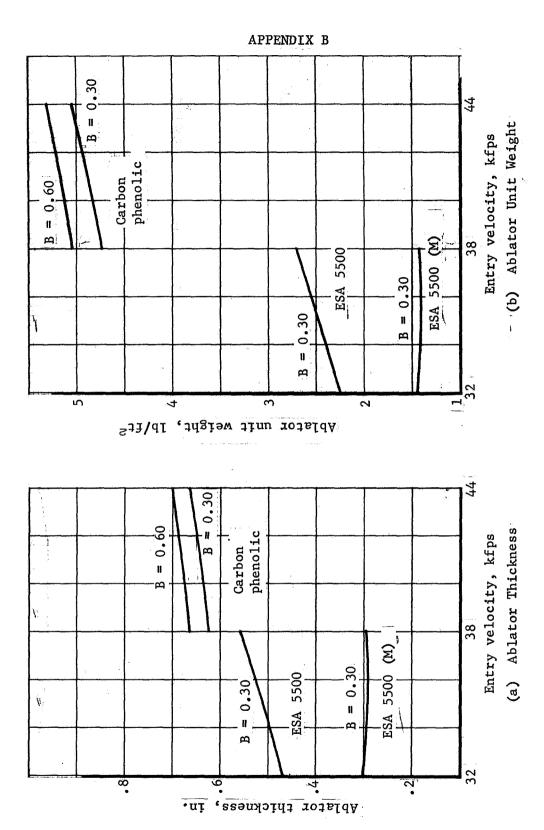


Figure Bl.- Ablation Material Required vs Velocity

TABLE BI.- HEAT SHIELD MATERIAL ENVIRONMENTAL SENSITIVITY

,			*	
Ļ	Thermo structural	Thermal stresses will be significant consideration	No problem	Possible problem area
Entry environment	Insulation efficiency	Poor	Boo 0	Best of materials being con- sidered
Entr	Shear	High (≈100 psf for high- pressure moldings)	Low (mechan- ical erosion at shears of 15 psf)	Low (mechan- ical erosion at shears of 15 psf)
	Low-temperature strain	No apparent problem; ther- mal expansion coefficient compatible with most structural	Flexible to -100°F; no problem	Rigid material; effects of sur- face cracking not available
	Vacuum effects	No apparent problem	Vacuum offgas- sing problem; cure process and/or resin modification re- quired	No apparent problem
	Launch Ioads	No problem	No problem	No problem
	Sterilization	No problem cure temper- ature 300°F	No apparent problem	Possible problem area
	Fabrication	Tape winding or shingle; flexible bond and/or mechanical attach	Vacuum bagging into H/C reinforcement Lorcement Lin; single cell injection for thickness No.5 in.; H/C rigidly bonded to structure	Single cell in- Possible jection into problem H/C reinforce- area ment; H/C rig-idly bonded to structure; casting possible
-		Carbon phenolic laminate	ESA-5500	Avcoat 5026- 39HCG

Developmental effort that is common to any material is the detail material processing required before application to the structural substrate and the actual fabrication and curing procedures to be followed. The effects of sterilization on the thermal and mechanical properties must be understood for any material ultimately selected.

After launch and before entry, the response of the heat shield to vacuum and space temperatures must be considered. Of the three materials being considered, carbon phenolic will be the least affected by these environments. Vacuum effects will be minimal because of the highly cross-linked nature of the phenolic resin system. Low temperature soak, although a consideration, is not expected to be a significant problem because the thermal expansion of carbon phenolic approximates that of most commonly used structural materials. Similarly, the ESA-5500 material will present no particular problem at low temperatures because it was specifically formulated with potential low temperature applications in mind. Offgassing of condensible volatiles is a definite problem with this type of material, which will require either resin modification and/or cure cycle changes. In either case, the final product must be reevaluated with respect to its low temperature strain capability. Epoxy-based materials, such as the Avcoat 5026-39HCG, become rigid at low temperatures and crack. For missions in which the heat shield is turned away from the sun, i.e., targeting for sunlight side of the planet, this could be a definite deterent to the use of this material.

During entry, the heat shield must survive a short (≈15 sec) thermal pulse composed of high convective and radiative heating rates and viscous shear levels. After the heat pulse, the heat shield must provide insulation between the hot surface and the structure for approximately 1 minute. Char retention is of paramount importance because reradiation from the high temperature surface is, considering the entire heat pulse, the most important heat-rejection mode. Mechanical erosion of the char drastically reduces the efficiency of a material because of a reduction in surface temperature and, hence, reradiation. When char is eroded, the majority of the heat input must be absorbed by the material. The char strength of carbon phenolic is vastly superior to that of either ESA-5500 or Avcoat 5026-39 HCG when high-pressure molding techniques are used. It is anticipated that this advantage will be retained for the fabrication procedure, which is developed for a Venus entry probe. However, because the strength of graphitic materials, in general, undergoes a sharp drop at temperatures above 6000°F, the char strength at the extreme temperatures predicted for Venus must be investigated.

The insulation efficiency of the heat shield is of great importance because the temperature rise of the structure must be limited during a thermal soakout period, which is approximately three times as long (45 vs 15 sec) as the heat pulse itself. In this respect, the Apollo material ranks first by virtue of its low density (33 lb/ft³) and low thermal conductivity (1.6 x 10^{-6} Btu/in.-sec-°R). Use of ESA-5500 does not result in a large penalty because its density is not high (58 lb/ft³), and it also has a low thermal conductivity (3.0 x 10^{-6} Btu/in.-sec-°R). The use of carbon phenolic would impose a large weight penalty because its density (91 lb/ft³) and thermal conductivity (9 x 10^{-6} Btu/in.-sec-°R) are both high.

The third major characteristic to be considered is the thermostructural capability of the ablative material, i.e., its ability to generate thermal stresses in the ablative layer and bondline during the entry phase. Carbon phenolic laminates retain their high strength at temperatures as high as 5000°F (ref. B1) and, therefore, thermal stress analysis, material thermomechanical property determination, and large-scale verification testing will be a required part of any program in which this type of ablative material is used. Elastomeric materials characteristically have a low modulus and strength so that thermal stresses are relatively insignificant. Elastomeric materials possess many other desirable features, including high insulation efficiency, minimum susceptibility to cold-soak failures, and simplicity of fabrication, inspection, and repair. The major detrimental characteristics of this class of materials, however, is a generally low resistance to aeromechanical forces, i.e., viscous shear stress and pressure gradient. Although shear forces are a consideration in any heat shield design and, in many cases, additional material must be provided to account for mechanical erosion, analytical prediction of mechanical erosion rates is uncertain, and extremely conservative design practices must be used. Because analysis indicates that mechanical erosion increases the thickness of ESA-5500 required by a factor of two over that required if shear is not considered, a series of material tests was initiated to demonstrate the feasibility of formulating an elastomeric material that would not erode mechanically at the moderate shear levels (<100 psf) predicted for entry from flyby and orbit.

The first step taken was to conduct a screening program in the Martin Marietta Corporation 1.5 MW plasma arc, in which 10 modified versions of ESA-5500 were tested and compared with the original formulation and with carbon phenolic. The models tested were $1\frac{1}{4}$ in. flat-ended cylinders. The two test conditions were as tabulated.

Test condition	Heating rate, Btu/ft ² -sec	Enthalpy, Btu/1b	Pressure,	Test time, sec
1	1140	7240	1.0	15
2	600	4000	1.0	15

The degree of improvement that can be anticipated is illustrated by comparing the recession rates of the basic ESA-5500 and ESA-5500 (M-10) in Table B2.

TABLE B2	ESA-550	O AND	ESA-5500 (M)	RECESSION	RATES
----------	---------	-------	------------	----	-----------	-------

Material	Test condition	T _w ,	r, ips	* <u>*</u> * * T
ESA-5500	1	4600	0.0204	1.73
ESA-5500 (M-10)	1	5020	0.0099	1.025
ESA-5500	2 '	4050	0.0132	1.02
ESA-5500 (M-10)	2	4200	0.00527	.59

a . *

ical mass loss rate assuming recession is controlled by diffusion limited combustion of the carbon in the char.

At test condition 1, the recession of (M-10) modification was approximately thermochemical, whereas ESA-5500 was eroded at a rate 70% greater due to pressure forces on the model face.

At this point in time, it appears that, of the group of existing materials, carbon phenolic would be the best material selection on the basis of the factors listed in table B1 and discussed above. The two major negative factors associated with the use of this material are weight and thermal stresses. Both the ESA-5500 and Avcoat 5026-HCG have good insulation characteristics but low char strength and low resistance to aeromechanical forces. The ESA-5500-type material possesses excellent thermostructural characteristics at both low and high temperatures. In view of the overall theoretical and experimental effort that will be required to obtain a high degree of confidence in any Venus heat shield design, it cannot be stated at this time that any of the state-ofthe-art materials is a clear cut choice. Thus, ESA-5500 and carbon phenolic have been selected for this study, because Martin Marietta has had the most experience with these materials and can, therefore, predict performance and sensitivity with the highest confidence level. ESA 5500M shows such promise that it has been included in the analysis of heat shield requirements for the various missions.

 $[\]frac{\dot{\tilde{m}}}{\dot{\tilde{m}}}$ is the ratio of the measured mass loss rate to the theoret-

Heat Shield Thickness and Weight Requirements

The thickness and weight per unit area of ablative material required is summarized in figure B2 as a function of initial entry angle and ballistic coefficient for entry velocities of 32 000, 38 000, and 44 000 fps. Because the structural substrate is aluminum, the maximum allowable ablator backface temperature was conservatively selected as 300°F.

In the design of the heat shield for the three missions, carbon phenolic and ESA-5500M are assumed to receed due to thermochemical reactions as described in reference B2. For ESA-5500, mechanical erosion is assumed to occur at the pyrolysis zone/char interface at a rate limited by the degradation kinetics of the plastic material (ref. B2). Thus, the difference in performance between the two versions of ESA-5500 is due to the mechanical erosion of the unreinforced material.

The ablation predicted for these materials is summarized in figure B3. ESA-5500 ablates a significant fraction of its original thickness, whereas for carbon phenolic and ESA-5500(M), the material loss is nominal. As shown in this figure, however, predicted surface temperatures are extreme for both of the materials for which erosion is not considered. The possible effects of these high temperatures is discussed later in terms of material resistance to aeromechanical forces.

Structure temperature histories for the design ablator thicknesses are shown in figure B4 for ESA-5500 (M) for the entry from approach trajectory and for carbon phenolic for the V/M flyby mission. The significant point to note from these curves is that there is no structure temperature rise predicted during the entry heating pulse. The entire temperature increase occurs as a result of the thermal soak while the probe is decelerating from Mach 2 (approximately the end of heating) to Mach 0.5, at which the aeroshell is jettisoned.

The aerothermal entry environment and the uncertainty factors applied to the theoretically determined heating components are given in table 93 of this report. Factored heating has been used to determine the design ablator requirements summarized above.

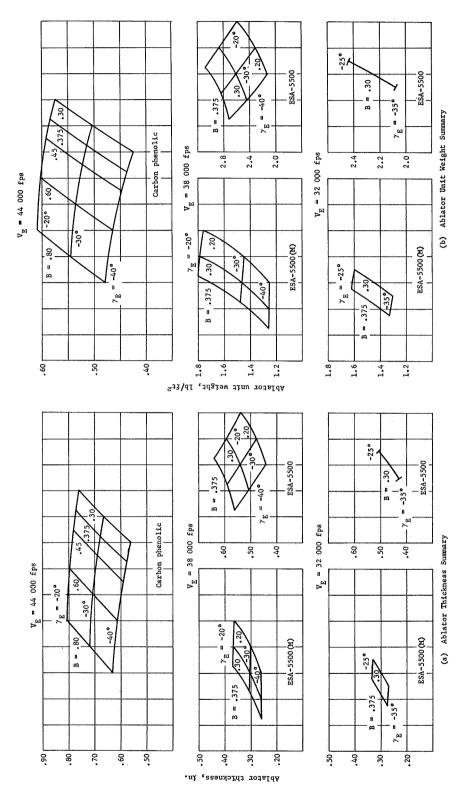


Figure B2.- BVS Heat Shield Requirement Summary

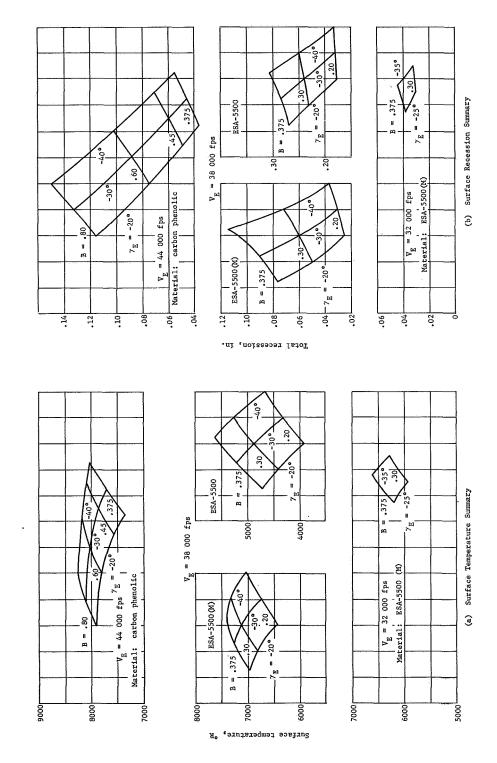


Figure B3.- Heat Shield Ablation Summary



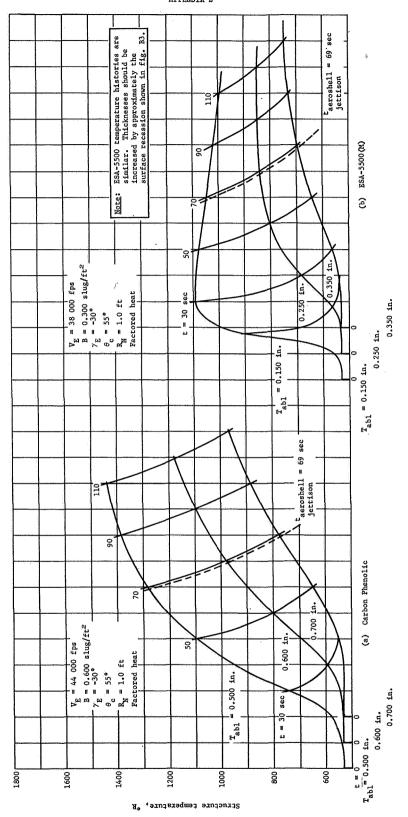


Figure B4.- Structure Temperature Histories

Heat Shield Sensitivity Studies

In view of the large uncertainties that are associated with the radiation heating rates and the extreme surface temperatures predicted for Venus entry, evaluation of the effects of unknowns in both the environment and ablation material performance is particularly pertinent to this type of study. Although the sensitivity studies conducted during the BVS study are by no means all-encompassing, they do deal with some of the more important unknowns. Specific problem areas examined were:

- 1) The sensitivity of heat shield thickness requirements to entry environment uncertainties has been examined;
- The sensitivity of carbon phenolic and ESA-5500(M) ablation have been evaluated in light of high-temperature strength data for graphite and carbon phenolic;
- 3) The effects of uncertainties in the thermodynamic properties of carbon vapor have been examined.

Thermal environment sensitivity.— The following cases were analyzed to determine the variation of the thickness of carbon phenolic required at the stagnation point as a function of variations in the factor applied to the nominal radiative heating rates. The study was made for the direct entry design case, $V_E = 38\ 000$ fps at $\gamma_E = 30\ ^\circ$:

	and and a graph of the state of	Radiation				
Case	F c convection	F _{NEQ} nonequilibrium	$_{ m EQ}^{ m F}$ EQ equilibrium and ${ m CO_4+}$	F _{UV} carbon continuum		
1	1.0	1.0	1.0	1.0		
2	1.0	3.0	1.5	3.0		
3	1.0	5.0	1.0	1.0		
4	1.5	1.0	1.0	1.0		
5	1.5	3.0	1.5	^a 3.0		
6	1.5	5.0	1.5	3.0		
7	1.5	3.0	1.5	1.5		
a _{n analise} decise switchis						

^aBaseline design criteria.

As can be seen from the results shown in figure B5, the sensitivity of thickness required is relatively insensitive to large uncertainties in the radiative heating of both items of the individual components and the total. For example, comparing the thickness required for the baseline criteria (case 5) with case 4, in which the nominal levels of all components were used, we see that decreasing the total radiant heat by 60% decreases the required thickness by only 7% from 0.624 to 0.585 in. The effect of increasing the nonequilibrium component by a factor of 5 (case 1 vs) case 3), which increases the total radiative load by 220% increases the thickness requirement by again only 7%. In addition to the low sensitivity of thickness required to radiant heat, the fact that the curve is smooth indicates an insensitivity to variation in the shape of the radiant pulse because the changes in factors significantly change the pulse shape.

Char strength sensitivity. - In all of the foregoing analyses, with the exception of the analysis of unmodified ESA-5500, it has been assumed that surface recession results from heterogeneous reaction between the boundary layer species and the char and sublimation of the char. However, the char formed by the degradation of a composite ablator, such as those considered in this study, is at best a porous form of graphite and, as such, cannot be expected to possess strength characteristics exceeding those of a good grade of graphite. The variation of ultimate tensile strength with temperature of POCO AXF-5Q graphite (fig. B6 from ref. B3) shows a sharp decrease in the temperature range from 5000 to 6500°F. The comparison between tensile properties of laminates of CCA-1 carbon and G-1550 graphite fabric impregnated with EC-201 phenolic resin and ATJ graphite in data presented in reference B1 at temperatures up to 5000°F indicates a similarity in mechanical properties. it would not be surprising if 6000°F represented a maximum temperature for carbonaceous composite ablators, beyond which their capability to resist aerodynamic forces was negligible.

Proceeding on the premise that 6000°F represents an upper limit surface temperature, analyses were conducted for carbon phenolic and ESA-5500(M), in which the surface temperature was not allowed to exceed this value and the maximum char thickness was limited to 0.01 in. during the period when the temperature is so limited. This allowable char thickness is based on the results of tests conducted in the high shear environment of the CAL wave superheater. Thus, it is assumed that for temperatures greater than 6000°F, the char strength is essentially zero, and even small shearing forces result in mechanical erosion of the surface.

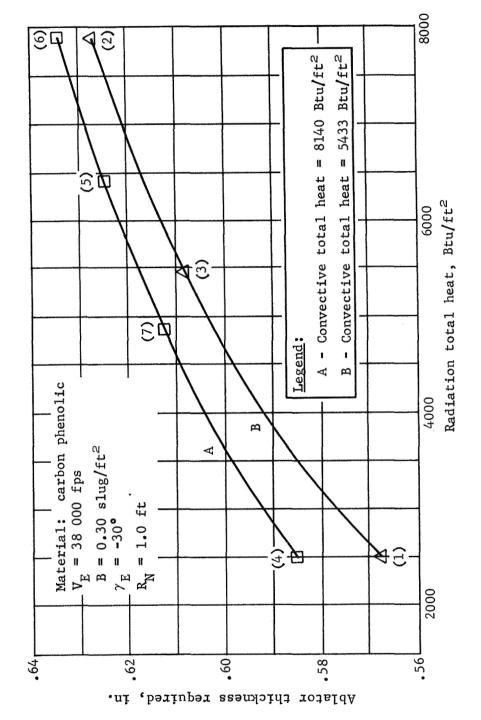


Figure B5.- Stagnation Point Ablator Sensitivity to Radiation Heating

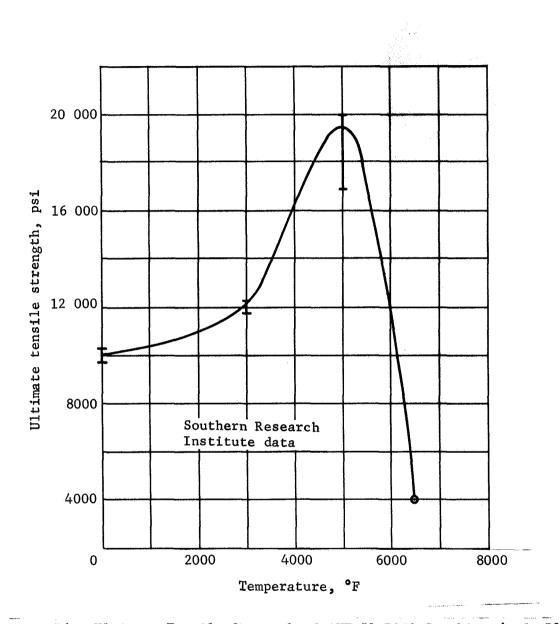


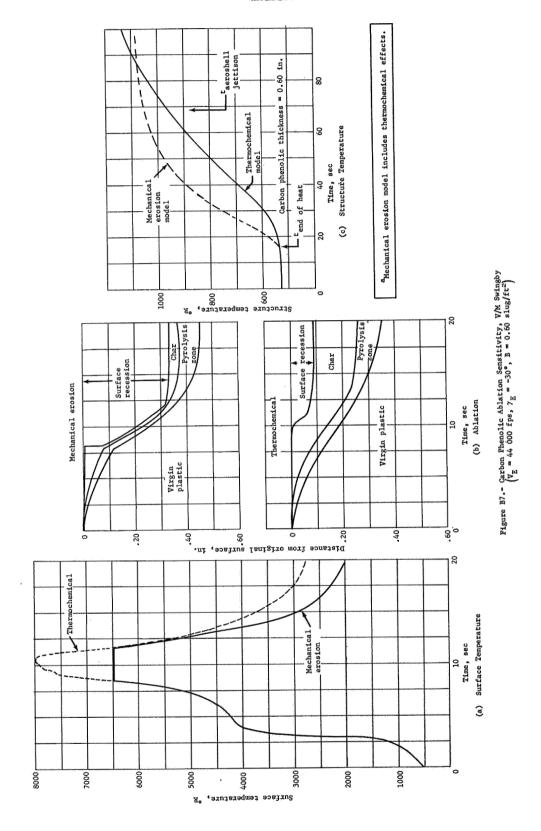
Figure B6.- Ultimate Tensile Strength of AXF-5Q POCO Graphite (ref. B3)

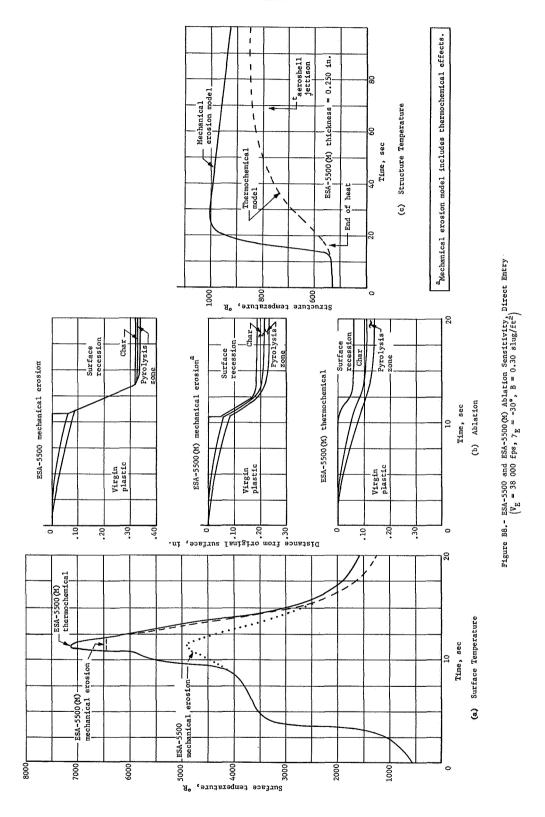
The nominal ablation of carbon phenolic compared to the above shear model is shown in figure B7 for the V/M flyby design trajectory. The surface temperature reaches 6000°F at approximately 9 sec. At this time, the char that has been built up is assumed to spall. The surface erosion rate subsequent to this time is controlled by the rate at which heat can be absorbed by the material and rapid recession takes place. At 12 sec, the surface temperature drops below 6000°F because the surface heat flux is decreasing and normal char growth once again takes place. For this case, the mechanical erosion results in a backface temperature increase 90°R above the design value in spite of the fact that the surface recession is increased from 0.085 to 0.34 in. This result is due to the fact that the heat that is stored in the carbon phenolic is reduced by mechanical erosion.

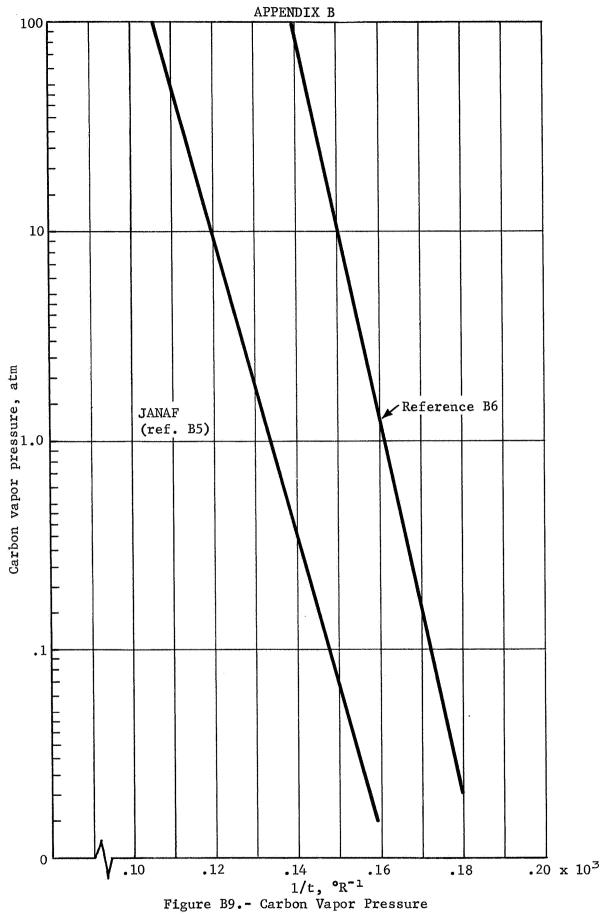
The ablation resulting from the loss of char strength on ESA-5500 (M) material is compared to the thermomechanical ablation and the ablation of ESA-5500 in figure B8 the direct entry mission. For the ESA-5500 (M) material, the loss of char strength at 6000 °R will result in an increase in surface recession from 0.058 in., resulting from chemical erosion to 0.187 in. The structure temperature rise is 140 °R greater when mechanical erosion is considered. This in itself is not catastrophic; however, the fact that the remaining thickness is only 0.063 in. and the rapid structure temperature rise indicates that additional thickness will be required to provide a reliable design. Even with the additional thickness requirement, however, the lower density ESA-5500 material will still retain a definite weight advantage over the carbon phenolic for the direct and orbital entries.

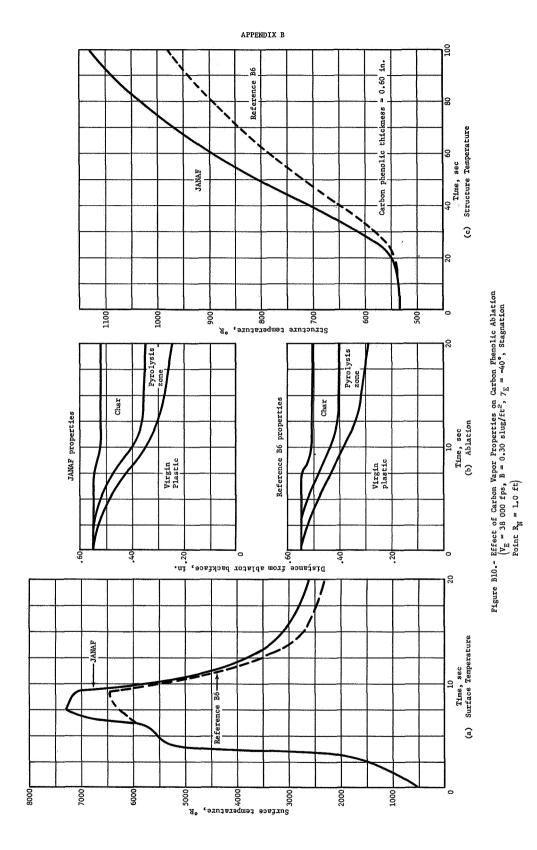
Carbon vapor property sensitivity. The thermodynamic performance of graphitic materials has been the subject of considerable controversy for sometime. Various estimates of the heats of formation of the carbon vapor species evolved at high temperatures have been put forward. An excellent summary of these is presented in reference B4. To evaluate the effect of this uncertainty, analyses were conducted using the two different carbon-vapor pressure curves (fig. B9) that represent the two extremes presented in reference B4. The JANAF data have been used in the design analysis for this study.

The results of analysis conducted for the direct BVS mission are shown in figure B10 (refs. B5 and B6). These data show that although relatively large differences in surface temperature and surface recession result from using the different carbon-vapor properties, the structure temperature is only slightly affected. The properties used in the design analyses (JANAF) are conservative.









HEAT SHIELD DEVELOPMENT REQUIREMENTS

Entry Simulation Testing

Regardless of the material used for the heat shield, even though it is one with extensive flight and ground test experience, a substantial number of development tests will have to be conducted because:

- 1) The formulation and fabrication processes will be different for this application because of the large diameter shallow cone configuration and the requirements for sterilization at high temperatures (the latter affects cure cycles and fabrication sequence of events). Consequently existing performance data may not be valid:
- 2) The Venus entry environment features several unique characteristics as discussed previously, i.e.,
 - a) Very high levels of radiation heating in addition to convective heating,
 - b) High-intensity ultraviolet radiation,
 - c) A high percentage of CO2 in the atmosphere,
 - d) High surface shear forces in conjunction with very high surface temperatures occur over large areas of the surface.

Also, in the case of rigid materials such as carbon phenolic, a potential problem exists relative to thermal and load induced stresses because of the large diameter relatively thin shell configuration of the heat shield.

Relative to the degree of simulation required in ground tests, it should be pointed out that in no major heat shield design has a complete simulation of the flight environment been possible. In fact, seldom has it been possible to produce the combination of peak levels simultaneously on even a small sample of the material, although this is always the goal. Consequently, the major objective of entry simulation test is to confirm or to establish an analytical model that is then used in design. If the model is heavily dependent on empirical correlations, it is necessary to constrain the design to the range of test conditions, or to use large margins. If the analytical model is a fairly fundamental expression, designs beyond the range of the test data are practical, but more extensive testing is required and design confidence is necessarily lessened.

Simulation Requirements for Venus Entry

Surface shear forces should be simulated through the full range of values anticipated in flight, which means cold wall values of 30, 70, and 120 psf for the 32 000, 38 000, and 44 000 fps entry velocities, respectively. These shear forces must be induced in conjunction with a heat flux capable of producing the peak entry surface temperatures calculated in the absence of mass loss by erosion, 6000, 7000, and 8000°R, respectively. Pressure levels should approach 1 atm or greater. These conditions can be achieved in existing plasma arc and laser-plus-cold flow facilities using pipe flow and/or shear wedge models. Shears should also be imposed on models at intermediate surface temperatures and, in these, it will be important to employ CO2/N2 as the test fluid because oxidation and other chemical processes will be the predominant contenders with the shear forces for the surface carbon instead of the sublimation process. This type of test can also be performed in existing plasma arc facilities.

Another critical parameter is combined radiant and convective heating. Here, however, it is believed that achievement of peak combined flux values, though highly desirable, is not mandatory. Test points should achieve at least two things: (1) radiant levels sufficient to generate ablative gas mass injection rates that reach or approach the cutoff point in the mass injection vs convective heat blocked relation, and (2) they should produce surface temperatures up through the chemical reaction and well into the sublimation regime with appropriate pressure levels. Assigning specific values of $\dot{\textbf{q}}_{c}$ and $\dot{\textbf{q}}_{R}$ to achieve these criteria is difficult because they will vary with the material being tested. However, the $\dot{q}_{\rm p}$ of 4000 Btu/ft²sec and $\dot{q}_{\rm p}$ of 1750 Btu/ft²sec planned for the Ames advanced facility should satisfy the minimum criteria stated above even for the 44 000-fps entry with the materials of interest. The peak conditions for the 38 000-fps entry $(\dot{q}_c = 1600 \text{ Btu/ft}^2 \text{sec})$ and $\dot{q}_p = 1700 \text{ Btu/ft}^2 \text{sec}$) are seen to fall within the ranges of the Ames facility.

A third aspect of the entry environment, the concentration of more than one-half the shock layer radiant energy in the ultraviolet wavelength region, is also of concern. Because the high energy photons of the vacuum ultraviolet region have an undesirable effect on plastic materials even at moderate flux levels, the question of whether a very high flux level will produce an unusual response in the carbonaceous chars of the ablative heat shield materials should be given some attention. No facilities exist or are

planned that produce high ultraviolet flux levéls; hence, it appears that an attempt should be made to evaluate this phenomenon on a laboratory scale and then decide whether a materials test facility is required, or whether, in fact, the energy can be treated as being absorbed at the surface and converted to heat as is presently assumed. The final aspect of ground test simulation is that of large-scale verification tests. The case of a 3/4-in. thick, 8.5-ft diameter shell constructed of a dense, high-modulus heat shield material bonded and/or mechanically attached to a thin, shallow-cone metal structure presents an entirely different situation relative to thermal/structural interaction than any heat shield design concept previously considered. With this arrangement, which is the most likely for a 44 000-fps entry, the conduction of a large-scale overall thermal/structural integrity test becomes almost a necessity. Even with less dense and less rigid materials, a demonstration of the absence of warping or bond failure should be considered.

The question is, "To what percentage of peak flight temperatures should such a test be conducted to properly represent a verification test?" The answer lies with the evaluation of thermal gradients or temperature distributions, primarily those through the thickness but also those along the cone's length. It may be that existing quartz lamp facilities can be used for the test even though temperature peaks of only the order of 4000°R could be attained, compared with 8000°R predicted for flight. Other possibilities would be the development of a higher-surface-temperature-producing facility involving resistance heated graphite rods or a graphite shell, the use of large-diameter nozzle plasma arc facilities and, less likely, the use of rocket engine exhaust facilities. Another possibility, not yet adequately evaluated, is that of conducting earth entry flight tests.

Conclusions

Heat shield design analyses have been conducted to determine the amount of ablative material required to protect the BVS/entry vehicle structure, equipment, and scientific payload from the entry thermal environment. The results of this study have shown that it is feasible to provide such protection with ablative materials that are now considered operational. Since the Venus entry thermal environment and the predicted response of ablative materials exceeds in severity the range of experience gained in Earth reentry flight and ground tests, it has been necessary to extrapolate beyond existing data. Examination of sensitivity to unknown factors, indicates, however, that the resulting designs are conservative.

Another conclusion, relative to the influence of test facility limitations on mission selection, is that at this stage none of the missions studies should be ruled out for reasons of less than total simulation capability although an awareness of the increased development costs and the somewhat greater design risk of the high velocity entries (44 000 fps) should be accounted for in mission trade studies.

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SPACECRAFT MODIFICATIONS

by Ronald E. Frank and Jack Pettus Martin Marietta Corporation

LUNAR ORBITER

The modified Lunar Orbiter as defined in NASA CR-66302, Study of Applicability of Lunar Orbiter Subsystems to Planetary Orbiters, was specified as the spacecraft for the orbital mission. (The report describes modifications of the Lunar Orbiter for the Mars and Venus missions.) Both versions include -- in addition to the basic spacecraft -- an entry probe system of 115 1b.

No major problems of compatibility between the Lunar Orbiter and the BVS have been identified. However, the assessment was performed only to the detail that could be supported by the referenced report and should be considered as a general survey only.

Of greatest concern was the weight that must be put into orbit, consisting of both the spacecraft and the capsule system. This resulted in a highly eccentric orbit ($\epsilon = 0.8$) for the mission. No attempt was made to assess the reasonableness of the Boeing weights; however, it should be noted that a stated guideline of their orbiter study was to use existing proven systems, and no emphasis was placed on reducing weight.

The required modifications to the Lunar Orbiter are summarized in table ${\tt Cl}$.

Figure Cl shows the orbiter spacecraft with the BVS capsule attached. The major modifications indicated are the larger orbit insertion propulsion module, a scan platform and relay antenna. In addition, the solar panels are shown extended to prevent shading by the 8.5 ft entry vehicle.

The baseline orbiter weights as specified in NASA CR-66302 are restated in table C2. The total orbiting weight of this table (925 lb) is reduced by 149 lb (velocity control) and 115 lb (probe) to arrive at a value of 661 lb "useful weight in orbit" for this mission.

Further modifications required for compatibility with the BVS mission are summarized in table C3. The incremental weight change identified was considered to be small enough to be neglected within the scope of this investigation. On this basis, the all up weight (weight on launch vehicle) becomes:

BVS/EV system	1126 1ь
Spacecraft	661
Spacecraft propulsion system (burnout)	298
Midcourse and orbit insertion propellant	1339
Spacecraft-to-booster adapter	<u> 174</u>
All up weight	3498 1b

TABLE C1.- SPACECRAFT MODIFICATIONS

Modification	Purpose	Justification
Structural modification to support capsule	To provide strength to support capsule	Additional mass due to capsule
Modify S/C attitude con- trol system	Planetary vehicle sta- bilization during cruise and orbit and origina- tion for capsule sepa- ration	Increase of mass to be stabilized/oriented
Add separation system for capsule	To separate capsule	Several discretes required to power up and separate capsule
Modification of S/C ther- mal control	Control of S/C tempera- ture	Presence of capsule will modify heat balance
Modification of solar pan- els	Provide view of sun	Presence of capsule will shade present panels
Modification of power system	Provide power to capsule and added S/C systems	See capsule power requirement and other S/C modifications
Add receiver	Receive BVS/entry vehi- cle telemetry data	Orbiter must provide re- lay link to Earth
Add bit synchronizer	Bit by bit synchroniza- tion of BVS data stream before entry into tape memory	See communications section above
Add command transmitter	To transmit commands to the BVS	Several commands are required to perform the BVS mission
Add command tone generator	To key the command trans- mitter	Allows commands to be generated
Add rf multiplexer	Provide common connection to the antenna for the two receivers	To allow for single antenna
Add tape recorder	Provide storage for BVS/ EV data	Approximately one million bits of data must be stored during entry and deployment of BVS
Add relay antenna	Provide TM link for BVS/	Relay link is required
Add new propulsion module	To effectively eliminate gravitational losses during orbit insertion burn (T/W > 0.2)	
Add scan platform	Provide planet coverage for S/C science	
Add sequencer discretes	Provide signals for BVS/ EV preseparation and sep- aration	

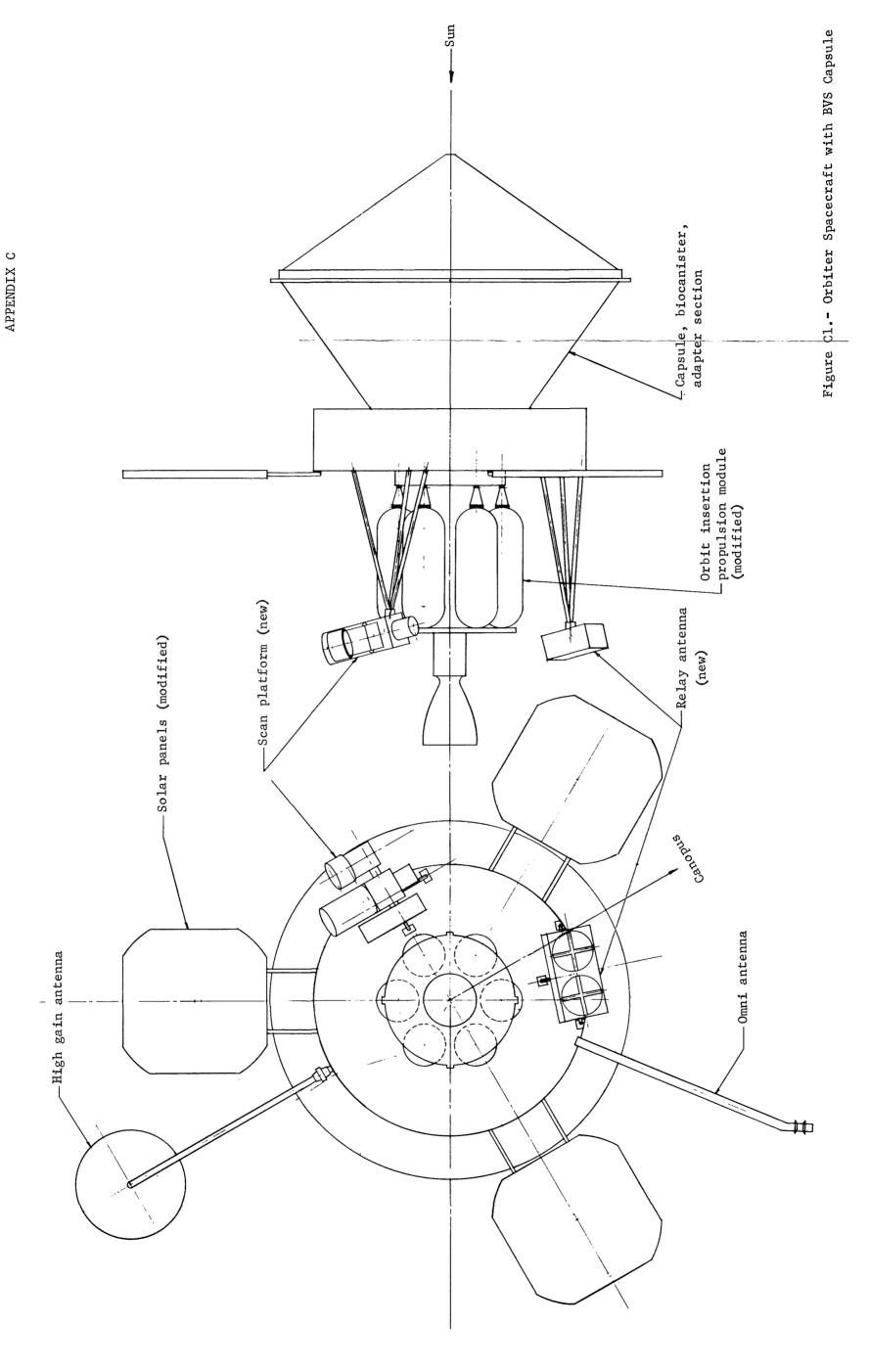


TABLE C2.- SUMMARY WEIGHT STATEMENT

	Weigh	t, 1b
	Venus	Orbiter
Science payload		
Science	109.0	
Probe (fixed plus separated weight)	^b 115.0	
Subsystems		304.0
Power	138.0	
Telecommunications	72.0	
Programer CC&S	32.0	
Attitude control	62.0	
Velocity control (included N ₂ gas and fuel reserves)	^b 149.0	
Structures and mechanisms		170.0
Assembly and integration		78.0
Total (useful) orbiting weight		925.0
Propulsion and gas		995.0
Attitude control gas	15.0	
Fuel	377.0	
Oxidizer	603.0	
Total spacecraft weight		1920.0

a Taken from Boeing Report NASA CR-66302, pp. 4-248, Table 4.6.7.7.

^b Deleted for BVS study.

TABLE C3 .- SPACECRAFT MODIFICATIONS AFFECTING WEIGHT

Item	Weight increment, 1b
Structure	Could not be estimated
Telecommunications	
Receiver	+3.0
Bit synchronizer	+1.0
Command transmitter	+4.0
Command tone generator	+2.0
RF multiplexer	+.6
Tape recorder	+12.0
Relay antenna	Replaces Boeing added antenna
Power	Minor cabling addition not esti- mated; sufficient power available
Assembly and integration	
Cabling	Could not be estimated
Science	<u>-11.0</u>
Net weight change	+12

With this payload on a Titan IIIC, which has a total capability of 3850 1b for this mission, the margin is 352 1b.

The orbit-insertion maneuver is a critical factor, especially for the mode of carrying the total planetary vehicle into orbit. Using a 100 $1b_f$ thrust engine, as proposed by Boeing (thrust/initial weight = 0.03), the gravitational losses amount to 26%, approximately 333 1b of propellant.

To reduce the gravitational losses to a negligible amount the propulsion module has been revised to incorporate the Apollo subscale engine with a thrust level of 2200 lb. Assuming no losses, the curve of figure C2 indicates the orbit eccentricity that can be achieved as a function of BVS/entry vehicle system weight.

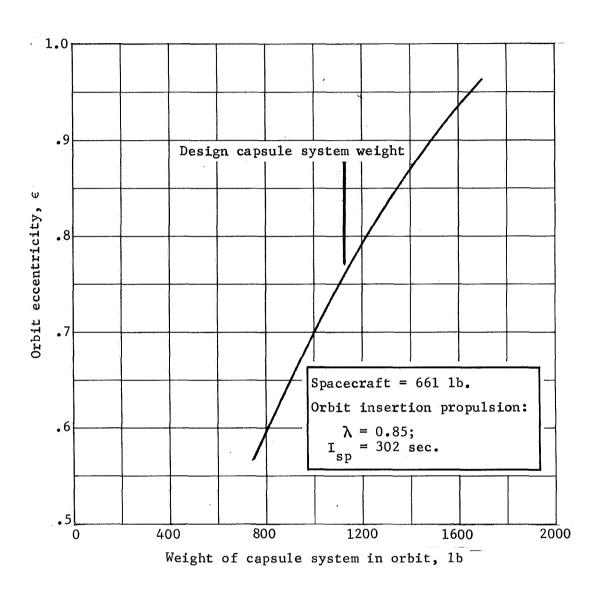


Figure C2.- Performance Capacility, Capsule System Weight in Orbit vs Orbit Eccentricity

System Compatibility

<u>Telecommunications</u>.- The major telecommunications support functions that the spacecraft must provide for the subsonic probe and BVS are shown in table C4.

Figure C3, reproduced from the referenced Boeing report, shows the baseline Lunar Orbiter telecommunications systems. (The S-band link to Earth appears to provide the needed bit rates.) The lower portion of this diagram shows a probe antenna, probe receiver, and tape recorder as well as TV and other science (all of which was classified as science in that report). Figure C4 is an expansion of the science equipment block of the Boeing diagram (lower portion of fig. C3) to which additional equipment required to support a subsonic probe and a BVS has been added. The balance of the science block (TV, etc.) is shown unchanged.

Additional equipment required includes a medium-gain antenna, an rf multiplexer, a bit synchronizer, a BVS data receiver, a command transmitter, command tone generator, and a second tape recorder. (It is assumed that characteristics of the probe receiver and antenna shown in the Boeing block diagram -- although not specified -- are such that they would be equivalent in cost to a vhf superheterodyne FSK receiver and vhf antenna meeting the requirements for this mission.)

The equipment required to receive BVS and subsonic probe data is briefly described below.

Receiver: A 390-MHz FSK receiver (identical to the BVS command receiver except for crystal frequency) is required to receive BVS telemetry data. A 400-MHz receiver for subsonic probe data is assumed as existing equipment.

Bit synchronizer: An additional bit synchronizer is required to perform bit-by-bit synchronization of the BVS data stream before entry of data into tape memory. It is assumed that a bit synchronizer for the subsonic probe data is existing equipment in the spacecraft.

Command transmitter: The command transmitter is a solid-state unit to be frequency shift keyed by command tones from the command tone generator. Keying rates between 500 and 2000 Hz are assumed.

Command tone generator: A command tone generator is required to key the command transmitter using a three-tone sequence for each of six commands. An alert tone and three command tone frequencies are required. The tone sequence and command sequences are controlled by the spacecraft programer and sequencer in response to Earth-to-spacecraft commands that are stored in the spacecraft.

TABLE C4.- BVS AND SUBSONIC PROBE FUNCTIONS TO BE SUPPORTED BY ORBITER SPACECRAFT

Support functions	Requirements	Comments on spacecraft equipment modifications and/or additions
Capsule status monitor functions (preseparation)	Control capsule aeroshell multi- plexer and receive hardline telem- etry data during cruise mode	Provide required sequencing control, routing and conditioning of aeroshell multiplexer data to S/C engineering multiplexer
Receive entry vehicle data including subsonic probe and BVS deploy data follow- ing separation from aero- shell	Receive telemetry data over BVS to S/C link during separation of capsule from S/C and during △V burn Receive telemetry data from BVS to S/C link during capsule entry to BVS separation from aeroshell	Minimum equipment complement to do this: 1) Medium gain antenna array; 2) RF multiplexer; 3) FSK receiver (2 each); 4) Bit synchronizer (2 each).
	Receive telemetry simultaneously from BVS and from subsonic probe after separation of these from aeroshell	
	Telemetry link modulation and bit rate to be 240 bps FSK both links	
Receive BVS data during orbital operations	Receive telemetry data from BVS once per orbit	Use same receiver and antenna as above
	Provide margin for a maximum range of 18 000 km	
	BVS transmitter is frequency shift keyed at 240 bps rate	
Beacon and command signals to control transmissions from BVS	Provide a beacon signal to alert BVS to begin transmission when S/C comes within range of BVS	Minimum equipment complement: 1) One frequency shift key modulated transmitter;
	Provide tone command modulation to command operating mode of BVS	2) Tone command generator.
	Provide range of at least 18 000 km for command link	Above equipment must be added to S/C; command storage must be provided in S/C programer and sequencer
	Transmit carrier unmodulated (after commands are sent) to provide sig- nal for doppler measurement by BVS	
	Provide capacity for 6 discrete commands	
	Store command sequence in S/C; sequence to be received from Earth station	
Storing and retransmission of data received from subsonic probe and BVS	Provide storage for 1 million bits BVS data and 500 000 bits subsonic probe data to be received simul- taneously	Additional equipment required - tape recorder and control Modifications - provide gating and control of data to NRT buffer of S/C
	Once per orbit provide storage for 150 000 bits of data received from the BVS during a period of approximately 10 minutes	programer/encoder
	Transmit data to Earth at least once per orbit	
Programing of spacecraft power and data transfer to accomplish the functions shown above	The turning on and off of power to receivers, recorder, transmitter, and other S/C equipment used to support the capsule and BVS must be accomplished as well as the control of data flow during receiving and retransmission of the data	The S/C programer/computer and sequencer must be programed to accomplish these functions

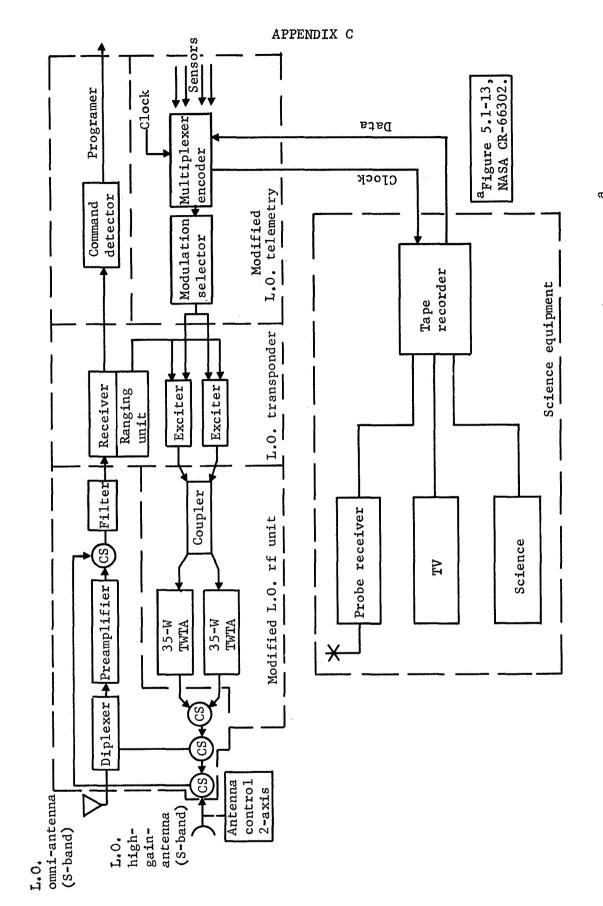
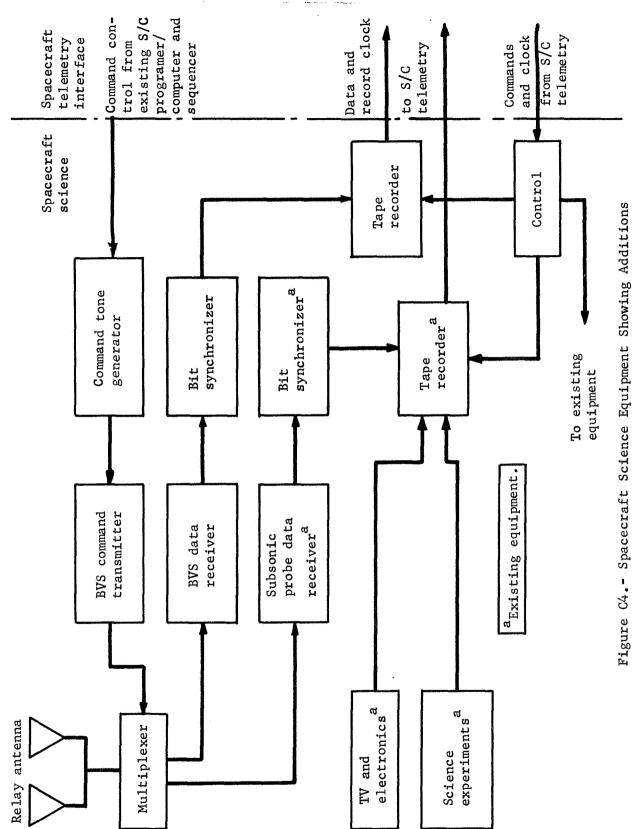


Figure C3.- Unmodified Telecommunication System, Mars/Venus Orbiter



RF multiplexer: The rf multiplexer isolates the two receivers and transmitter and provides a common connection to the antenna for each of the units.

Tape recorder: A tape recorder for storage and playback of BVS data has been tentatively identified as additional equipment. This recorder can store BVS data during capsule entry and BVS deployment at the same time the existing recorder is storing subsonic probe data. The additional recorder will also allow the storing of TV data at the same time BVS data are being received during orbital operations.

The additional recorder should have a capacity of approximately 1 million bits and must run at playback speeds compatible with the S-band telemetry rates of 200, 400, 800, and 1600 bps (speed will depend on number of real-time words interlaced with the stored data).

Relay antenna: The relay antenna is a dual-element crossedslot, cavity-backed antenna having an elliptical pattern. Each element is nearly identical to that of the BVS antenna that has been described earlier.

The modification and use of the remaining spacecraft equipment is assumed feasible, although detail information was not available.

<u>Guidance</u>, <u>control</u>, <u>and navigation</u>. The capsule does not have the capability for maneuvering. Therefore, it is required that the spacecraft maneuver to the required deorbit attitude before capsule separation. To minimize tipoff rates at capsule separation, it is required that the limit cycle rate be limited to 0.1°/sec.

During the preseparation phase, command update information on deorbit engine burntime will be transmitted from Earth. This information is to be loaded into the aeroshell sequencer burntime update register. In addition, the coast timer initiate and separation sequence initiate commands will be transmitted from Earth. The spacecraft must convert these to discrete signals that will then initiate the aeroshell sequencer functions.

It is assumed that the lunar orbiter system could be modified to perform these functions.

<u>Spacecraft science</u>.- A proposed orbiter science payload is shown in table C5. This payload does not equal the baseline weight allowance; however, it was not feasible to assess the weight significance of the scan platform in this study.

TABLE C5 ORBITER SPACECRAFT EXPERIMENT CHARACTERISTICS	Development status	Mariner '69 Instrument	Similar to Mariner '69 Instrument	Similar to Mariner '69 Instrument	Similar to Mariner '69 Instrument	Similar to Mariner '67	Similar to OGO-E	
	Deployment, mounting	On scan platform	On scan platform	On scan platform	Antennas on end of solar panels	On most of omni antennas	Facing sun (end of solar panel)	
	Data (encounter)	3200 bps	1330 bps 600 bits/63 sec (9.5 bps)	2.5 x 10 ⁵ bits per picture 10 ⁷ -bit storage	100 bps	30 bps	50 bps	
.5 ORBI	Power, watts	12.0	4.5 3.0 (20)	20.0	0.4	5.0	10.0	63.5
TABLE (Weight, 1b	30.0	17.5 7.5 (35)	15.0	0.8	5.0	15.0	98 (109)
	Experiment	UV spectrometer	IR spectrometer IR radiometer	TV (3-color)	Three-frequency occultation (receivers and antennas)	Magnetometer	Plasma probe	Totals Allocations

<u>Power subsystem.</u>- The baseline Lunar Orbiter solar array (four panels) can supply adequate power for the BVS mission.

Table 5.2-3 of NASA CR-66302 lists the items making up the load demand upon the power subsystem of the Lunar Orbiter. These data form the basis of the report's figure 5.2-3, which has been replotted in figure C5 with the additional loads added for use with the BVS (cross-hatched). Modifications required for use with the BVS include addition of the following equipment:

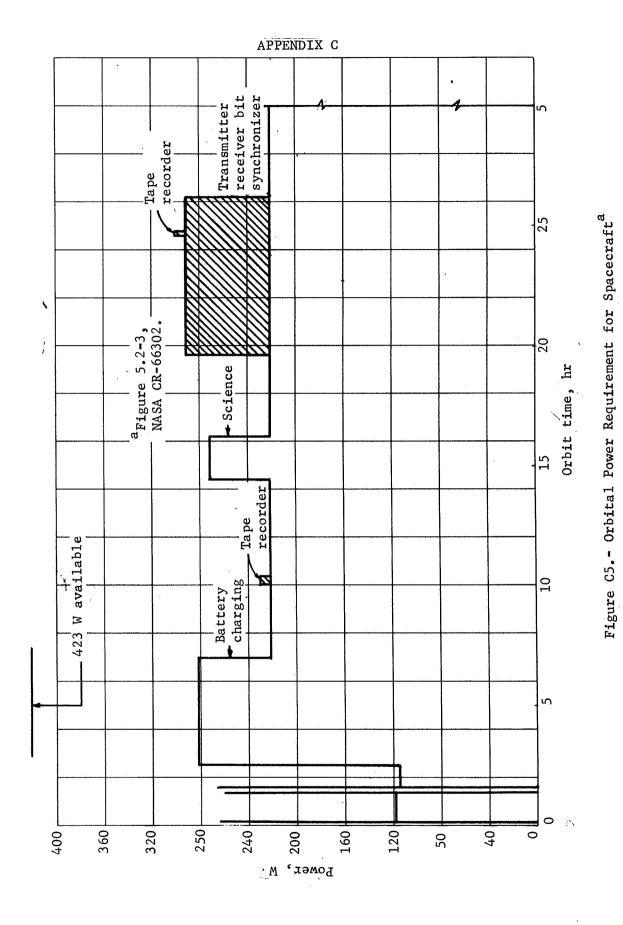
	<u>Load, W</u>
VHF transmitter	67
VHF receiver	1.5
Bit synchronizer	1
Tape recorder	8

The first three items are in operation from 5 hr before operation of the BVS transmitter to $1\frac{1}{2}$ hr afterward. The tape recorder is in operation when data are being received from the BVS (10 min) and for 20 minutes when the orbiter retransmits these data to Earth.

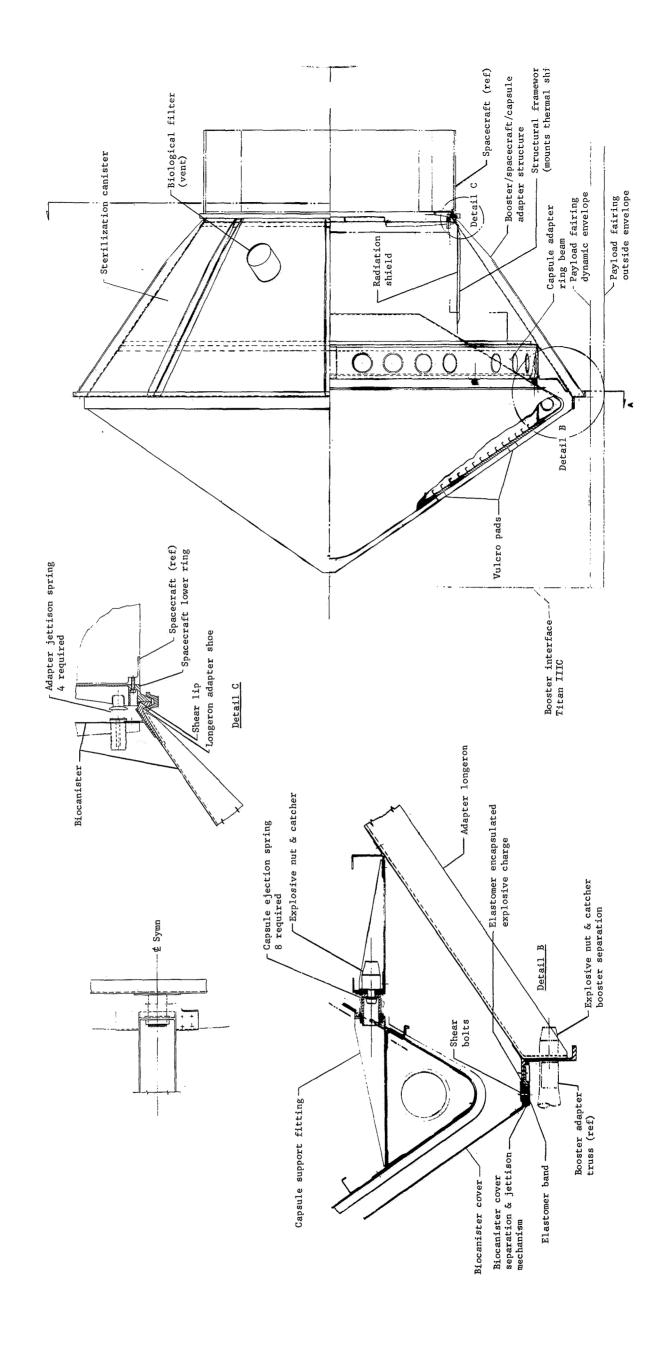
The modifications cause the maximum demand on the orbiter power subsystem to be increased from 281.2 to 297.8 W. This will have a negligible effect on the power subsystems.

Mechanical interface. Figure C6 shows the 8.5-ft diameter entry vehicle mounted in the biocanister capsule adapter ring beam attached at eight places. Each of the eight attach points contain a spring to supply separation velocity when the entry vehicle separates from the spacecraft. The aft section of the biocanister is attached to the orbiting spacecraft by V-band clamps. The large diameter ring of the aft biocanister mounts the total system to the Titan III transtage payload ring frame. The forward section of the biocanister is separated pyrotechnically to allow deployment of the entry vehicle.

<u>Electrical interface</u>.- The electrical interface is shown in figure C7. The functions represented include a trickle charge during the cruise mode to the battery chargers mounted in the capsule adapter; status monitor of the BVS subsonic probe and aeroshell mounted equipment and command function as required.



67



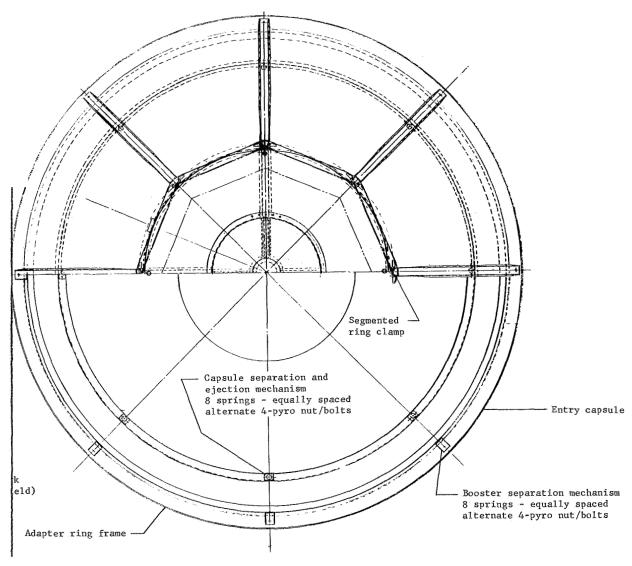


Figure C6.- BVS/Entry Vehicle 69 and 70

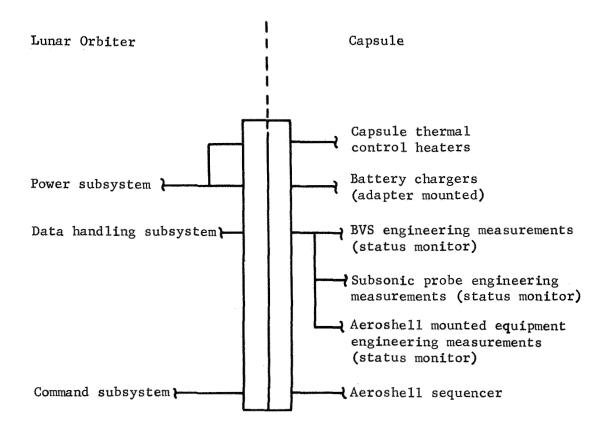


Figure C7.- Lunar Orbiter/Capsule Electrical Interface

MARINER '69

The Mariner spacecraft as defined in the Mariner Mars 1969 Functional Requirements Document, with revisions, was specified as the spacecraft for the flyby mission.

No major problems of compatibility between the Mariner '69 and the BVS have been identified. Modifications are required and are identified to support the addition of the BVS/Entry Vehicle during transit, provide status monitor of the BVS, subsonic probe, and aeroshell-mounted equipment, and provide a relay link to Earth for the BVS and subsonic probe during coast, atmospheric entry, and deployment.

The required modifications to the Mariner are summarized in table C6.

Design

Figure C8 shows the integration of the Mariner '69 spacecraft and the BVS/Entry Vehicle in its biocanister. Modifications to the Mariner '69 spacecraft are based on the requirements of a Venus flyby mission and the deployment of an entry vehicle containing the BVS. Because of the sun/Earth/Venus relationship during cruise and encounter, and the fact that the spacecraft must have a communications link with the entry vehicle up to the time of balloon deployment, several modifications to the spacecraft will be necessary. They are as follows:

- The solar panels must be inverted to receive the sun from the capsule side. They must also be lengthened to prevent shading by the capsule;
- The scan platform will be relocated to the opposite side of the octagonal structure, and modified as required to accept the spacecraft science complement;
- 3) The high-gain antenna will be relocated to the new cone and clock angles;
- 4) Two receiving communication systems must be mounted on the spacecraft, one for BVS entry and deployment data, and one for subsonic probe data. A relay antenna plus an additional data storage unit must also be located on the spacecraft;

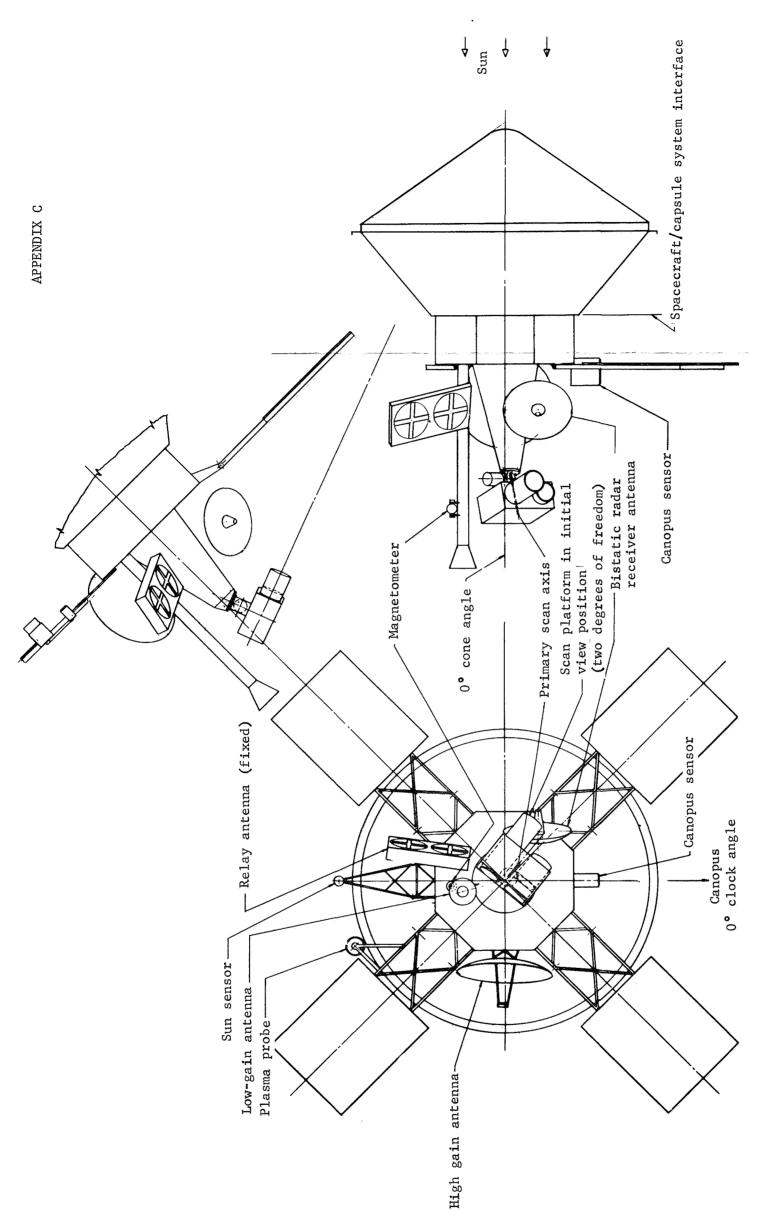


Figure C8.- Flyby Spacecraft Configuration with BVS Capsule

TABLE C6.- SPACECRAFT MODIFICATIONS

Modification	Purpose	Justification
Structural modification to attach capsule	To provide interface for cap- sule adapter	
Modification of S/C thermal control	Control of S/C temperature	Presence of capsule will modify heat balance
Modification of solar pan- els	Provide view of sun	Presence of capsule will shade panels; also panels must be rotated 180° to view sun
Modification of power sys- tem	Provide power to capsule and added S/C systems	See capsule power requirement and other S/C mods
Add receiver (2 each)	Receive BVS/EV telemetry data	S/C must provide relay link to Earth
Add bit synchronizer (2 each)	Bit by bit synchronization of BVS data stream before entry into tape memory	See communications section
Add rf multiplexer	Provide common connection to the antenna for the two re- ceivers	To allow for single an- tenna
Add tape recorder	Provide storage for BVS/EV data	Approximately one million bits of data must be stored during entry and deployment of BVS
Add relay antenna	Provide TM link for BVS/EV	Relay link is required
Relocate scan platform	Provide planet coverage for S/C science and allow for capsule attachment to S/C	Scan platform mounting on same side as capsule
Add sequencer discretes	Provide signals for BVS/EV preseparation and separation plus receipt of BVS telemetry	
Reorient high-gain antenna	Provide proper orientation to Earth	Cone and clock angles dif- ferent from Mars mission
Reorient midcourse propul- sion engine	Provide proper midcourse ma- neuver	Engine must provide thrust through planetary vehicle center of gravity
Add bistatic radar antenna	View planet at subearth point during encounter	Required to perform bistatic experiment
Add plasma probe	View sun	Required for plasma experiment
Remove approach guidance subsystem	Experiment for Mars	Not required for Venus mission

- 5) The Mariner '69 midcourse propulsion engine will be realigned to act through the new center of gravity;
- 6) A bistatic radar antenna will be added to view the planet at the sub-Earth point during the encounter approach;
- 7) A plasma probe is added to view the sun past the probe canister. It is supported off the solar panel structure and deployed with it;
- 8) A mechanical/electrical interface with the capsule adapter will be required;
- 9) The approach guidance system will not be carried.

The Mariner spacecraft with the modifications made as summarized in table C6 will adequately perform the reference flyby mission.

System Compatibility

<u>Telecommunications</u>.- Spacecraft telecommunications support functions required of the Mariner Mars 1969 spacecraft system to support the 1972 Venus flyby mission are identified in table C7.

Additional equipment required are a relay antenna, rf multiplexer, two receivers (one each for the BVS and subsonic probe), two bit synchronizers, and a digital tape recorder. The spacecraft support equipment is shown in the simplified block diagram of figure C9. The weight and power summary is shown in table C8.

A brief description of the spacecraft equipment required to support the BVS and subsonic probe is provided below.

Relay antenna: The relay antenna is a dual-element cavity-backed crossed-slot having an elliptical pattern. Each element is nearly identical to that of the BVS and subsonic probe antennas described earlier. A gain pattern for the spacecraft relay antenna is shown in the BVS Radio Subsystem Performance section.

RF multiplexer: The rf multiplexer isolates the two receivers and provides a common connection to the spacecraft relay antenna.

TABLE C7.- BVS AND SUBSONIC PROBE FUNCTIONS TO BE SUPPORTED BY MARINER SPACECRAFT

Support function	Requirements	Comments
Capsule status monitor functions (preseparation)	Control capsule aeroshell multiplexer and receive hard-line telemetry data during cruise mode	Provide required sequencing control, routing, and conditioning of aeroshell multiplexer data to S/C engineering multiplexer
Receive entry vehicle data including subsonic probe and BVS deploy data following separation from the aeroshell (until station is completely deployed and subsonic probe has impacted on the planet)	Receive telemetry data over BVS to S/C link during separation of capsule from S/C and during $\triangle V$ burn Receive telemetry data from BVS to S/C link during capsule entry to BVS separation from aeroshell	Minimum equipment complement to do this: 1) Medium gain antenna ar- ray; 2) RF multiplexer; 3) FSK receiver (2 each);
	Receive telemetry simultane- ously from BVS and from sub- sonic probe after separation of these from the aeroshell Telemetry link modulation and bit rate to be 240 bps FSK both links	4) Bit synchronizer (2 each).
Storage and retransmission of data received from sub- sonic probe and BVS	Provide storage for 0.86 mil- lion bits BVS data and 0.64 million bits subsonic probe data; simultaneous reception will occur during certain mission phases	Minimum equipment complement to to this - digital tape recorder
Programing of spacecraft power, data storage, and transfer to accomplish functions shown above	The turning on and off of power to receivers, recorder, and other S/C equipment used in support of the BVS and subsonic probe must be accomplished as well as the control of data flow during receiving and retransmission of the data	The S/C programer/computer and sequencer must be programed to accomplish these functions

^a Data volume is based on BVS transmission from S/C separation for 22 min and from BVS entry - 20 min to BVS entry + 17.5 min at 240 bps. Transmission from entry + 1.5 minutes to entry + 6.5 minutes at 240 bps was assumed for the subsonic probe. This 45-min operating period is compatible with the probe view time for a nominal space-craft lead time of 45 min.

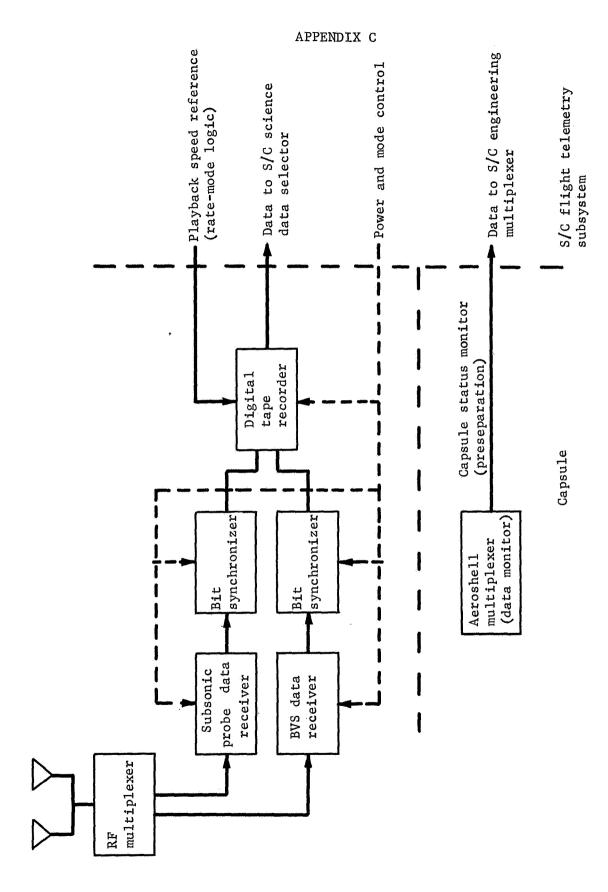


Figure C9. - Spacecraft Support Equipment

TABLE C8.- SPACECRAFT SUPPORT EQUIPMENT POWER AND WEIGHT SUMMARY

Equipment	Load, W	Weight, 1b
Relay antenna		10.0
RF multiplexer		.6
FSK receiver (2)	1.5 (each)	3.0 (each)
Bit synchronizer (2)	1.0 (each)	1.0 (each)
Digital tape recorder	8.0	12.0
Totals	13.0	30.6

Receiver: Both the BVS and subsonic probe receivers are double superheterodyne frequency shift key units with mark and space predetection filters followed by square law detectors and a summer. The BVS and probe receiver nominal frequencies are 390 and 400 MHz, respectively. The receivers are of the same design as those required for the orbiter in the BVS orbital mission.

Bit synchronizer: Each bit synchronizer is required to perform bit-by-bit synchronization of the BVS and subsonic probe data streams before entry of data into tape memory. The units are of the same design as required for the orbiter in the BVS orbital mission.

Digital tape recorder: A tape recorder for storage and play-back of the BVS and subsonic probe data has been identified as additional equipment. The Mariner Mars 1969 data storage subsystem functional requirements, M69-4-2016A, indicate complete use of present data storage capability is required for existing space-craft science. The additional recorder will have a minimum storage capability of 1.5 million bits with record and playback speeds compatible with a record data rate of 240 bps and a playback data rate of 270 bps.

The additional equipment will affect several existing space-craft subsystems, such as structures, power, cabling, flight telemetry, and the programer. The addition of the tape recorder for example, will require more electric power, control of operating mode (record/playback) and speed, as well as implementing a playback sequence to control the output of the three recorders.

<u>Flyby spacecraft experiments</u>.- The spacecraft experiments and their objectives are summarized in table C9.

TABLE C9.- SCIENTIFIC OBJECTIVES AND INSTRUMENTS FOR FLYBY SPACECRAFT

Instrument or experiment	Objectives
Ultraviolet (uv) spectrometer (similar to Mariner '69 instrument)	Obtain high spatial resolution uv spectra of day side, night side, and twilight atmosphere of Venus to determine abundance and altitude distribution of upper atmosphere constituents
Infrared (IR) spectrometer and radiometer (similar to Mariner '69 instruments)	Obtain high spatial resolution IR spectra of atmosphere and clouds to provide information on atmospheric and cloud composition and structure
Photo-imaging (3-color TV)	Obtain images of cloud cover at resolutions of about 0.5 to 1 km/TV line in white, blue, and yellow light providing information on cloud structure, breaks, and circulation pattern
Bistatic radar receiver	Provide information on surface topography, radius of planet, small-scale roughness, and general reflectivity and electrical properties of surface
Magnetometer and plasma probe	Investigate planetary and interplanetary fields, interaction of solar wind with planet, define shock fronts detected by Mariner V
Celestial mechanics	Refine mass of Venus, investigate density distribution within planet

The experiment characteristics are summarized in Table C10. As can be seen, both the total weight and the power are less than that allocated so there is some margin for growth. Most of the experiment characteristics are based on those given in the JPL Mariner '67 and Mariner '69 Functional Requirements Documents.

<u>Power subsystem.</u>- The solar panel area for the Mariner Mars 1969 spacecraft is given as 83 ft². When flown to Venus, this panel area could produce 1050 W, based on a specific output of 12.6 W/ft². Because this power is excessive, as shown below, the area can be reduced considerably.

TABLE C10. - FLYBY SPACECRAFT EXPERIMENT CHARACTERISTICS

Experiment	Weight, 1b	Power, W	Data (during encounter)	Mounting, deployment	Development status	Viewing
UV spectrometer	30.0	12.0	3200 bps	On scan ca	Mariner '69 instrument	Slit parallel to planet surface, within about 40° from subsolar point
IR spectrometer and	17.5	4.5	1330 bps	On scan platform	Mariner '69 instrument	Limb-to-limb scanning, light
IR radiometer	7.5	3.0	600 bits/63 sec (~9.5 bps)	•		and dark sides and space
TV (3-color)	15.0	20.0	~2.5 x 10 ⁵ bits/picture 10 ⁷ bit stor- age	On scan platform	Similar to Mariner '69	Limb-to-limb scanning light side and termi- nator
Bistatic radar receiver	15.0	5.0	~200 bps	Body fixed	Unknown, but current technology	Unknown, but Facing sub-Earth current point on planet technology
Magnetometer	5.0	5.0	30 bps	On most of omni-anten-	Similar to Mariner V instrument	!
Plasma probe	15.0	10.0	50 bps	Facing sun	Similar to OGO-E experiment	Facing sun
Totals	105.0	59.5			4	

APPENDIX C

Power requirements from Table IV of M69-3-250A, dated 15 Nov. 1967, are given below:

Normal flight sequence phases	Mars '69, W
Launch	337
Star acquisition	337
Cruise	315
Maneuver	368
Encounter	389
Playback	331
Abnormal flight sequence phase,	
gyros on	
Cruise	350
Encounter	428
Playback	366

Contributing to the values shown are the science power requirements listed in Table V of M69-3-250A as:

<u> Item</u>	Power, W
Television power	32.0
Infrared radiometer power	3.0
Infrared spectrometer power	4.0
Ultraviolet spectrometer power	12.0
Data automation subsystem power	20.0
Total science power	71.0

The science items listed will be replaced by those given below:

Item	Power, W
TV (3-color)	20
UV spectrometer	12
Bistatic radar	5
Magnetometer	5
Plasma probe	10
IR spectrometer	_20
Total	7.2

The following loads will be added to the spacecraft power subsystem:

Communications	Power, W
FSK receiver (2)	3
Bit synchronizer (2)	2
Digital tape recorder	8
Power	
Chargers (2) for BVS and aeroshell batteries (operating at C/50)	20
Thermal	
Electric heaters for capsule	<u>38</u>
Total	71

Should all of the loads listed be connected simultaneously, the total will be $143~\mathrm{W}$ added, as compared to $71~\mathrm{W}$ replaced or a net gain of $72~\mathrm{W}$.

Adding the load gain of 72 W due to spacecraft modifications to the value of 428 W shown for "Encounter" (with gyros on) a total of 500 W results. Paragraph 3.4.2.1 of M69-4-2004A, dated 14 Nov. 1967, shows 464 W to be the guaranteed solar panel power capability at encounter. The maximum possible power has been shown to be 70 W over the guaranteed value. Thus, the ratio of maximum possible power to that required is 1.25. Applying this same margin to the new value for the modified spacecraft would give 625 W as the gross output capability of the solar panels. This amount of power would require an area of 49.5 ft 2 as compared to 83 ft 2 installed for the Mars mission.

Mechanical interface. The capsule adapter interface with the spacecraft is shown in figure C2 in the orbital mission section. This interface is essentially identical to that with the orbiting spacecraft. Also, the attachment and separation mechanisms for the capsule from the adapter and the biocanister from the adapter are shown in figure C2.

Electrical interface. The electrical interface between the spacecraft and capsule system is shown in figure C10. A circuit is required from the spacecraft power subsystem to provide a trickle charge during the cruise mode to the battery chargers mounted in the capsule adapter. This provides charging for the BVS, subsonic probe and aeroshell-mounted batteries.

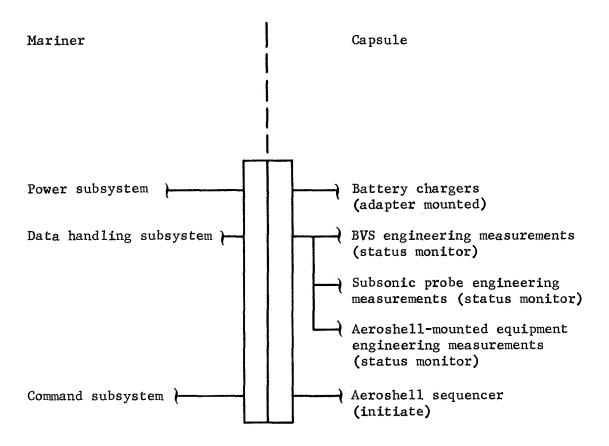


Figure C10.- Mariner/Capsule Electrical Interface

A wire bundle of 10 wires is required to provide status monitor of the BVS, subsonic probe, and aeroshell-mounted equipment. This will provide data transmittal and control of status monitor. A circuit is required from the spacecraft command subsystem to the aeroshell sequencer to command the sequencer on and off.

MARINER, VENUS/MERCURY

The Mariner spacecraft as defined in JPL Document 760-1, "Study of a Venus/Mercury Mission with a Venus Entry Probe," was specified as the spacecraft for the Venus/Mercury mission.

No major problems of compatibility between this spacecraft and the BVS/Entry Vehicle have been identified; however, modifications are required to substitute the BVS/Entry Vehicle for the entry probe identified in the JPL document due to the differences in weight and size of the two capsules and use of a direct communications link to Earth instead of a relay link via the spacecraft.

These modifications are summarized in table C11 and are discussed below.

Design Modifications

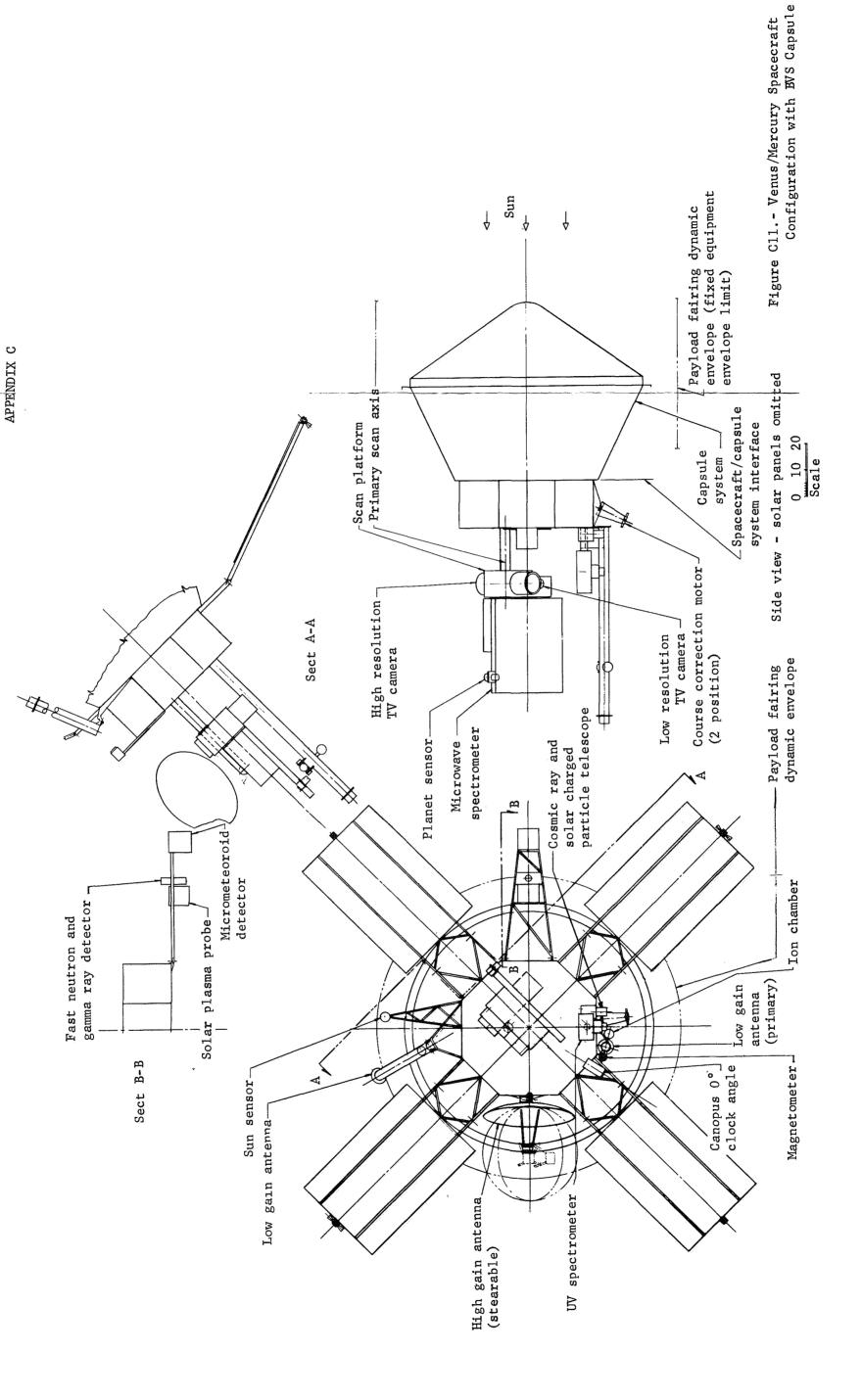
Spacecraft structure. Figure C11 shows the integration of the spacecraft and the BVS/Entry Vehicle in its biocanister. The diameter of the entry capsule is 7.0 ft and the overall length with propulsion module, is approximately 5.0 ft. It is mounted on the spacecraft in place of the entry probe shown in JPL Document 760-1.

The capsule is adapted to the spacecraft with a cone frustum canister/adapter that also maintains sterility of the capsule. The biocanister is completed by a closure bulkhead at the spacecraft interface and by a jettisonable canister cover that attaches at the major diameter of the cone frustum. The booster adapter also attaches at the major diameter of the biocanister.

Modifications to the spacecraft are primarily relocations of science and communications equipment resulting in new mounting and deployment structure. The midcourse engine must be reoriented because of the large difference in Venus capsule system weight. Two position capability will be retained. The basic octagonal body structural configuration will remain the same.

TABLE C11.- SPACECRAFT MODIFICATIONS

TABLE CII SFACECKAFI MUDIFICALIONS	Purpose	provide interface for sule adapter	Control of S/C temperature Presence of capsule will modify heat balance	w of sun Presence of capsule will shade fixed panel area and part of deployed area	Provide power to capsule See capsule power requirements before power switchover and charge capsule batter-ies during cruise	not used Direct link to Earth used for entry try and post-entry	Compensate for removal of Some cruise science deleted (see some cruise science	Provide proper midcourse maneuver both before and following Venus encounter tion and following capsule separtation Engine must provide thrust through planetary vehicle center of grav- ity both before capsule separtion	Some cruise science removed Increased weight of capsule with bVS requires deleting some cruise science
SLE CII	Pı	To provide inte capsule adapter	Control o	Provide view of	Provide powbefore powers and charge ies during	Relay link not used	Compensate for remosome cruise science	Provide pi maneuver l following	Some cruise science to reduce S/C weight
LAI	Modification	Structural modification to attach capsule	Modification of S/C thermal control	Modification of solar panels	Modification of power system	Remove S/C-mounted relay link equipment	Modify telemetry format and channel assignments	Reorient midcourse propulsion engine	Remove surplus cruise sci- ence



Spacecraft science. The spacecraft science complement in addition to the BVS/Entry Vehicle is shown in table Cl2. This reduces the science payload to a total of 180 lb by eliminating some of the cruise science shown in JPL Document 760-1. The encounter science for both Venus and Mercury remains intact and the major science objectives have been retained.

Power, W Weight, 1b Experiment Television cameras (2 each) 47 (total) 32 Microwave spectrometer/imager 50 40 25 12 UV spectrometer. 7 5 Magnetometer 15 10 Plasma probe Scan platforms, actuators, etc. 36 20

TABLE C12.- SPACECRAFT EXPERIMENTS

The major effect of the reduced payload on spacecraft subsystems is felt in the spacecraft data automation system that will be required to handle less data in the cruise mode and thus be made compatible with the current science complement.

180

119

Totals

Spacecraft telecommunications. - No relay communications link between the capsule and the spacecraft is required (the capsule will transmit directly to Earth following its separation from the spacecraft); therefore, the spacecraft relay equipment may be deleted. This eliminates 16.5 lb of equipment consisting of antenna, receiver, and telemetry equipment. The hardlines required for preseparation checkout of the capsule in the JPL configuration can be used for the BVS/Entry Vehicle.

Similarly, the discretes required for powering up the JPL capsule and initiating preseparation and separation sequences can be retained.

Discretes associated with receipt of relay data from the capsule and for transmission of the data to Earth are no longer required and can be deleted.

<u>Spacecraft power subsystem.-</u> Peak power loads for the mission will remain essentially the same because the deletion of the relay equipment results in an insignificant reduction in power.

The solar cell configuration, however, must be modified to move both the fixed and deployed panel area further from the roll axis to prevent shading by the larger diameter capsule.

No other modifications to the subsystem have been identified other than removal of power switching for the deleted communications relay equipment.

A photovoltaic array was selected as the baseline power subsystem configuration for the Venus/Mercury mission according to the referenced JPL Document 760-1. Because the mission involves close approach to the sun (0.43 AU at Mercury encounter) the solar panels are exposed to a solar flux several times that at Earth creating severe thermal problems.

The power subsystem is composed of solar cell panels, panel switching circuitry, a battery, and power conditioning equipment. The power source is sized for the continuous power demand (about 270 W), while the battery is sized to supply the launch/preacquisition power requirement and the power peaks, which are beyond the capability of the solar array.

To maintain a solar panel temperature below 140°C to avoid melting the solder connections, a semireflective, semitransparent metal coating was applied at the back of the cover glasses to reflect 61% of the total incoming energy. Seven fixed panels totaling 23 ft² and four extendible panels totaling 34 ft² provide sufficient solar panel area to maintain a minimum of 270 W. To limit the range of voltage input to the power conditioning equipment, sections of the array are electrically reconnected after Venus encounter to increase the number of cells in series by 50%. This compensates for the reduction in cell voltage caused by the increase in temperature. The reconnection will boost the array open-circuit voltage after Venus encounter to about 52 V and will provide at Mercury a minimum array voltage above 28 V.

The power subsystem uses a 1200 W-h battery, identical to that to be used on Mariner 1969. The power conditioning equipment is also based on Mariner 1969 components and design philosophy.

Spacecraft and BVS/Entry Vehicle Interfaces

Mechanical interface. The capsule adapter interface with the spacecraft is the same as for the orbital and flyby missions discussed previously.

Electrical interface. The electrical interface between the capsule and spacecraft is the same as for the flyby mission consisting of 10 conductors to provide status monitoring data, to provide power to the trickle chargers (to maintain charge on BVS, subsonic probe, and aeroshell batteries), and to provide command control of the capsule subsystems before separation of the capsule.

TV DROP SONDE

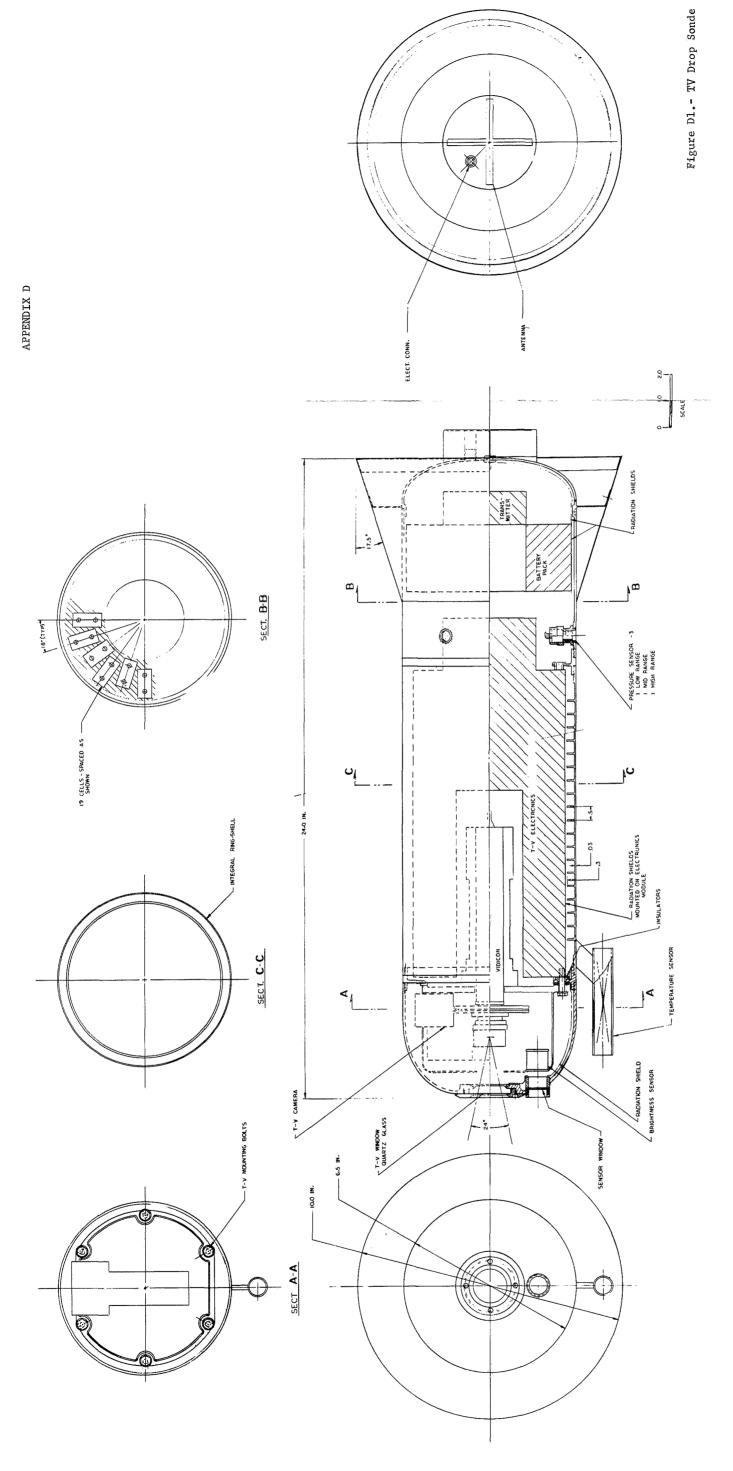
by Jack D. Pettus, Allan R. Barger and Paul G. Reznicek Martin Marietta Corporation

This appendix presents a conceptual design of a TV drop sonde concept for use with the BVS. The feasibility of imaging in the clouds or dense atmosphere of Venus depends not only on system design considerations, but also on the question of light levels and degree of diffusion in the atmosphere.

The concept proposed is based on housing a TV camera in a drop sonde to be carried in the BVS. Pictures can be taken from the BVS (at about 60 km altitude) and/or taken during descent. As illustrated in figure D1, the sonde would be about 6-1/2 in. in diameter and 2 ft long, containing a television camera, its electronics, power and data transmission equipment, and atmospheric pressure and temperature sensors. The TV camera looks forward through an optically clear quartz window located symmetrically in the nose section. Three pressure sensors are equally spaced around the body toward the aft end in the region of stable static pressure. A weight allocation is given in table D1.

TABLE D1. - TV SONDE WEIGHT STATEMENT

Item	Weight, 1b
TV camera	5.0
TV electronics	10.0
Battery pack	2.2
Transmitter, 2 oscillators	•5
Antenna	.4
Window	•3
Structure (body shell and equipment mounting and	
thermal control)	<u>12.0</u>
Tota1	30.4



SYMBOLS

A	visual albedo
B _{min}	minimum detectable brightness, foot-lamberts
Eo	vidicon tube sensitivity, foot-candle seconds
f/d	relative aperture
F _L	solar constant, lumens/cm ²
f _L	focal length of TV camera lens, cm
I	fllumination, foot-lamberts
S	smear rate, degrees/second
t _e	exposure time, seconds
T _T	transmission of the lens
TV	television
$\alpha_{\mathbf{R}}$	camera angular resolution, radians
$ heta_{ extsf{f}}$	half-angle of field of view for TV camera, degrees
$\theta_{\mathtt{i}}$	incidence angle of sunlight, degrees

MISSION PROFILE

The altitude/time history of the TV drop sonde is shown in figure D2 from the BVS float altitude to the surface (6050 km radius) for the upper and lower model atmospheres. The sonde, which has a ballistic coefficient of 5.0 slug/ft², is dropped with an initial vertical velocity of zero from the BVS float altitude of 58 km (190 000 ft). The effect on descent time of atmosphere model variation between upper and lower models is seen to be very small. A total of 2000 sec to the surface is required for the upper atmosphere. Mach number remains below 0.3 during the entire drop.

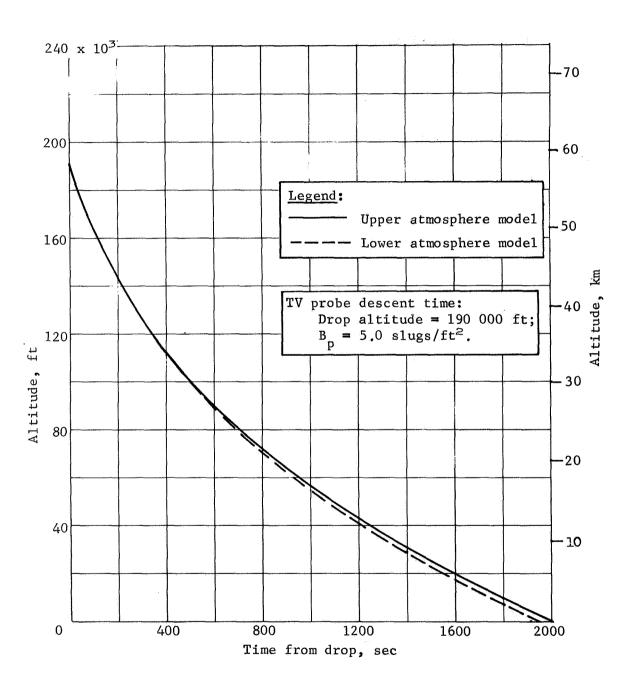


Figure D2.- Altitude/Time History of TV Drop Sonde

Imaging begins at an altitude of approximately 20 km with the camera. This is followed by transmission of the image data, then erasure of the image, and exposure for the next image. In all, four images are taken and transmitted with temperature and pressure data injected into the digital data stream.

Temperature and pressure data are stored during the first 18 minutes and transmitted before the first image.

SCIENCE SYBSYSTEM

The science subsystem consists of a TV camera and optics, pressure sensors, and a temperature sensor. The purpose of the TV camera is to obtain visual images of the surface on the near surface environment. At least four pictures are desired starting at about 20 km altitude.

Static pressure sensors and a temperature sensor are included, both to measure the profiles and to provide an altitude reference (barometric) for the TV pictures.

Figure D3 shows a typical arrangement for a TV camera and optics. Some of the mounting structure is superfluous for use on a drop sonde and is estimated to weigh about 5 lb. The associated electronics (not including transmitter) weigh about 8 to 10 lb, for a total of about 15 lb. Power requirements are 2.5 W for the camera and 12.5 W for the electronics.

For purposes of sizing the camera and optics, a resolution of 10~m/TV line in the last picture (taken at about 16~400~ft or 5~km) was selected. The image format on a 1-in. vidicon is $1.12\times1.12~\text{cm}$. The angular resolution (for 10~m at 5~km) is

$$\alpha_{R} = \frac{10 \text{ m}}{5 \times 10^{3} \text{ m}} = 2.0 \times 10^{-3} \text{ rad}$$

and the focal length is

$$f_L = \frac{1.12}{200} = 2.8 \text{ cm}$$

The field of view is then given by

$$\frac{1.12}{2.8} = 2 \tan \frac{\theta_f}{2}$$

or $\theta_{\rm f}$ = 22.6°. The lens diameter, assuming an f-number of 1, is then 2.8 cm.

Figure D3.- Surface Imaging

With a 5-msec exposure time, the allowable smear rate from all sources (for 1/2 TV line smear) is

$$S = \frac{\alpha_L}{2t_e} = 10^3/5 \times 10^{-3}$$

=
$$1/5$$
 rad/sec = 11.5 °/sec

The image smear depends on the altitude, horizontal and vertical velocity, and pitch and roll rates. Smear due to horizontal and vertical velocities is negligible ($\leq 0.6^{\circ}/\text{sec}$); smear rates due to pitch and roll are shown in figure D4. Because the pitch rate depends on the wind gusting that is unpredictable, the roll rate should be kept as low as possible, (below 1°/sec). This would then leave a comfortable margin of about 5°/sec for the allowable pitch rate before image smear becomes noticeable.

The major problem in the design of a camera system for this application is the uncertainty in the light levels. For this reason an SEC vidicon tube with a variable iris control is suggested. Iris control from f/d=1 to 20 would give a range of minimum detectable brightnesses from 0.1 to 40 ft-L. A brightness sensor with a large dynamic range (± 3 decades) is required to control the iris.

The probability of obtaining images by using a TV camera depends on the light level, the color of the light, the ratio of the signal to noise (the ratio between the intensity of light reflected or emitted by the objects in the field of view to the intensity of light backscattered by the intervening atmosphere), and the amount of distortion (refraction) of the signal by the media (atmosphere) between the object and camera. Calculations, based upon Rayleigh and Mie scattering in a 100-atm-surface-pressure atmospheric model, of the optical thickness of the Venus molecular (clear) atmosphere and several Venus cloud models indicate that 5 to 1% of the incident light at Venus may penetrate to the surface. These calculations also indicate that the light reaching the surface is completely diffuse (no shadows will exist) and is orange-red in color.

The signal-to-noise ratio has been shown to be sufficiently large over several kilometers of viewing distance to enable imaging. Depending on atmospheric motion, refraction of light by the Venus atmosphere may result in distortion. But, over several kilometers of viewing distance (especially at high altitudes), distortion may be insignificant.

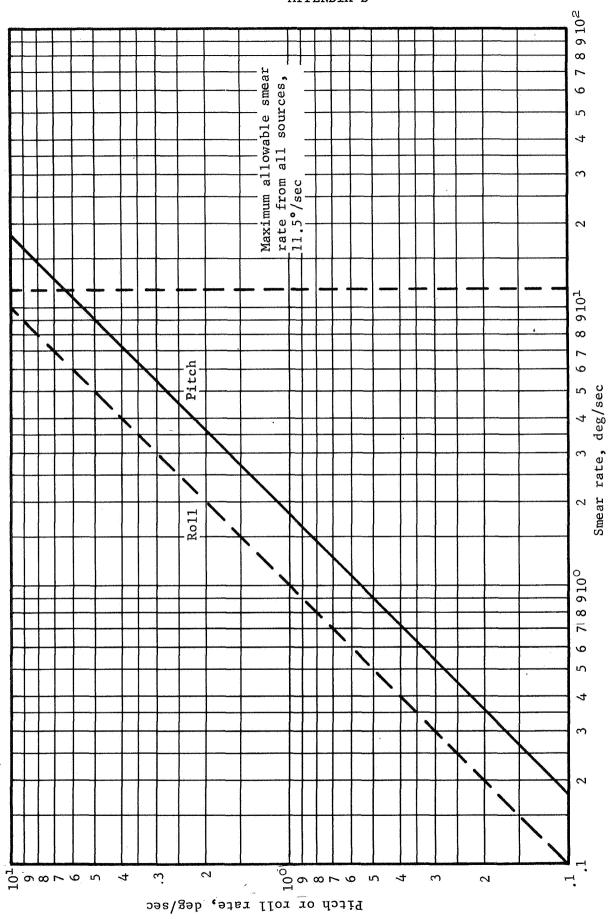


Figure D4.- Smear due to Roll and Pitch

102

TELECOMMUNICATIONS

Telecommunications functions for a TV drop sonde consist of providing a telemetry and data subsystem to interface with science sensors and transmit the accumulated data to the BVS.

The sonde will take four images in the last 18 minutes of fall, at approximately 250 kbits per picture. The TV imaging tube will retain the image so that it may be transmitted directly without storing the picture data in an external store. Pressure and temperature measurement data will be inserted in the data stream at the end of each line of the picture during the minimum data transmission rate, which is approximately 1024 bps for transmitting four images in the last 18 minutes of fall.

A typical block diagram for a sonde telecommunications subsystem is shown in figure D5. The transmitter is of solid-state design and operates continuously at an output of 355 mW and a frequency of 1500 MHz. Modulation is frequency shift key (FSK), with a split phase signal at 1024 bps. The antenna is a circularly polarized curved dipole integral with the aft end of the sonde so that the antenna elements are flush. The antenna half power beam width is 72°, with an "on" axis gain of 8 dB.

The data subsystem consists of a multiverter that interfaces with the camera electronics and with the pressure and temperature instruments. The frame sync generation timing and all picture processing are accomplished by the camera electronics, which is part of the science subsystem.

Performance for the sonde to BVS telemetry link is shown in table D2. Antenna pointing loss of 6 dB for both receive and transmit antenna is shown to allow for drift of the sonde with respect to the station for worst-case range and antenna aspect angle. A maximum frequency uncertainty of 60 kHz including doppler has been assumed requiring a predetection filter bandwidth of 64 kHz.

The 355 mW transmitter power provides a margin allowance for 4 dB multipath and 3.5 dB of adverse tolerances. The 4-dB multipath allowance can be considered extremely conservative because 1 dB is more likely to be the case.

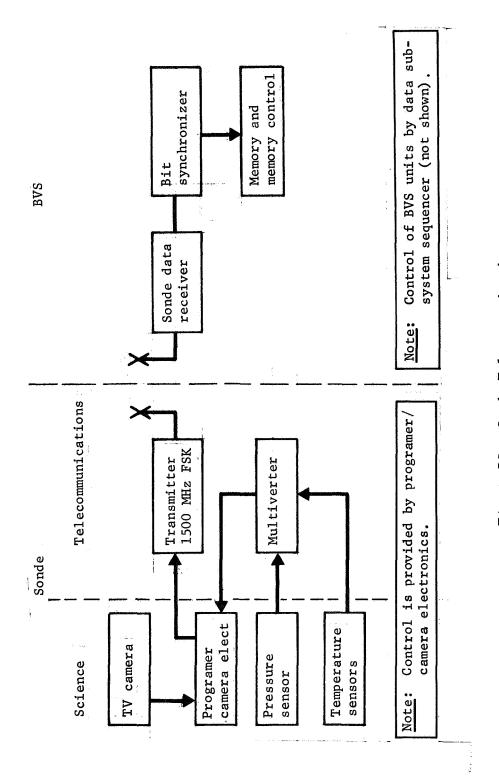


Figure D5.- Sonde Telecommunications

APPENDIX D

TABLE D2.- DROP SONDE LINK CALCULATIONS, FSK MODULATION (1024 BPS)

<u>anni na kata da a a a a a a a a a a a a a a a a a</u>	The second secon
Atmospheric attenuation	-1.0
Transmitter circuit loss	-1.0
Transmitter antenna gain	+8.0
Transmitter antenna pointing loss	-6.0
Space loss 1500 MHz, 100 km	-136.3
Receiving antenna gain	+8.0
Receiving antenna pointing loss	-6.0
Receiving circuit loss	1.0
Net loss	-135.3 dB
Receiver noise spectral density	~165.0 dBm
Channel filter bandwidth (64 kHz)	48.1 dB
Channel noise power	-116.9 dBm
Required input signal to noise for $P_b^e = 10^{-3}$ (TW = 64 000/1024 = 62.4)	4 dB
Multipath margin	+4.0 dB
Adverse tolerance sum	+3.5 dB
Required receive power	-109.8 dBm
Required transmitter power	+25.5 dBm
	355 mW

EFFECT ON BVS AND SPACECRAFT DESIGN FOR ORBITAL MISSION

Presently the data accumulation rates for the baseline (no TV drop sonde) BVS are relatively low, and permit the use of solid-state memories and a data transmission rate of 240 bps for 10 minutes for the BVS-to-spacecraft telemetry link.

The storage capacity required for the BVS to store the 18 minutes of data at a transmission rate of 1024 bps is a minimum of 1 106 000 bits as compared to about 36 000 bits of storage required for the baseline BVS. This can be accomplished with a magnetic tape machine with an estimated weight of 8 1b.

APPENDIX D

The increase in the number of bits of data to be relayed to the spacecraft makes it necessary to increase the BVS-to-space-craft data transmission rate. Figure D6 shows both the number of bits to be transmitted for a given number of pictures and the data rate required for a given transmission period. For example, at 240 bps (the baseline rate), it requires between 20 and 30 minutes to transmit the station data including one picture. The rate must exceed 450 bps to accomplish the same in 12 minutes. To transmit the basic science data plus four TV pictures to the spacecraft in 12 minutes, the rate from the top curve of figure D6 is more than 1500 bps.

Figure D7 shows the attainable bit rates for various combinations of communication range and sum, in dBw, of transmitter power and antenna gains less a multipath allowance using noncoherent FSK. The example illustrated is appropriate for many station locations with a maximum range of 15 000 km. Under those conditions, a rate of 480 bps may be the maximum that the baseline system should handle. This would yield one picture in a 12-minute period. As the rate is increased without increasing transmitter power or changing to a more efficient modulation scheme, the possibility of a drastically increased data error rate due to the station drifting to an unfavorable location is increased.

Use of coherent phase shift key modulation with the same 20 W of rf power and the same antennas yield the results shown in figure D8. A 5-dB improvement is realized over that of the non-coherent FSK approach, and, from the 15 000-km curve of figure D8, it can be seen that the rate can be increased to 1500 bps or greater. This rate can accommodate the transmission of four images in 12 minutes or less, which will allow relay of the pictures during the first encounter after station deployment. For subsequent communications passes, the data rate could be reduced if desired to provide communications under more adverse conditions.

The effect on spacecraft design is to require additional data storage capacity to accommodate the TV picture data. Additional time will have to be allotted in the spacecraft-to-Earth transmission schedules for relay of the additional data.

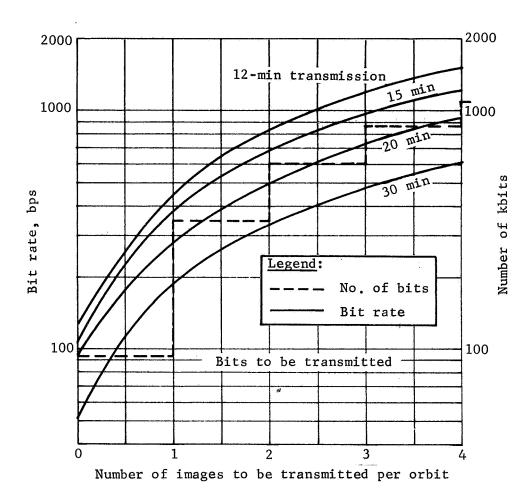
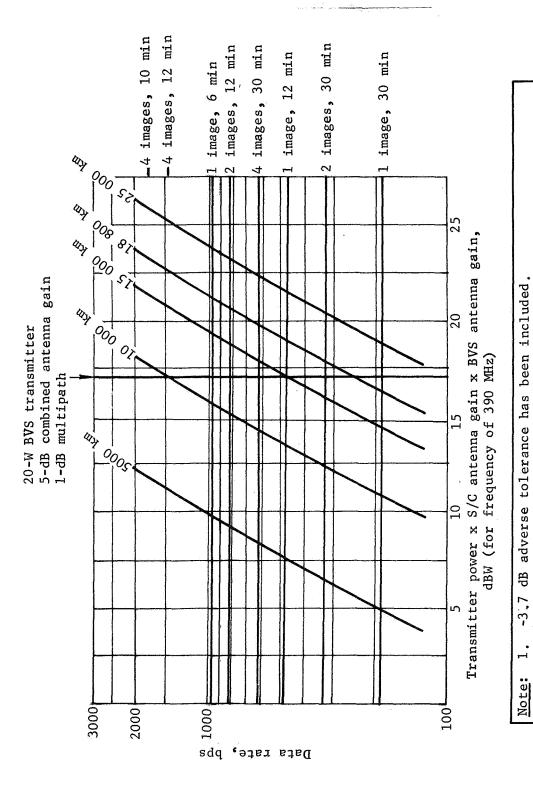
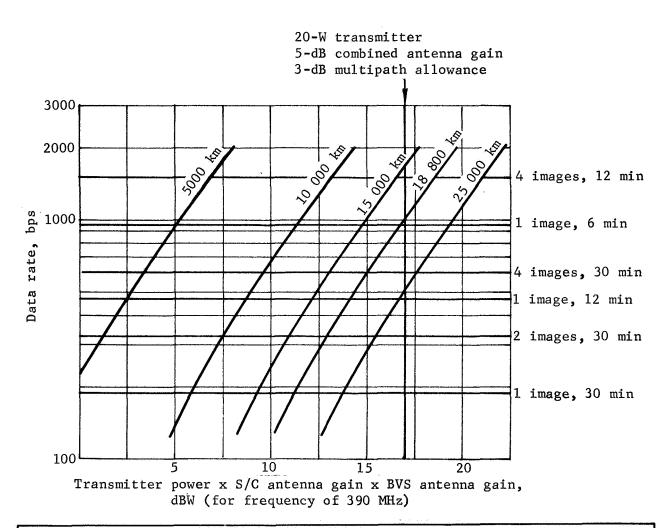


Figure D6.- Bit Rate Required vs Number of Images to be Transmitted for Various Transmission Periods



by 1 dB to account for multipath allowance; i.e., 20-W transmitter Figure D7.- Transmitter Power Antenna Gain Products vs Bit Rate for Various and 5-dB antenna gain gives 18 dBW minus 1 dB multipath = 17 dBW Bit error rate, 1 in 10^3 . Communications Ranges Using Frequency Shift Key Modulation

Multipath margin must be accounted for. Example shown reduces gain



Note: 1. -3.7 dB adverse tolerance has been included.

2. Multipath margin must be accounted for. Example shown reduces gain by 3 dB to account for multipath allowance; i.e., 20-W transmitter and 5-dB antenna gain gives 18 dBW minus 1 dB multipath = 17 dBW.

Figure D8.- Transmitter Power Antenna Gain Product vs Bit Rate for Various Communications Ranges Using Coherent Phase Shift Key Modulation

APPENDIX D

EFFECT ON BVS DESIGN WITH A DIRECT EARTH LINK

For direct Earth link transmissions such as used for the Venus flyby and the Venus/Mercury flyby, baseline data rates of 30 and 120 bps, respectively, are used. At these rates it would require 2.3 and 0.75 hr of continuous transmission to send science plus one TV picture to Earth. Use of coding could reduce the required transmission period to about 1.4 and 0.45 hr, respectively, which brings the period for one transmission for the Venus/Mercury mission within range of the present stored electrical energy allocation but the transmission period for the Venus flyby mission would remain a problem.

Increased BVS antenna gain in the form of lightweight switchable arrays integrated into the balloon design may be the answer or dependence on solar energy to provide the additional energy for the flyby mission.

STRUCTURE AND THERMAL CONTROL

The concept selected makes the sonde body a hermetically sealed container that is evacuated. The body structure must therefore withstand the overpressure of 100 atm at the planet surface. The vacuum interior permits use of radiation shields interlining the shell for thermal control as well as mounting the pressure sensors into the body shell and achieving a direct ambient pressure measurement.

A minimum volume body of reasonable length-to-diameter proportions is provided that can package the TV camera and equipment. Because these weight and aerodynamic characteristics do not achieve the desired ballistic coefficient, an aerodynamic flare is provided at the base. The flare also provides good directional stability during descent.

The sonde body structure is made up of a series of integrally machined ring-stiffened cylindrical segments. Threaded joints are employed at the main body assembly joints to facilitate assembly, sealing, and installation of equipment.

APPENDIX D

Two components in the drop sonde have low operating temperature limits; the battery has a desired limit of 90°F, and the TV camera has a limit of 105°F. The maximum temperature of the drop sonde before release is 95°F, because the local atmosphere can be 93°F maximum. Cooling the batteries below local ambient is costly in weight and power, thus it is desirable to take the loss in battery efficiency. To limit the temperature of the battery and TV camera a phase change material that has a melting point above the maximum sonde float temperature of 95°F must be used. Eicosane, a parafin, with a melting point of 98°F and a heat of fusion of 108 Btu/1b, was selected.

Three basic methods of thermal control were considered in limiting the temperature rise of the sonde components during the 33.3-minute descent to a surface atmosphere temperature of 931°F. Temperature of the probe shell was considered to follow the local atmosphere temperature.

One method considered was a vented probe. To cool the hot entering atmosphere, a heat exchanger with phase change material acting as a heat sink is used. The high expected atmosphere pressure eliminates the use of boiling water or ammonia as a heat sink. The optimum thermal control system weight for the vented probe is 8.9 lb. Phase change material with packaging will weigh 7.5 lb and high-temperature fibrous insulation will weigh 1.4 lb. The insulation, 1-in. thick, is on the inside of the container wall.

A second method of control considered a sealed probe but with a gas to eliminate electrical arcing at low pressure. Low pressure could result from outgassing of material with an evacuated probe. This system is similar to the above system except 4.5 lb for heat exchanger and phase change material are not required. The system weight has 1.4 lb of fibrous insulation and 3.0 lb of phase change material with packaging.

A third method (which was selected) has an evacuated sealed container with radiation shields and phase change material. A lightweight radiation shield is attached to the inside of the shell. With 1.3 lb of phase change material, the total thermal control system weight is 1.5 lb.

DUAL-ALTITUDE BALLOON

by Patrick C. Carroll and Robert W. Stoffel Martin Marietta Corporation

The statement of work specified that a dual-altitude mission be investigated. The dual-altitude concept implies that some duration of the mission be performed at an initial selected altitude and the remainder of the mission at a different altitude. The 175-1b gondola was used for sizing the various concepts.

Basically, the concept studied consisted of initial deployment at an altitude radius of 6125 km, which is above the clouds, and a second float altitude radius of 6108 km. This change in altitude is accomplished by relieving the hydrogen gas superpressure and pumping atmospheric gas into the balloon maintaining superpressure at the two altitudes. The pumping is accomplished with a small fan-type blower that pumps against the superpressure. The blower power is supplied by either a solar array or batteries; the battery power concept is a significantly heavier system.

A second method studied allowed the balloon to become a zero-pressure balloon by dumping the hydrogen gas superpressure, causing the balloon to descend until a small amount of makeup gas is dumped into the balloon at 6108 km, which allows the balloon to be neutrally buoyant at that altitude.

A third method involves the slow, controlled inflation of the balloon taking place over the altitude range of from 6125 to 6108 km. This produces a descent time of under 1 hr.

A reversed mission, dual-altitude balloon, was analyzed, wherein the balloon (station) is inflated at 6108 km, as in the baseline BVS, but with a larger superpressure balloon enveloping (but collapsed over) the inflated 18-ft diameter balloon. When the gas is released into the larger balloon, it causes the system to rise to 6125 km with the larger, superpressure balloon.

Except for the slow, controlled inflation method, which remains a 400-lb station, all of the above concepts appear feasible, but result in increased station weights of 500 to 900 lb.

DUAL-ALTITUDE MISSION DESIGN CRITERIA

The following criteria were used for the dual-altitude concepts:

- 1) Mean atmosphere (90% CO₂);
- 2) Initial float radius of 6125 km,

$$P_a = 30.25 \text{ mb } (0.439 \text{ psia}),$$
 $T_a = -35.7^{\circ} \text{ F } (424^{\circ}\text{R}),$
 $\rho_a = 0.004 \text{ lb/ft}^3,$

 $\frac{\overline{M}}{a} = 42.41.$

3) Initial superpressure of 6 mb;

- 4) Final float radius for superpressure balloon of 6108 km, except for solar cell power operated pump configuration that will float at radius determined by power limitation of solar cells;
- 5) A 175-1b gondola will be used;
- 6) The following configurations will be analyzed,
 - a) Superpressure throughout mission with battery powered pump,
 - b) Superpressure throughout mission with solar cell powered pump,
 - c) Superpressure initially and then zero pressure for in the clouds mission,
 - d) Superpressure throughout mission with controlled inflation taking place from 6125 to 6108 km. The parachute would be released at 6125 km, and the inflation module released at 6108 km,
 - e) Reversed mission approach, deploying at 6108 km and rising to 6125 km.

CONFIGURATION DESCRIPTION AND OPERATION

The baseline single altitude configuration is shown for comparison with the dual-altitude concepts. This configuration is deployed near and stabilizes at a float radius of 6108 km. The baseline concept does not include makeup gas. The baseline concept balloon skin was designed to a film stress of 3600 psi at a superpressure of 6 mb. Although Mylar can be stressed to 10 000 to 12 000 psi, safety margins were selected that resulted in the 3600-psi stress limit. However, for the dual-altitude configurations, the high altitude conditions result in very sensitive weight variations with allowable stress. Results of a parametric tradeoff of balloon design vs allowable stress are shown in figures E1 and E2.

Balloon weight is:

$$W_B = At \rho = \pi D^2 t \rho$$

where

 $A = balloon area, ft^2;$

t = balloon skin thickness, ft;

 ρ = balloon material density, 1b/ft³.

Balloon stress is:

$$\sigma = \frac{PD}{4t}$$
 or $t = \frac{PD}{4\sigma}$

This produces balloon skin density based on balloon volume:

$$\rho_{B} = \frac{W_{B}}{V_{B}} = \frac{AT_{O}}{V_{B}} = \frac{(\pi D^{2}) \frac{PD}{4 \sigma O}}{\frac{\pi}{6} D^{3}}$$

$$\rho_{\rm B} = \frac{6}{4} \frac{\rm P_{\rm O}}{\sigma}$$

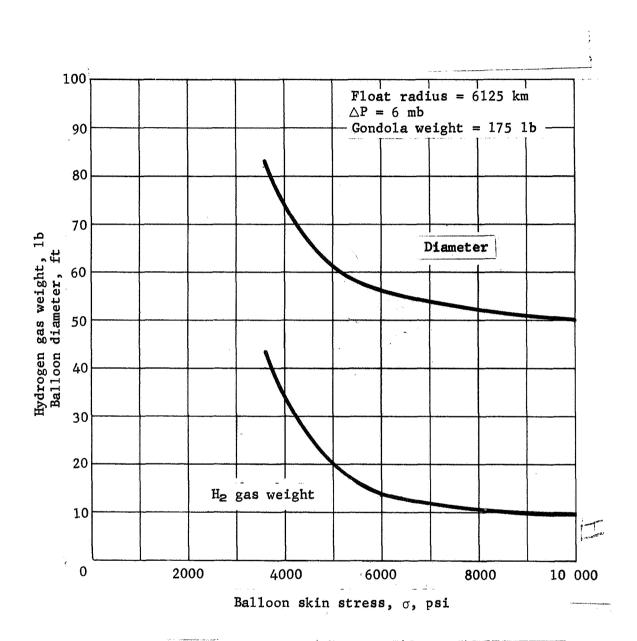


Figure El.- Effect of Allowable Balloon Stress on Balloon Size

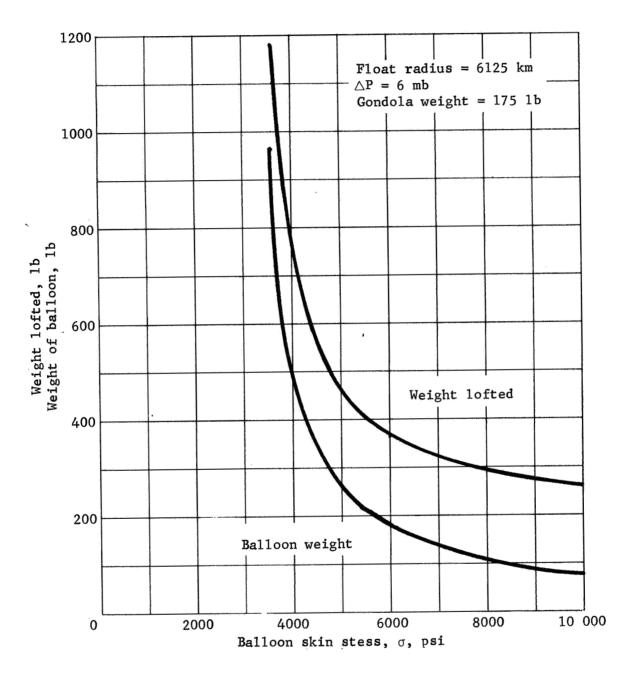


Figure E2.- Effect of Allowable Balloon Stress on Balloon Weight

and the required balloon volume is related to the gondola weight densities by:

$$V_{B} = \frac{W_{gondo1a}}{\rho_{Atm} - \rho_{B} - \rho_{H_{2}}}$$

where

 $^{\circ}$ Atm = atmospheric density, 1b/ft³,

 $\rho_{\rm H_2}$ = buoyant gas density, 1b/ft³.

From figures E1 and E2, it can be seen that the system weights, and specifically the balloon weight, are very sensitive to allowable stress, and a value below 6000 psi results in extreme system weights. Therefore, an allowable stress of 6000 psi was selected as the design criterion for the dual-altitude configurations. This stress is still well under the yield stress of 12 000 psi, but results in lower safety factors than that of the baseline design.

A dominant factor in balloon performance is the balloon gas temperature and its relation to the atmospheric temperature. The evaluation of this relationship for the Venus atmosphere is shown in figure E3. The temperatures are for a pure hydrogen gas in the balloon, and the effect of clouds is depicted. Below a radius of 6120 km, the nominal atmosphere assumes clouds exist; however, the temperature was calculated without clouds as well because there is the possibility of breaks in the cloud layer.

For the concepts in which atmosphere is pumped into the balloon to change float altitude, the average balloon gas temperature is shown in figure E3.

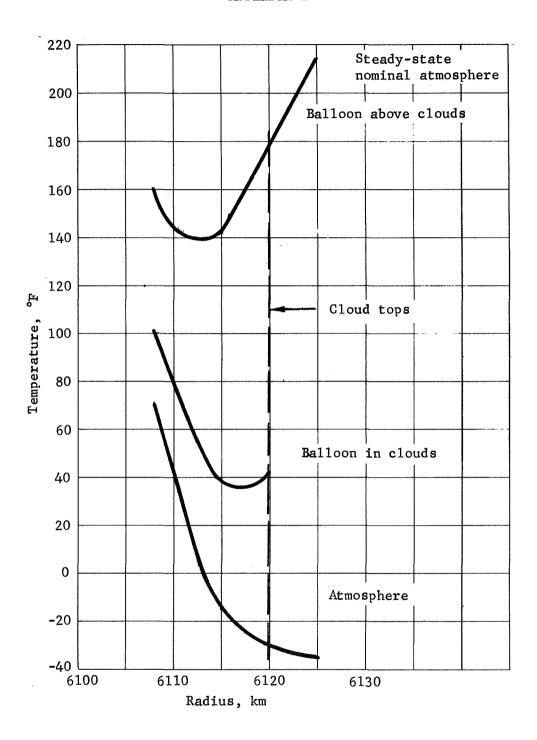


Figure E3.- Balloon Temperature

CONCEPT DESCRIPTION AND OPERATION

Configurations A and B are conceptually the same except for the pump power source -- batteries in one case and solar cells in the other. The sequence of events is as follows:

- 1) BVS descends to deployment altitude on parachute;
- 2) Balloon is deployed, inflated, and floats at a radius of 6125 km. A 6-mb superpressure designs the balloon at this condition;
- To descend with a constant superpressure of 6 mb, atmosphere is pumped in and Ho gas is simultaneously vented. Figure E4 shows the H2 and atmosphere gas mixture required to obtain equilibrium flotation at every altitude during descent. Upon entering the clouds, the temperature drops by about 136°F, thus drastically reducing lift. In actual practice, the balloon would be allowed to descend rapidly through this altitude with no makeup Ho because, at a lower altitude, less H2 is required to finally stabilize. At the final altitude, the balloon would have a mixture of atmosphere and hydrogen at a superpressure of 6 mb and a molecular weight slightly lower than the atmosphere, floating in a stable mode. Figure E5 shows a pump installation for the balloon. The blower is mounted to the balloon canister with a shutoff valve.

The significant weight penalty for Configurations A and B (approximately 508 lb) is due to the requirement for 6-mb superpressure, resulting in a significant weight of hydrogen gas and the large balloon (62.5-ft diameter).

The pumping requirement for Configuration A is $85 \, \mathrm{ft^3/min}$ based on a 24-hr period that allows the pumping to be completed within the 25-hr orbital period. A Rotron Manufacturing Company, Inc. PROPIMAX-2 tube axial fan (Model 367JS) will meet the pumping requirement with 80 to 100 ft³/min against a 2.5-mb head at 35 W. This results in 840 W-h or 32.3 A-h for power. The resulting silver-zinc battery weight is 30 lb, and the pump and Rotron Batac power supply (model BC111) weight about 1 lb.

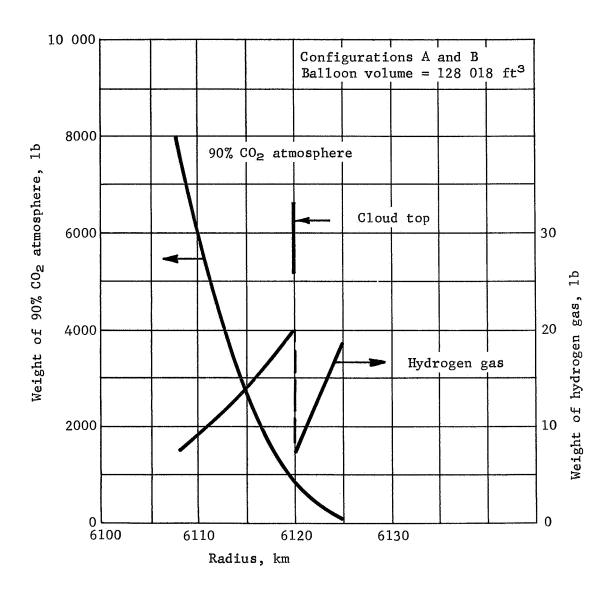
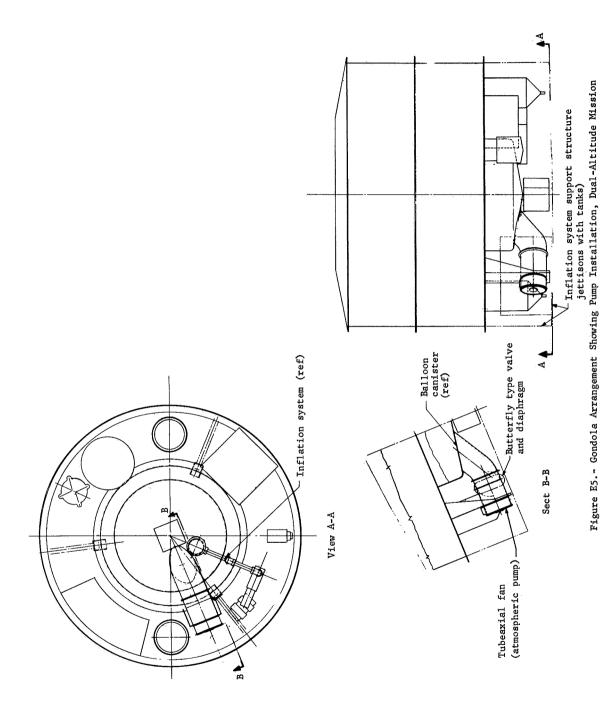


Figure E4.- Gas Mixtures Required for Equilibrium Float



In Configuration C, rather than pumping atmospheric gases into the balloon to decrease its net lift, balloon gas is vented to start the descent. The balloon is designed to become zero pressure at lower altitudes so it may be designed to a superpressure of only 2 mb at the high altitude providing a margin of 6.7% superpressure at design altitude. The sequence of events is as follows:

- BVS descends to deployment altitude on parachute, is deployed, inflated, and stablizes at 6125 km. A 2-mb superpressure designs the balloon at this condition;
- 2) The hydrogen gas superpressure is partially vented to start descent;
- 3) Balloon descends to 6108 km, and makeup gas is released into the balloon to provide equilibrium flotation.

This system is neutrally stable because of the zero-pressure condition, but will slowly drift up or down without an active control system to maintain altitude. This concept results in a 665-1b BVS.

Configuration D provides dual-altitude operation by a slow inflation of the balloon. With the baseline balloon, the inflation rate is controlled so that the 6-mb superpressure is not exceeded during the inflation process. The balloon becomes fully extended shortly after passing the radius altitude of 6125 km. Its descent rate is determined by the balance of gravity and aerodynamic drag acting on the balloon. Figure E6 indicates the radius altitude of the balloon as a function of inflation time. The time required for the balloon to sink from 6125 to 6108 km is approximately 30 minutes (1800 sec). These curves were generated from a balloon deployment dynamics program that does not consider solar heating during the inflation process, and therefore, allowed the balloon to be inflated faster than it would be in practice. With a slower inflation, the extra weight of the inflation system must be carried longer, resulting in a slightly faster descent. This method can be accomplished with the 400-1b BVS.

Configuration E represents a natural and simple way to change altitude by reversing the altitude sequence and starting at the low altitude. The concept consists of a balloon inside a larger balloon. The internal balloon is inflated initially at 6108 km and floats with a 6-mb superpressure. When change in altitude is desired, the balloon is vented into the larger collapsed balloon that inflates, and the system rises until the large balloon is fully inflated to a superpressure of 2 mb. In the event of premature failure of the small balloon, the system rises to the upper altitude. This system does not require pumping or makeup gas and is stable at either altitude. This concept results in a 500-1b BVS.

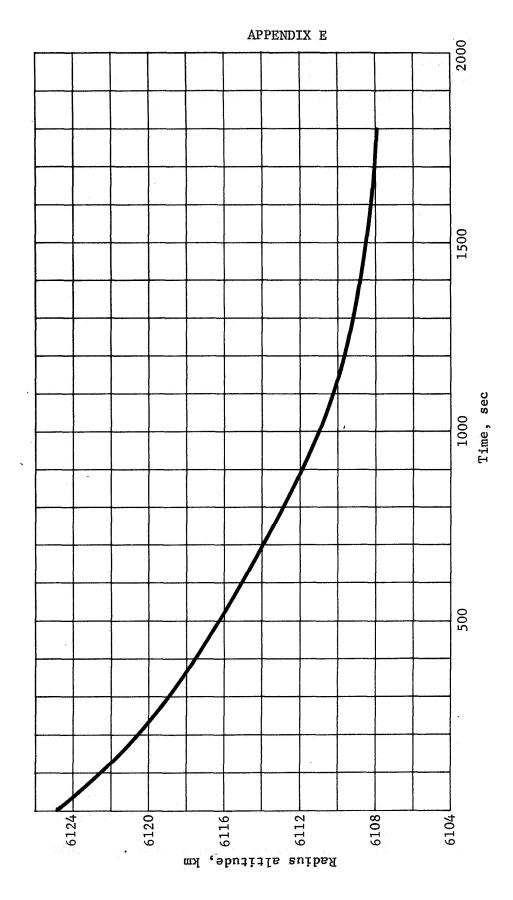


Figure E6.- BVS Altitude with Time for a Slowly Inflated Balloon

Comparison

Table El displays various weights and parameters for the four dual-altitude concepts under consideration as well as for the base-line single altitude balloon. Of interest is the total system weight, where a minimum increase over the baseline 400-lb is desirable. A second consideration in the comparison of the four concepts is the ability of the particular concept to provide atmospheric measurements at the 6125-km level in addition to the 6108-km level.

Configuration D, in which the balloon does not actually stabilize at a higher altitude, will not provide an appreciable increase in mission success probability because the descent time is only twice that spent descending on a parachute in the baseline configuration. For the orbiter case, this slow descent operation may even inhibit the transmission of atmospheric data during the initial pass of the orbiter because of difficulty in deploying science before dropping the balloon inflation tanks.

Configuration C results in zero-pressure operation at 6108 km and, therefore, will require an active gas makeup or ballasting system to stabilize and maintain that altitude. The extra 265 lb required for this system does not include the weight required for maintenance of altitude. Because the anticipated hazards can be overcome by an active makeup system, in any case, the addition of a gas makeup system or a ballasting system to the baseline design would prove more weight effective.

Configuration E is the lightest of the four dual-altitude schemes and has the added advantage of providing protection against balloon leakage. The operation is in reverse, i.e., the balloon is first deployed at the lower altitude.

Conclusion

The dual-altitude balloon appears feasible. Four of the possible methods have been analyzed and are shown to have various degrees of desirability and mission life at the different altitudes. The dual altitude capability is achieved with some degree of added complexity and weight. The weight increase can amount to slightly more than 500 lb.

APPENDIX E

TABLE EL. - COMPARISON OF DUAL-ALTITUDE CONFIGURATIONS

	Baseline single altitude mission	Configurations A and B dual-altitude super/super	Configuration C dual-altitude super/zero	Configuration D dual-altitude slow inflation	Configuration E reversed mission super/super
Parameter Initial radius, km Final radius, km Initial superpressure, mb Final superpressure, mb Balloon volume, ft³ Balloon diameter, ft Requires pump Atmosphere pumped in, 1b Balloon skin stress, psi	6108 6108 6 6 3043 18.0 No None 3600	6125 6108 6 6 6 6 128 018 62.5 Yes 7933.0	6125 6108 2 0 97 361 57.1 No	6125 6108 6 6 6 3043 18.0 No 	6108 6125 6 2 2 2 3844/62459 19.4/49.2 No
Weight statement Balloon weight, lb (Second balloon), lb Inflation gas, lb Support fabric weight, lb Makeup gas weight, lb Pumps and batteries, lb Gondola weight, lb	14.63 9.14 1.75 1.75.0	268.3 18.7 10.0 40.0 175.0	96.6 12.7 14.0 6.3 87.9	14.63 9.14 1.75 	8.1 43.6 11.5 15.0 175.0
Initial floated weight	200.52	512.0	389.5	200.52	253.2
10% of initial gas weight, 1b Main gas tanks, 1b Tank support weight, 1b Control weight, 1b Parachute weight, 1b	0,92 140,04 24,32 16,0 18,2	1,9 288,4 50,2 16,0 40,0	1,3 195,6 34.0 16.0 28.6	0.92 140.04 24.32 16.0 18.2	1.2 177.8 30.9 16.0 21.6
Total BVS system weight, lb	0*00*	5*806	0.599	0.004	500.7

STERILIZATION

by James E. Cole and Ted H. Tucker Martin Marietta Corporation

The BVS sterilization study resulted in an interpretation of the planetary quarantine analysis for Venus in terms of engineering criteria. In addition, innovations have been added based on conclusions drawn from corollary sterilization studies and experiments in the general area of bioassay, sterilization/decontamination operations, and sterile-insertion and sterile repair. These techniques permit installation or addition of heat-sensitive items after terminal sterilization as well as replacement of failed hardware without repetition of the terminal sterilization treatment. The only use of the technique in this study is for sterile insertion in the loading of hydrogen gas in the BVS after it has undergone terminal sterilization. R&D studies now in process at Langley and Martin Marietta are expanding the capabilities of these techniques for much wider applications. Significant cost savings can be realized from the recommendation that short exposures to dry heat be substituted for ETO decontamination. This recommendation would classify ETO decontamination as an optional method rather than, as in the beginning of the study, a program requirement -- with no alternative. The alternative method of decontamination is the use of heat as a method for reducing the biological contamination level. In combination, these criteria represent a significant reduction in the impact that sterilization has on the design, development and test of spacecraft for Venus missions without detraction from the basic planetary quarantine requirements.

STERILIZATION CRITERIA

Significant planetary quarantine and sterilization requirements used in this study are as follows:

- 1) Contamination probability level of 10⁻³ for all potential sources of contamination while biological studies of the planet are being carried out;
- 2) The BVS/Entry Vehicle will be heat sterilized so that the probability that a live microorganism remains is 10^{-3} ;
- 3) The probability of impact of the planet Venus by an unsterilized orbiter shall not exceed 3 \times 10⁻⁵ in an orbit not to decay within 50 yr;

- 4) The probability of accidental planetary entry by an unsterilized flyby spacecraft shall not exceed 3×10^{-5} ;
- 5) The BVS/Entry Vehicle shall be biologically sealed in a sterilization canister following terminal sterilization and remain sealed until separation in flight;
- 6) Design of the canister shall be such that no contaminated surface shall be in line-of-sight of a sterile surface during canister separation;
- 7) The trajectory of the separated canister shall be such that it does not violate the planetary quarantine requirement.

STERILIZATION IMPACT ON SYSTEMS AND COMPONENTS

The BVS Sterilization Constraints and Requirements document was developed for use in this study. This document discussed in detail the impact that sterilization requirements have on Venus planetary systems hardware with regard to hardware qualification, and the extent of microbiological contamination control that must necessarily be imposed throughout the assembly and test phase. Itemized below are some of the more pertinent criteria:

- 1) BVS hardware shall be qualified in accordance with the 1973 Voyager Capsule Systems Constraints and Requirements Document, Revision 2, (ref. F1), and supplemented where necessary with JPL Spec VOL-50503-ETS (ref. F2);
- 2) Parts and or materials shall be selected from a NASA-approved sterilizable parts list, or qualified to a Martin Marietta/customer-approved qualification test procedure (a proposed qualification test procedure is shown in the BVS Sterilization Constraints and Requirements Document);
- 3) Qualification of assemblies/subsystems to prove compatibility with sterilization environment shall be by demonstration of structural integrity and normal functioning after exposure to six 64-hr cycles of heat sterilization at 135°C in a nitrogen atmosphere;

- 4) Capsule system sterilization qualification shall be performed on the proof test model (PTM) by exposing it to three cycles of heat sterilization at 135°C in a nitrogen atmosphere for periods of 57, 60, and 72 hr, respectively;
- 5) Flight hardware shall be exposed to one sterilization heat cycle in a nitrogen atmosphere at 125°C for a period of 60 hr at assembly/subsystem level;
- 6) Assembly through subsystem level shall be performed in a class 100 000 environment as defined by Fed Std 209a and NASA Std 5340.2:
- 7) Flight capsule system final assembly shall be performed in a class 100 environment as defined by Fed Std 209a and NASA Std 5340.2;
- 8) Biological monitoring shall be performed on all flight and proof test model hardware subsequent to assembly/ subsystem assembly until encapsulated in the sterilization canister and terminally sterilized;
- 9) Each flight capsule shall be manufactured, assembled, tested, and encapsulated in such a manner as to enter the terminal sterilization cycle with less than 1×10^5 viable spores;
- 10) The terminal sterilization process shall subject the capsule to a time-temperature cycle equivalent in lethality to 125°C for 24.5 hr.

BVS STERILIZABLE EQUIPMENT SURVEY RESULTS

Table F1 summarizes the results of the BVS sterilizable hardware survey completed near the end of the feasibility study.

The information shown in the table is based, in part, on work done at Martin Marietta with sterilizable electronic hardware and electric power sources. The information came from a variety of reports, but the one most frequently used was a JPL report in which they reported their work with the capsule system advanced development (CSAD) program in their Space Program Summary 37-49, volume III (ref. F3). Martin Marietta report entitled, "Investigation of the Feasibility of Sterile Assembly of Silver-Zinc Batteries" (ref. F4) was another report from which information was obtained.

TABLE F1.- BVS STERILIZABLE HARDWARE

11111111111111	- 575 5111	CILIZADES IN		
	Ster	ilization st	tatus	
BVS equipment list	Accept-	Under in- vestiga- tion	To be investi- gated	Reference/remarks
Electronic Central data multiplexer/ encoder Data storage	X X	x		Plated wire memory, CSAD Librascope
Sonde receiver and data assembly Sonde antenna	x			CSAD omni antenna
Data handling S/S prog Command receiver Command detector Command decoder Transmitter Diplexer Main antenna Radar alt (electronics) Radar alt (array) Sequencer	X X X X X X X			CSAD (S-band)
Electrical				
Main batteries Auxiliary batteries Instrument power supply Power pack Solar cells Cable and connectors	X X X X X			C SAD C SAD
Science				
Bioscience Triax accelerometer Pressure exp Temperature exp Light backscatter Solar aspect	x x x		x	CSAD CSAD 1964 Mariner image dissector: CBS Labs CSAD
Water vapor detector Visual photometer	Х		х	CSAD
Mechanical/electromechanical Structure Ordnance valves Pressure switch Solenoid valves Parachute Balloon	X X X X X	x		

The equipment shown as acceptable in the chart indicates that there are acceptable parts available (heat sterilizable) for the general classification of electronic equipment using commom parts (integrated circuits, resistors, capacitors, etc.) with the exception of tantalum capacitors for which 125°C is the upper limit.

An investigation is currently in progress at Martin Marietta on sterilization compatibility of balloon materials and processing. Initial test data indicate that the material (singular or composite) can be heat sterilized (ref. F5).

BVS STUDY SUMMARY

The sterilization study has resulted in establishing a feasible plan for selection of sterilizable parts and materials and qualification of parts, assemblies, and subsystems. Manufacturing and test methods developed during the study will assure production of sterilized, flightworthy equipment. Review and evaluation of the BVS equipment list has identified a number of areas requiring additional work to assure sterilizability. Use of short dry heat exposure (in lieu of ETO) is recommended to achieve cost savings and enhanced reliability. This change will permit the use of parts and materials that meet all other program requirements, except for ETO compatibility, and therefore deletes the need for separate qualification tests.

REFERENCES

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- F3. Anon.: Capsule System Advanced Development Program Summary 37-49 vol. III. JPL, Feb. 29, 1968.
- F4. Anon.: Investigation of the Feasibility of Sterile Assembly of Silver-Zinc Batteries. Martin Marietta Corporation, Denver, Colorado, Sept. 1968 (NASA Contract NAS1-7656).
- F5. Anon.: Materials Engineering Test Plan No. 68/50P. Martin Marietta Corporation, Denver, Colorado, July 3, 1968.

MULTIPATH ANALYSIS

by James W. Berry Martin Marietta Corporation

The performance, of a relay communications link between a planet descent vehicle and an orbiting or flyby spacecraft may be degraded by scattered signals from the planet surface. The relative magnitude, phase, and time delay between the direct and reflected signals, received at the spacecraft, will determine the degree to which the link will be affected.

The appendix describes the multipath environment considered in the design concept for a relay communication link between the BVS and the spacecraft.

SYMBOLS

С	velocity of light, kilometers/second
E _d	peak direct signal voltage
Es	peak scattered signal voltage
$^{\mathrm{G}}\!_{lpha}$	ratio of BVS antenna power gain in direction of space- craft to gain in direction of signal reflected by planet to the spacecraft
M _{rc}	relative permeability
R	surface reflection coefficient
R _{CP}	reflection coefficient for a circular polarized signal
R_d	difference in path length between direct and reflected signal, kilometers
R _V ,R _H	reflection coefficient for vertical and horizontal polarized signals, respectively
T	correlation distance
$^{t}{}_{D}$	time delay, seconds
V	velocity, meters/second
Y	normalized admittance
$\boldsymbol{\alpha}_{\mathtt{P}}$	BVS antenna aspect angle to spacecraft, deg.

$\alpha_{\mathbf{Y}}$	BVS antenna aspect angle of signal reflected from planet, degrees
(^y CP) _m	fading parameter modified for antenna directivity and difference in path length between reflected and direct signal
$^{\gamma}_{ ext{FM}}$	ratio of peak direct signal to rms of scattered signal
€rc	relative complex permittivity
θ_{1}	local angle of incidence of reflected wave, degrees
λ	wavelength, meters
$\rho_{ m R}$	ratio of reflected signal path length to the direct signal path length
$\sigma_{\mathbf{c}}$	conductivity of surface of Venus
$\sigma_{ m d}$	standard deviation of surface height
τ	correlation time, seconds

SURFACE MODEL

The fading parameter, γ_{FM}^2 , is a measure of the severity of the fading. Turin (ref. G1) defines gamma as

$$\gamma_{\text{FM}} = \frac{\text{peak direct signal}}{\text{rms scattered signal}} = E_{\text{d}} / (E_{\text{s}} / \sqrt{2})$$
 (G1)

where

 $E_{d} = peak direct signal$

 $E_s = peak scattered signal$

Because the surface reflection coefficient, R, is the ratio of the peak scattered signal to peak direct signal, we have from (G1)

$$\gamma_{\rm FM} = \sqrt{2}/R$$

Assuming the reflection coefficient for an incident signal of circular polarization can be approximated by

$$R_{CP} = \left(R_V^2 + R_H^2\right)^{\frac{1}{2}}$$

where R_{V} and R_{H} are the surface reflection coefficients for incident signals of vertical and horizontal polarizations, respectively, then,

$$\gamma_{\rm CP}^2 = \frac{2}{\left(R_{\rm H}^2 + R_{\rm V}^2\right)} \tag{G2}$$

Equation (G2) was modified to account for the relative magnitudes of the direct signal to the spacecraft and the incident signal to the planet

$$\left(\gamma_{\text{CP}}^2\right)_{\text{m}} = \gamma_{\text{CP}}^2 \, \rho_{\text{R}}^2 \, G_{\alpha} \tag{G3}$$

The surface reflection coefficient is a function of the incidence angle and the electrical properties of the reflecting surface as shown by Beckmann and Spizzichino (ref. G2).

$$R_{V} = \frac{Y \cos \theta_{1} - \sqrt{Y - \sin^{2} \theta_{1}}}{Y \cos \theta_{1} + \sqrt{Y - \sin^{2} \theta_{1}}}$$
(G4)

$$R_{H} = \frac{\cos \theta_{1} - \sqrt{Y} - \sin^{2} \theta_{1}}{\cos \theta_{1} + \sqrt{Y} - \sin^{2} \theta_{1}}$$
(G5)

These reflection coefficients are representative of a smooth reflecting surface, where θ_1 is the local angle of incidence (see fig. G1), and Y is the normalized admittance as given by Beckmann (ref. G3).

$$Y = \epsilon_{rc} / M_{rc}$$

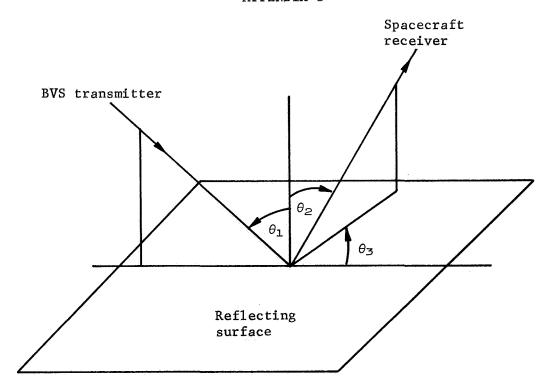


Figure G1.- Angle Convention

where ϵ_{rc} is the relative complex permittivity

$$\epsilon_{rc} = \epsilon/\epsilon_0 + i 60 \lambda \sigma$$

Here, several simplifying assumptions were made: pure specular reflections were considered, i.e., $\theta_1 = \theta_2$ and $\theta_3 = 0^\circ$; the conductivity, σ , of the Venusian surface is sufficiently low at 400 MHz that,

$$\epsilon_{rc} = \epsilon/\epsilon_0$$

and that the relative permeability, $M_{\rm rc}$ of the surface is unity. The surface of Venus is thought to be dry and sandy or rocky with a relative dielectric of permittivity of 3.75, as determined from cw radar measurements (ref. G4). Equations (G4) and (G5), may now be expressed as a function of incidence angle

$$R_{V} = \frac{3.75 \cos \theta_{1} - \sqrt{3.75} - \sin^{2} \theta_{1}}{3.75 \cos \theta_{1} + \sqrt{3.75} - \sin^{2} \theta_{1}}$$
 (G6)

$$R_{H} = \frac{\cos \theta_{1} - \sqrt{3.75} - \sin^{2} \theta_{1}}{\cos \theta_{1} + \sqrt{3.75} - \sin^{2} \theta_{1}}$$
 (G7)

Equations (G3), (G6), and (G7) then define the surface model considered in this analysis. Plots of equations (G6) and (G7) are shown in figure G2.

Fading Margin

The margin in system performance required to overcome effects of the fading environment depends on the selected system modulation, the fading rate, and the time delay between the direct and reflected signals received at the spacecraft.

The BVS attains radial descent shortly after separation from the entry vehicle. Therefore, the correlation time (i.e., time interval between complete correlation of the direct and reflected signals, $\Delta \phi = 0^{\circ}$, and complete uncorrelation, $\Delta \phi = 180^{\circ}$), defined in (ref G5) for a falling lander is applicable.

$$\tau = \frac{1}{\sqrt{8K} \ \nu \ \sigma_{\rm d} / T \ \sin \theta_2}$$

where

 ν = radial velocity of descent vehicle

$$K = 2\pi/\lambda$$

 σ_d/T = surface slope (standard deviation/correlation distance) $\theta_2 = \theta_1$

It has been estimated that the rms slope of the Venus surface is 4 to $7\,^{\circ}$ or

$$0.0345 \le \sigma_d / T \le 0.059$$

Because the radial velocity of the BVS is less than 500~m/sec during a majority of the descent profile, the minimum correlation time will be

$$2.5 \le \tau \le 7.0$$
 msec



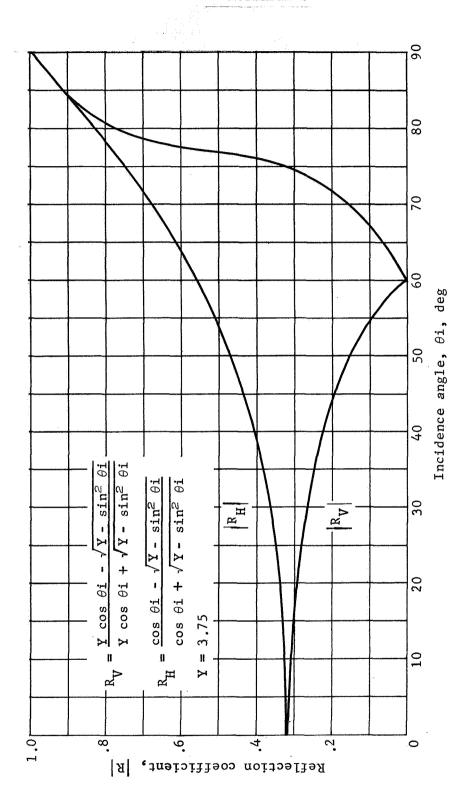


Figure G2.- Reflection Coefficient for Venus Surface

APPENDIX G

The fading rate is considered slow if the received reflected signal is constant over the system information bit period (i.e., correlation time >> than the system information bit period). The data rate of the reference system is 240 bps or equivalent of a bit period equal to \approx 4 msec. This would indicate a fast fading rate occurs during a portion of the deorbit trajectory. However, during the terminal phase of the deorbit trajectory, the radial velocity of the BVS is quite low and the correlation time will increase to possibly several seconds. Therefore, the fading rate would go from fast to slow during the descent trajectory and a slow fading condition would have to be considered to ensure a conservative communication link design.

The modulation selected for the reference system was noncoherent FSK. The required fading margin varies with fading parameter as shown in figure G3. These curves were derived from analytical and experimental data (ref. G5) for a system bit error probability of 4 in 10^3 , noncoherent FSK modulation and slow fading conditions. The effects of time delay become significant for fading parameters less than 10.

The time delay between the direct and reflected signals received at the spacecraft is

$$t_d = R_d / c$$

where R, is the difference in path length of the direct and reflected signals and c is the velocity of light. In general, the time delay may be neglected if it is less than 1/10 of the information bit period. For differential path lengths greater than 125 km, the time delay will become significant for the reference system because the bit period is ≈4 msec. For the preentry phase (entry - 10 min thru entry) of a typical BVS descent trajectory, differential ranges on the order of 300 km occur. However, during this phase the fading parameter is typically 12 or greater. The differential range has decreased to ≈50 km by 30 sec after entry and the fading parameter is approximately 7.5. In general, during periods where the time delay is greater than 1/10 of a bit period, the fading parameter is greater than 12, and the time delay does not become significant. The curve of figure G3, which does not reflect the effect of time delay, was used in the analysis.

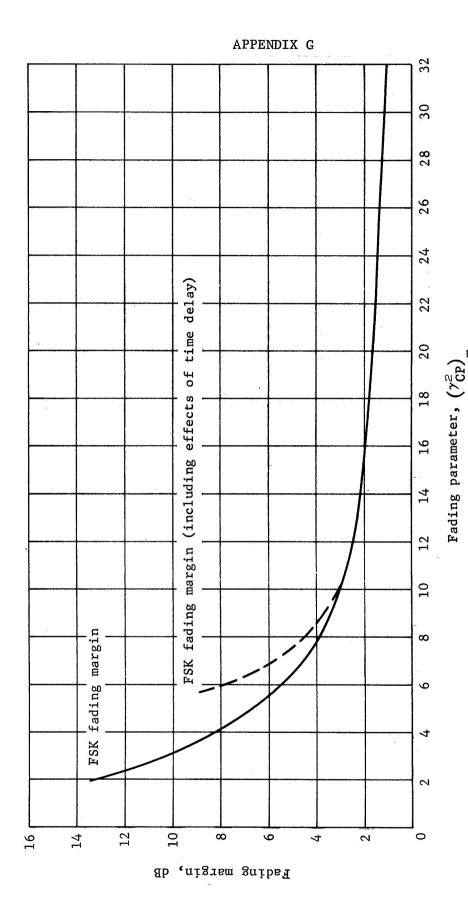


Figure G3. - Fading Margin vs Fading Parameter

APPENDIX G

COMMUNICATIONS GEOMETRY

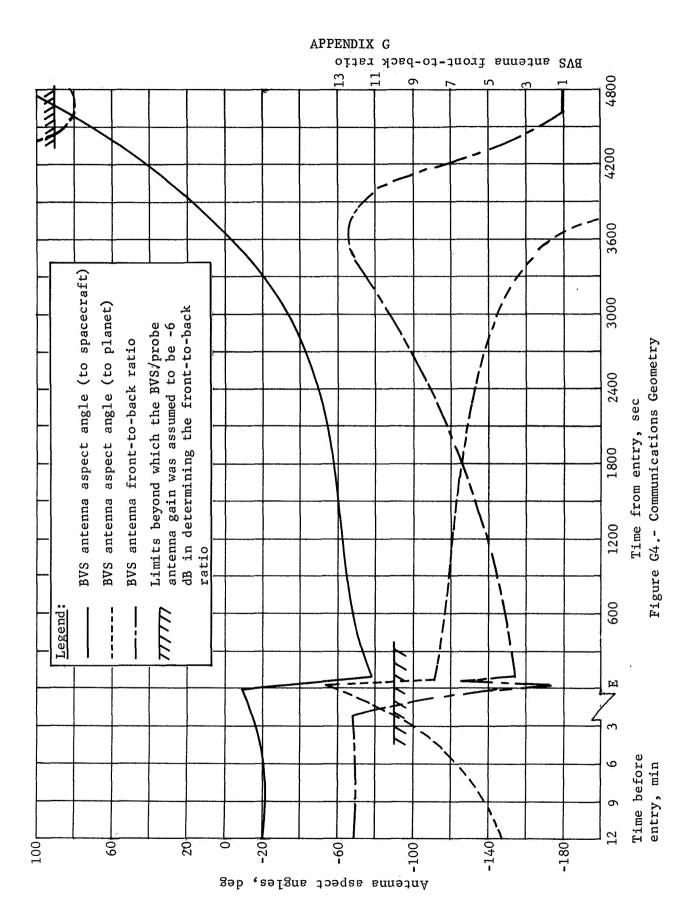
Typical communications geometry between the spacecraft and BVS is shown in figure G4. Variations in the BVS antenna aspect angles to the spacecraft α_{p} and to the planet α_{γ} are shown along with the ratio of the BVS antenna direct to reflected signal power gain. Typical variations in incidence angle are shown in figure G5.

SUMMARY

Using this model to simulate the multipath environment, time histories of the required fading margin were calculated. These are shown in figure G5 and on the performance margin profiles (in the telecommunications subsystems section) above the adverse tolerance. The fading margin increases to approximately 4 dB near entry where large incidence angles and small BVS antenna front-to-back gain ratios exist. The fading environment then becomes less severe, due generally to the radial attitude of the BVS, until the spacecraft approaches the terminal link horizon where conditions similar to the entry phase recur.

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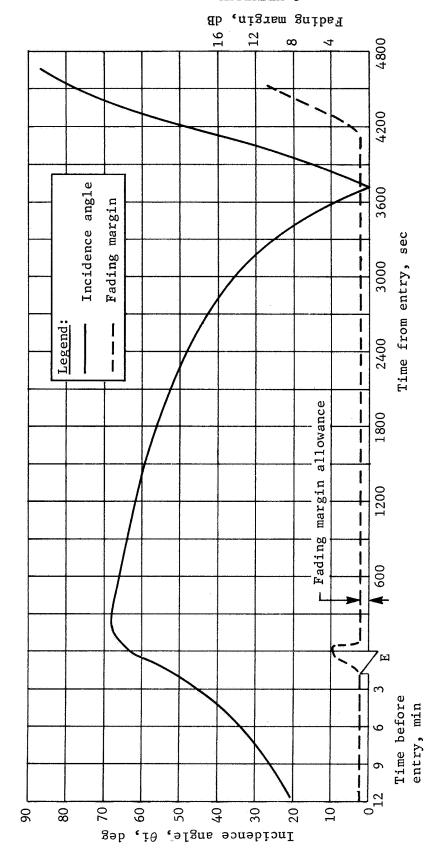


Figure G5.- Incidence Angle Variation and Fading Margin

DOPPLER AND RANGING OPTIONS FOR BVS POSITION DETERMINATION

by Walter F. Hane and Jack D. Pettus Martin Marietta Corporation

The baseline communications links between the Buoyant Venus Station (BVS) and the orbiting spacecraft use noncoherent frequency shift keyed (FSK) 400-MHz signals. The link from the spacecraft to the BVS transmits command codes. The link from the BVS transmits telemetry data back to the spacecraft for 10 minutes after the incoming signal from the spacecraft has exceeded a preset level. The spacecraft transmitted frequency is 410 MHz and that from the BVS is 390 MHz. Optional approaches to the baseline were considered, however, for implementing doppler and ranging for the orbital mission without appreciably deteriorating performance of the baseline links. Four approaches were considered, as follows:

- 1) One-way doppler from spacecraft to BVS with doppler data transmitted back to the spacecraft;
- 2) One-way doppler from spacecraft to BVS;
- 3) Two-way doppler from spacecraft to BVS and back to the spacecraft;
- 4) Two-way ranging along with the two-way doppler.

The reference data used as guidelines for the investigation are:

- 1) Two-way range 50 000 km max., 4000 km min.;
- Two-way propagation time 0.167 sec max., 0.013 sec min.;
- 3) Desired range resolution ±500 m;
- 4) Time for 500-m resolution 1.67 µsec;
- 5) Minimum frequency required for 1.67 μ sec, based on $\frac{1}{4}$ -cycle resolution 150 kHz;
- 6) Range rate resolution 1 m/sec or less;
- 7) Maximum one-way doppler at 400 MHz ±9 kHz;
- 8) Maximum one-way rate of change of doppler 90 Hz/sec;
- 9) Minimum one-way rate of change of doppler 5 Hz/sec.

Of primary importance was the criterion that, whatever techniques were selected, they must have minimal detrimental effects on the performance and reliability of the FSK links. It was desired, in the interest of minimum weight, size, and electric power consumption, to include the doppler and ranging function on the FSK command and data rf links. This was accomplished.

Basically, all four approaches use the same carrier generation and recovery techniques. The gated oscillators of the baseline

transmitters are replaced by two single-sideband FSK generators that alternately switch from upper sideband to lower sideband single tone modulation for generating the mark and space FSK frequencies. Both of the frequencies transmitted by each transmitter are derived from a common oscillator in the transmitter so that coherent demodulation may be used to recover a FSK modulation exclusive reference signal for doppler measurement and ranging. For doppler measurement, no modulation is required, only frequency measurement of a regenerated reference carrier. For ranging, the FSK signals are phase modulated ±22.5° with the ranging code. This reduces the FSK signal strength only 0.7 dB, which, with baseline power, still provides the major portion of the performance margin. The power used for the ranging code is 7.8 dB below that of the FSK signal. The FSK signal level is not reduced when only doppler operation is used without ranging. Operation of the FSK command and data system is unaffected by failure of the doppler and ranging systems to achieve coherent lockup and operation.

Table H1 shows estimates of measurement accuracy for the three doppler and one ranging technique presented. Because the high percentage of error in the one-way doppler measurements use of rate measurements are suggested for a one-way doppler approach. Two-way doppler and ranging, using the technique described, provides a total peak measurement error of less than one doppler cycle from the average over the measurement level and range measurement errors (neglecting relative motion during the ranging interval) of ± 490 m.

SYMBOLS

BPF bandpass filter

DISCRIM discriminator

FSK frequency shift keyed

RCVR receiver

VXO voltage controlled crystal oscillator

XMTR transmitter

XTAL crystal

φ phase angle, degrees

DOPPIER AND RANGING MEASUREMENT SYSTEMS

PERFORMANCE DATA DOPPLER AND RANGING MEASUREMENT SYSTEMS	Two-way doppler S/C-BVS-S/C Total range S/C-BVS-S/C	Change due to OSC stability = 1 x 10^{-5} of BVS time delay ± 0.25 µsec doppler frequency =		Counter error = up to Total round trip peak ±0.5 Hz error = 3.25 µsec	tal doppler = ±18 000	Total peak error = <pre></pre> <pre>Cotal peak error = Conting period Error due to motion of cover counting period Solution of cover c</pre>		
ERFORMANCE DATA DOPPI	One-way doppler Tv BVS to S/C S,	Ct bi	¥ ————————————————————————————————————		To	ŭ∨6 	Same as one-way S/C to BVS ex- cept no addi- tional error	due to BVS-S/C
TABLE H1 P	One-way doppler S/C to BVS	S/C XMTR OSC ± 4100 Hz	BVS RCVR OSC + 410 Hz	Total ±4510 Hz	Total doppler ±9000 Hz	Discriminator error 0.5% of measured fre- quency = 45 Hz	Total peak error = 4555 Hz plus error due to BVS to S/C data system and 40 Hz for digi-	tizing error

CHANGES TO BASELINE SYSTEM

No significant changes to carrier frequencies and none to transmitted power or bit rate are proposed. Therefore, the FSK demodulator design remains basically unchanged. However, the means of generating the FSK output frequencies is changed. The two independent crystal oscillators, in each baseline transmitter, used to generate the FSK signals are replaced by one master oscillator from which the desired output frequencies are generated. This assures an absolute frequency ratio between the output frequencies that aids in the operation of the doppler demodulator. These frequencies are $21~\mathrm{F} \pm 0.01~\mathrm{F}$ for the spacecraft and $20~\mathrm{F} \pm 0.01~\mathrm{F}$ for the BVS, where F is 19.5 MHz.

The mark and space frequency difference of $\pm 195~\rm kc$ ($\pm 0.01~\rm F$) used in the baseline system is retained. Actually, wide frequency spacing allows simpler less selective input filters. Use of fixed ratio carriers allows use of the total FSK signal power for phase lock loop locking, in a modulation exclusive mode, for operating the doppler and ranging systems.

If it were not required to keep the FSK system operation nondependent on lockup of the 0.01 F carrier oscillator, the FSK predetection filter bandwidths could be reduced to improve performance.

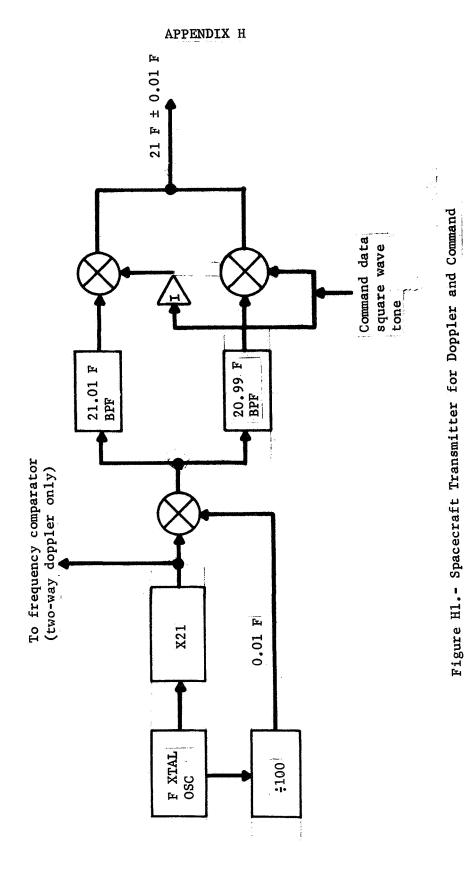
Increase in size, weight, and power for the addition of two-way doppler and ranging (table H2) is slight because common use of the VXO for both receiver and transmitter effects some saving that can be used for the range code detection and regeneration equipment.

ONE-WAY DOPPLER FROM SPACECRAFT TO BVS

A block diagram of the spacecraft transmitter is shown in figure H1. The heart of the transmitter is a single crystal oscillator operating at frequency F (19.5 MHz). This oscillator has a stability of 1 x 10^{-5} . The output frequency of this oscillator is multiplied by 21 to generate the basic output frequency carrier. The oscillator output is also divided by 100 in a two-stage regenerative divider. The 0.01 F (195 kHz) output from this divider is used to tone modulate the 21 F output carrier in a balanced modulator, thereby generating a double sideband suppressed carrier signal with sidebands at 21.01 and 19.99 F.

TABLE H2. - EQUIPMENT WEIGHT, POWER, AND VOLUME SUMMARY

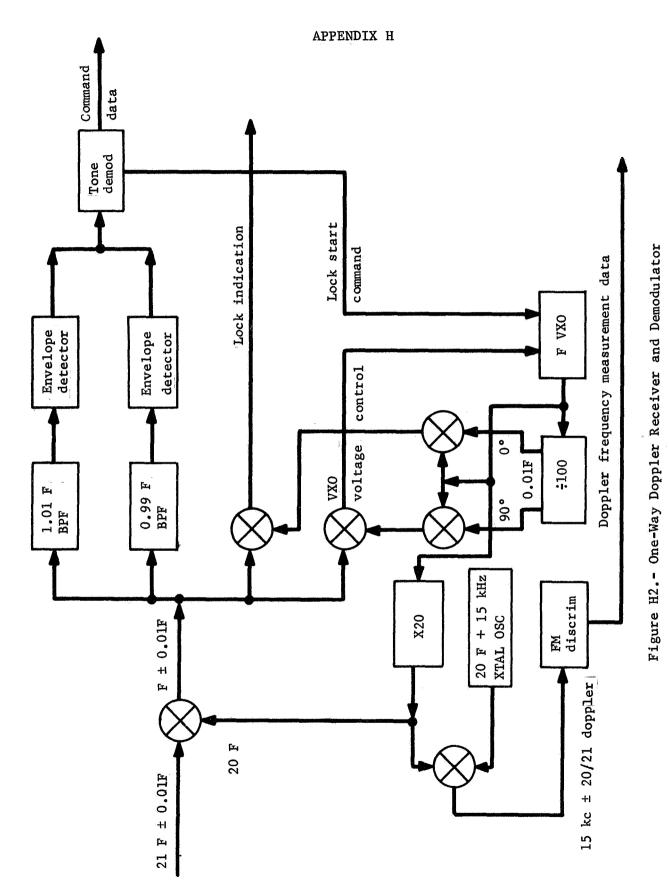
Item	Baseline	One-way	One-way	Two-way	Ranging
	(one-way	doppler	doppler	doppler	and two-way
	doppler)	S/C-BVS	BVS-S/C	S/C-BVS-S/C	doppler
S/C XMTR (1) Weight, lb Power, W Size, in.3	4	4.4	4.4	4.5	4.7
	67	72	72	73	74
	96	105	105	107	110
S/C RCVR (1) Weight, 1b Power, W Size, in. ³	3	4	5	5	5
	2.5	2.5	3.0	3.5	. 3.5
	95	90	100	125	125
<pre>S/C range code demod (1) Weight, 1b Power, W Size, in.³</pre>	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		f 1 1 1 1 1 1 1	I I I I I I I I I	2 1.5 30
BVS XMIR (1) Weight, 1b Power, W Size, in. ³	7 67 96	4.4 72 105	4.4 72 105	2.5 72 62	2.5
BVS RCVR (1) Weight, 1b Power, W Size, in, 3	3	4	3	4	4
	2.5	2.5	2.5	2.5	2.5
	95	100	95	100	100
BVS range code demod (1) Weight, 1b Power, W Size, in. ³			; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ;	1 1 1 1 1 1 1 1 1 1 1 1	2 1.5 30
Total Weight, 1b Power, W Size, in. ³	14 139 382	12.8 149.0 400	16.8 149.5 405.0	16.0 151.0 394.0	20.2 155 457.0



These two sidebands are separated by a pair of bandpass filters. The outputs of these bandpass filters are alternately gated to the output power amplifier by the command data; thereby generating an FSK signal. This later operation is the same as that performed in the baseline system. The concern over carrier and sideband suppression usually associated with suppressed carrier modulation systems is minimized in this application because the class \mathbf{C} output power amplifier in the transmitter functions similar to a limiter, in that it suppresses the lower level signals in the presence of the single desired high level signal.

Figure H2 is a block diagram of the BVS, FSK, and doppler receiver demodulator. Functional circuitry required for the recovery of the FSK command tones is the same as used in the baseline system except for the fact that the local oscillator is derived by multiplying the voltage controlled crystal oscillator (VXO) frequency by 20. This VXO, when not locked on the signal from the spacecraft, is frequency stabilized by a local crystal with a stability of 1×10^{-6} . The VXO is freed from local crystal frequency control when either the lock start command from FSK tone demodulator is activated by the presence of a command tone of adequate level or by an incoming spacecraft signal at a frequency close to that of the VXO. When released by the lock start command, the VXO will be pulled toward and phase locked to frequency derived from the spacecraft. (A frequency search capability, not shown, is required due to the frequency uncertainties of the transmitter and receiver and doppler.)

After lock, the local oscillator signal 20 F will contain 20/21 of the incoming doppler shift, and this doppler will be subtracted from the incoming doppler so that the doppler contained in the FSK signal, at the input of the FSK filters, will be reduced by a factor of 21. When the doppler system is locked up, the FSK signals will be centered in the FSK mark and space bandpass filters. A lock indication binary level is provided out of the doppler demodulator to the BVS data system to inhibit the storing of doppler data until the doppler receiver demodulator is locked. The 20 F local oscillator signal is mixed with a local crystal oscillator operating at a frequency approximately 20 F + 15 kHz. The output of this mixer is a 15 kHz signal, which may be shifted 13.5 kHz due to doppler, the spacecraft oscillator drift, and the receiver crystal oscillator drift. This signal is used by the frequency modulation discriminator to generate an output analog voltage with a level directly proportional to the input frequency. As shown in table H1, this technique yields a data signal of extremely low accuracy because the combined frequency drift of the oscillators in the spacecraft and BVS appear to the



FM discriminator the same as a doppler signal and can reduce the accuracy of the doppler measurement by 50%. Therefore, this technique is best suited for doppler rate or delta doppler measurements because delta values are based on short-term stability.

ONE-WAY DOPPLER FROM BVS TO SPACECRAFT

The techniques used in this approach are identical to those described in the previous section for the one-way doppler from the spacecraft to BVS. The advantage is that, with this approach, it is not necessary to transmit the resultant doppler data measurement back to the spacecraft from the BVS. Therefore, it does not suffer that additional deterioration in data accuracy. However, this deterioration is extremely small compared to inherent errors associated with oscillator instabilities. A disadvantage for this approach occurs when the BVS transmitter "on" time is limited to a fraction of the total view time for a pass because measurements can be made for only a small portion of the doppler S curve.

TWO-WAY DOPPLER SPACECRAFT TO BVS TO SPACECRAFT

Fundamentally this technique involves the use of two one-way doppler systems operating back to back. The exceptions being that the carrier frequency of the BVS transmitter is derived from the spacecraft transmitter signal by phase locking to it in the BVS receiver and using the local mixer oscillator signal of the BVS receiver as the BVS transmitting carrier. Also, the doppler measurement is made much more accurately. The transmitter block diagram shown in figure H1 is applicable as the two-way doppler spacecraft transmitter with the addition of using the 21 F carrier as shown in the figure. The output of this multiplier is used as the frequency comparator for determining the doppler shift of the incoming BVS signal.

Figure H3 is a block diagram of the BVS receiver and demodulator for two-way doppler operation. It is similar to the oneway doppler system except that it does not use a mixer and FM discriminator for frequency determination at the BVS. The local VXO is phase locked to the incoming signal and, in the process, generates the 20 F signal that is used as the incoming local mixer oscillator. In addition, this 20 F is used as the carrier frequency for the BVS transmitter as shown in figure H4.

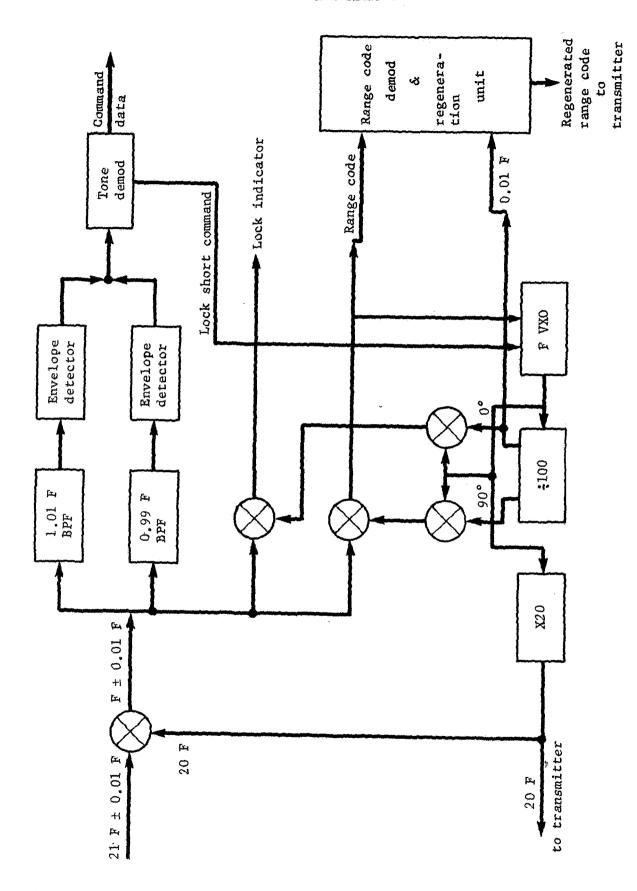


Figure H3.- BVS Receiver and Demodulator for Doppler, Ranging, and Command

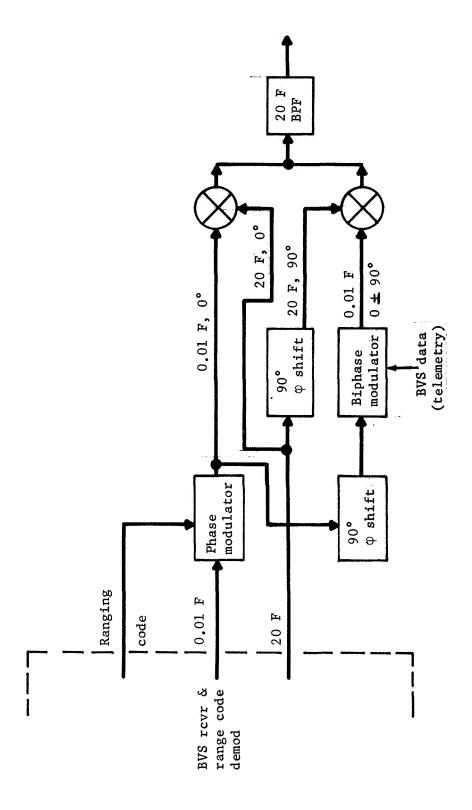
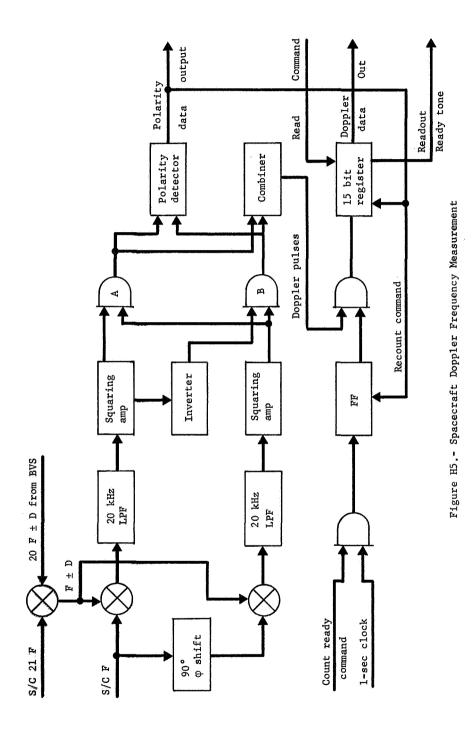


Figure H4.- BVS Transmitter for Ranging, Doppler, and Data

This 20 F signal is modulated by the BVS data in the same manner that the spacecraft transmitter operates. The operation of the doppler frequency measurement performed in the spacecraft is shown in figure H5. The received 20 F signal containing doppler from the BVS is multiplied with the local spacecraft 21 F signal and the output of this mixer is used to provide one of the inputs to the quadrature demodulator. The other set of inputs to this demodulator is spacecraft F signal fed to one balanced demodulator 90° out of phase with the input to the other one. The outputs of these two mixers are pulses at twice the doppler rate. The pulses from the two mixers will be either ±90° with respect to each other depending on whether the doppler frequency is plus or minus. Thus, doppler polarity is determined by the use of the A and B gates shown in the figure, and the polarity detector. The output of the polarity detector will either be a 1 or a 0 level depending on whether the doppler frequency is plus or minus with respect to the original carrier frequency. The doppler pulses are also fed to an AND gate in the doppler frequency measurement section. Another input to this gate is from a flip-flop that is activated by 1-sec clock pulses after a count ready command is received. After starting count, doppler pulses are fed to the 15-bit register, during the count period, which will be exactly 1-sec increments as determined by the local 1-sec clock. When the count period is complete, a readout ready line is activated, which notifies the spacecraft data system that it can proceed to read out the data stored in the register. Therefore, each measurement is contained in a 16-bit word -- 1 bit for polarity, 15 bits for frequency. The accuracy of this measurement is $\pm \frac{1}{2}$ doppler cycle. In the event that the doppler frequency passes through zero during the period of the count and the polarity data output line changes state, the register is reset and a recount started on receipt of the next 1-sec clock pulse.

TWO-WAY DOPPLER AND RANGING

When ranging capability is provided, it is used in addition to the two-way doppler technique described in the previous section. A PN ranging code is used to phase modulate the FSK signal generated by the spacecraft. The period of the ranging code must be greater in time than the total propagation time from the spacecraft to BVS to spacecraft plus any time delays that occur in the system. In this case, for illustrative purposes, the ranging code period has been selected to be 1.09 sec. The range resolution requirement of ±500 m dictates the minimum period of 1 bit of the ranging code required to achieve this resolution.



157

This resolution is provided by using the 0.01 F component for the phase locked loops in the BVS and spacecraft receivers to lock upon.

Figure H6 is a block diagram of the spacecraft transmitter used for the ranging and doppler system. FSK output from this transmitter is the same as that provided in one- and two-way doppler systems. However, due to higher frequency sidebands generated around each of the FSK frequencies by the ranging code it is necessary to delete the relatively narrow bandpass filters used in the previous techniques and replace them by a phasing type of single sideband FSK generation scheme. The F frequency output from the crystal oscillator is divided by 100. This 0.01 F signal is phase modulated ±22.5° by the ranging code. The phase modulated ranging code is fed directly to one of the balanced modulators and is considered a 0° reference 0.01 F signal. output of the phase modulator is also fed to a 90° phase shifter and then biphase modulated by the command data serial bit stream. This then generates a 0.01 F signal that is being changed from +90 to -90° by the data modulation. This signal is used in the other balanced modulator. The output of the crystal oscillator is multiplied by 21, and this signal then used as the other inputs to the two balanced modulators, one of which is shifted 90° as shown in the figure. The outputs of the two balanced modulators are linearly combined and passed through the 21 F bandpass filter. The effect of the phase change by the command data is to cause the summing of the outputs of the two balanced modulators to generate an FSK signal with the range code phase modulation impressed on it.

The BVS receiver and demodulator used for ranging and doppler is the same as shown in figure H3. Note, however, that unlike the "doppler only" case, at the output of the phase modulated demodulator, P, the ranging code is present.

The range code demodulator and regeneration unit automatically and sequentially acquires the clock component and each of the three acquirable subsequences of the code assuming a sequence of combined acquirable PN codes having a clock component (ref. H1). This results in the regeneration of the ranging code which is used to modulate the return link to the spacecraft in the same manner that the ranging modulation was applied to the spacecraft transmitter.

The spacecraft range code demodulator and regeneration unit associated with the receiver signal at the spacecraft is identical to the BVS unit except that a counter is added to record time delay in microseconds between identical states of the transmit code generator and the receiver code regenerator.

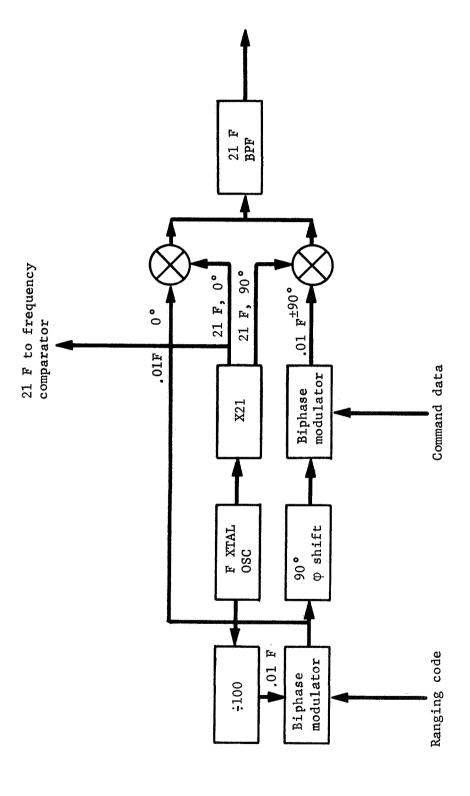


Figure H6.- Spacecraft Transmitters for Ranging, Doppler, and Command

Acquisition times associated with the doppler and ranging system along with the code characteristics are shown in table H3. Note that a nominal acquisition period for ranging is approximately 49 sec, including frequency search, carrier lock, clock acquisition, and three-component range code acquisition at both ends of the link.

Because the time is based on the S/N ratio available at threshold for the FSK data link it can be assumed that acquisition of the code and measurement of range can easily be accomplished during the first minute or so of the communications pass.

REFERENCES

H1. Golomb, S. W. et al.: Digital Communications with Space Applications. Prentice-Hall, Inc., 1964, pp. 91-105.

TABLE H3. - ACQUISITION TIME RANGING CODE

Required error probability = 10^{-3} System N/B = -169.5 dBm

Signal strength = -132.5 dBm

If ST/(N/B) = X, then

$$T = (X) \frac{(N/B)}{S} = \frac{(1.12)10^{-19}}{(5.62)10^{-16}} (X) = 1.99(10^{-4}) (X)$$

Code characteristics:

Each element acquisition time = $P (log_2 P) T (4)$

Maximum range = 328 000 km Code length = $164\ 000\ km$ Code components = 11,47,103Cross correlation - 1/2 Clock frequency = 48.8 kHz

Number of code elements	Log ₂ P	St/NB = X	T	Total time/ component, sec
$P_1 = 11$	3.46	4.0	7.97×10^{-4}	0.121
$P_2 = 47$	5.55	2.8	5.59 x 10 ⁻⁴	0.583
$P_3 = 103$	6.69	2.6	5.20 x 10 ⁻⁴	1.43
				a

Total acquisition = 2.134

Note: Two-way acquisition ----- 2 (2.134) sec Two-way carrier and clock - 2 (22.0) sec

> Total two-way acquisition time (including carrier and clock acquisition)

49 sec

^a Does not include two-way carrier and clock acquisition time that is estimated to require an additional 22 sec each way, assuming a search rate of 2.5 kHz for the carrier and 1 sec clock acquisition.